

$x = \rho a v u \cos \varphi$  ,  $y = \rho a v u \sin \varphi$  ,  $z = a(u^r - v^r)$       سوال اول

$$\frac{\partial r}{\partial q_i} = h_i \hat{q}_i \quad \frac{\partial r}{\partial q_i} \cdot \frac{\partial r}{\partial q_i} = h_i^r \hat{q}_i^r = h_i^r$$

$$r = (\rho a v u \cos \varphi) \hat{i} + (\rho a v u \sin \varphi) \hat{j} + a(u^r - v^r) \hat{k}$$

$$\frac{\partial r}{\partial v} = (\rho a u \cos \varphi) \hat{i} + (\rho a u \sin \varphi) \hat{j} + (-\rho a v) \hat{k}$$

$$\begin{aligned} \frac{\partial r}{\partial v} \cdot \frac{\partial r}{\partial v} &= h_v^r = \rho^2 a^2 u^2 \cos^2 \varphi + \rho^2 a^2 u^2 \sin^2 \varphi + \rho^2 a^2 v^2 = \rho^2 a^2 u^2 (\cos^2 \varphi + \sin^2 \varphi) + \rho^2 a^2 v^2 \\ &= \rho^2 a^2 (u^r + v^r) \quad \Rightarrow \underline{h_v = \rho a \sqrt{u^r + v^r}} \end{aligned}$$

$$\frac{\partial r}{\partial u} = (\rho a v \cos \varphi) \hat{i} + (\rho a v \sin \varphi) \hat{j} + (\rho a u) \hat{k}$$

$$\begin{aligned} \frac{\partial r}{\partial u} \cdot \frac{\partial r}{\partial u} &= h_u^r = \rho^2 a^2 v^2 \cos^2 \varphi + \rho^2 a^2 v^2 \sin^2 \varphi + \rho^2 a^2 u^2 = \rho^2 a^2 (v^r + u^r) \\ &\Rightarrow \underline{h_u = \rho a \sqrt{v^r + u^r}} \end{aligned}$$

$$\frac{\partial r}{\partial \varphi} = (-\rho a v u \sin \varphi) \hat{i} + (\rho a v u \cos \varphi) \hat{j}$$

$$\begin{aligned} \frac{\partial r}{\partial \varphi} \cdot \frac{\partial r}{\partial \varphi} &= h_\varphi^r = \rho^2 a^2 v^2 u^2 \sin^2 \varphi + \rho^2 a^2 v^2 u^2 \cos^2 \varphi = \rho^2 a^2 v^2 u^2 \\ &\Rightarrow \underline{h_\varphi = \rho a v u} \end{aligned}$$

$$ا) \nabla f = \sum_i \hat{q}_i \frac{1}{h_i} \frac{\partial f}{\partial q_i}$$

$$\nabla f = \frac{1}{\rho a \sqrt{u^2 + v^2}} \frac{\partial f}{\partial v} \hat{v} + \frac{1}{\rho a \sqrt{u^2 + v^2}} \frac{\partial f}{\partial u} \hat{u} + \frac{1}{\rho a r u} \frac{\partial f}{\partial \varphi} \hat{\varphi}$$

$$ب) \nabla \cdot A = \left[ \frac{\partial}{\partial v} (A_v h_u h_\varphi) + \frac{\partial}{\partial u} (A_u h_v h_\varphi) + \frac{\partial}{\partial \varphi} (A_\varphi h_v h_u) \right] \frac{1}{h_v h_u h_\varphi}$$

$$= \frac{1}{\rho a^2 r u (u^2 + v^2)} \left[ \rho a^2 u \frac{\partial}{\partial v} (A_v v \sqrt{v^2 + u^2}) + \rho a^2 v^2 \frac{\partial}{\partial u} (A_u u \sqrt{v^2 + u^2}) + \rho a^2 (v^2 + u^2) \frac{\partial A_\varphi}{\partial \varphi} \right]$$

$$ج) \nabla \times A = \frac{1}{h_v h_u h_\varphi} \begin{vmatrix} \hat{v} (\rho a (v^2 + u^2)) & \hat{u} (\rho a (v^2 + u^2)) & \hat{\varphi} \rho a r u \\ \frac{\partial}{\partial v} & \frac{\partial}{\partial u} & \frac{\partial}{\partial \varphi} \\ \rho a (v^2 + u^2) A_v & \rho a (v^2 + u^2) A_u & \rho a r u A_\varphi \end{vmatrix}$$

$$د) \nabla \cdot \nabla f = \frac{1}{h_v h_u h_\varphi} \left[ \frac{\partial}{\partial v} \left( \frac{h_u h_\varphi}{h_v} \frac{\partial f}{\partial v} \right) + \frac{\partial}{\partial u} \left( \frac{h_v h_\varphi}{h_u} \frac{\partial f}{\partial u} \right) + \frac{\partial}{\partial \varphi} \left( \frac{h_v h_u}{h_\varphi} \frac{\partial f}{\partial \varphi} \right) \right]$$

$$\int V \cdot da = \int (\nabla \cdot V) dT$$

سوال (۳)

$$\nabla \cdot V = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho (\rho (r + \sin^2 \theta))) + \frac{1}{\rho} \frac{\partial}{\partial \theta} (\rho \sin \theta \cos \theta) + \frac{\partial}{\partial z} (r z^r)$$

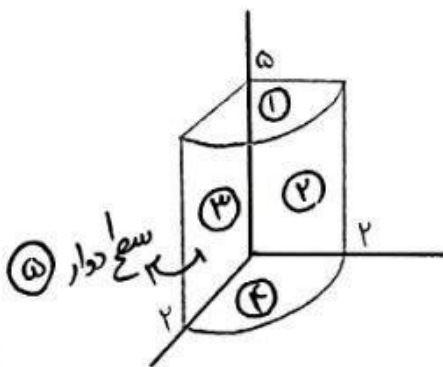
$$= \frac{1}{\rho} (r \rho (r + \sin^2 \theta)) + \frac{1}{\rho} (\rho (\cos^2 \theta - \sin^2 \theta)) + r z$$

$$= \omega + r z$$

$$\int (\nabla \cdot V) dT = \int (\omega + r z) \rho d\rho d\theta dz = \omega \int_0^r \rho d\rho \int_0^{\frac{\pi}{r}} d\theta \int_0^{\omega} dz +$$

$$r \int_0^r \rho d\rho \int_0^{\frac{\pi}{r}} d\theta \int_0^{\omega} z dz = \omega (r) \left(\frac{\pi}{r}\right) (\omega) + r (r) \left(\frac{\pi}{r}\right) \left(\frac{r \omega}{r}\right)$$

$$= 2\omega\pi + 7\omega\pi = \underline{100\pi}$$



① سطح بالا:  $z = \omega$ ,  $da = \rho d\rho d\theta \hat{z}$

$$V \cdot da = r z^r \rho d\rho d\theta = r \omega \rho d\rho d\theta$$

$$\int V \cdot da = r \omega \int_0^r \rho d\rho \int_0^{\frac{\pi}{r}} d\theta = r \omega (r) \left(\frac{\pi}{r}\right) = \underline{7\omega\pi}$$

② سطح راست:  $\theta = \frac{\pi}{r}$ ,  $da = d\rho dz \hat{\theta}$

$$V \cdot da = \rho \sin \theta \cos \theta d\rho dz = 0$$

$$\int V \cdot da = 0$$

③ سطح چپ:  $\theta = 0$ ,  $\int V \cdot da = 0$

④ سطح پایین:  $z = 0$ ,  $\int V \cdot da = 0$

⑤ سطح دوار:  $\rho = r$ ,  $da = \rho d\theta dz$

$$\int V \cdot da = \int \rho(r + \sin^2\theta) \rho d\theta dz = r \int (r + \sin^2\theta) d\theta dz$$

$$= r \int_0^{\frac{\pi}{4}} (r + \sin^2\theta) d\theta \int_0^a dz = r_0 \left[ \int_0^{\frac{\pi}{4}} r d\theta + \int_0^{\frac{\pi}{4}} \sin^2\theta d\theta \right]$$

\*  $\sin^2\theta = \frac{1 - \cos 2\theta}{2}$

$$= r_0 \left[ r \left(\frac{\pi}{4}\right) + \int_0^{\frac{\pi}{4}} \left(\frac{1 - \cos 2\theta}{2}\right) d\theta \right] =$$

$$r_0 \left[ \pi + \frac{1}{2} \theta \Big|_0^{\frac{\pi}{4}} - \frac{1}{2} \sin 2\theta \Big|_0^{\frac{\pi}{4}} \right] = r_0 \left[ \pi + \frac{\pi}{8} \right] = r_0 \left( \frac{9\pi}{8} \right) = 45\pi$$

$$\Rightarrow \int V \cdot da = 45\pi + 0 + 0 + 0 + 45\pi = 90\pi \quad \checkmark$$

$$\vec{A} = \frac{ky}{x^2+y^2} \hat{i} - \frac{kx}{x^2+y^2} \hat{j}$$

سوال سوم

شکل نشانگر مسیر بسته‌ی دایره‌ای به معادله‌ی  $x^2+y^2=a^2$  است.

$$\oint \vec{A} \cdot d\vec{l} = \int \vec{\nabla}_x \vec{A} \cdot d\vec{a}$$

سخت‌ترین:  $\oint \left( \left( \frac{ky}{x^2+y^2} \right) \hat{i} - \left( \frac{kx}{x^2+y^2} \right) \hat{j} \right) \cdot (dx \hat{i} + dy \hat{j})$

$$x^2+y^2=a^2; \quad x = a \cos\theta, dx = -a \sin\theta d\theta; \quad y = a \sin\theta, dy = a \cos\theta d\theta$$

$$\oint A \cdot d\vec{l} = \oint \left( \frac{k(\cos\theta)}{a^r} \hat{i} - \frac{k(\sin\theta)}{a^r} \hat{j} \right) \cdot (-a\sin\theta d\theta \hat{i} + a\cos\theta d\theta \hat{j})$$

$$= k \oint (-\sin^2\theta - \cos^2\theta) d\theta = -k \int_0^{2\pi} d\theta = -2k\pi$$

سخت راست:

$$\vec{\nabla} \times \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{ky}{x^2+y^2} & \frac{-kx}{x^2+y^2} & 0 \end{vmatrix} = \left( 0 - \frac{\partial}{\partial z} \left( \frac{kx}{x^2+y^2} \right) \right) \hat{i} - \left( 0 - \frac{\partial}{\partial z} \left( \frac{ky}{x^2+y^2} \right) \right) \hat{j}$$

$$+ \left( \frac{\partial}{\partial x} \left( \frac{-kx}{x^2+y^2} \right) - \frac{\partial}{\partial y} \left( \frac{ky}{x^2+y^2} \right) \right) \hat{k}$$

$$= \left( \frac{-k(x^2+y^2) - (-kx)(2x)}{(x^2+y^2)^2} - \frac{k(x^2+y^2) - (ky)(2y)}{(x^2+y^2)^2} \right) \hat{k}$$

$$= \frac{kx^2 - ky^2}{(x^2+y^2)^2} - \frac{kx^2 - ky^2}{(x^2+y^2)^2} = 0$$

$$\Rightarrow \int \vec{\nabla} \times \vec{A} \cdot d\vec{a} = 0$$

قضیه برقرار نیست. چرا؟ اگر به شکلی که بردار  $\vec{A}$  تعریف شده است دقت کنیم در جایی که  $0 \neq -2k\pi$

به ازای  $x, y$  هر دو صفر داشته باشیم تعریف نداریم.



از قضیه دیورژانس استفاده می‌کنیم.

الف)

$$\nabla \cdot E = \frac{\rho}{\epsilon_0}$$

$$\int \nabla \cdot E \, d\tau = \frac{1}{\epsilon_0} \int \rho \, d\tau$$

$$\Rightarrow \int E \cdot da = \frac{q}{\epsilon_0}$$

$$\int \nabla \cdot E \, d\tau = \int E \cdot da$$

باقی:  $E \int da = \frac{1}{\epsilon_0} \int \rho(r) \, d\tau$  ;  $d\tau = r^2 \sin\theta \, dr \, d\theta \, d\varphi$

$$4\pi r^2 E = \frac{1}{\epsilon_0} \int_0^r \alpha r (r^2 \sin\theta \, dr \, d\theta \, d\varphi)$$

$$= \frac{1}{\epsilon_0} \int_0^r \alpha r \, r^2 \, dr \, d\Omega = \frac{4\pi\alpha}{\epsilon_0} \int_0^r r^3 \, dr$$

$$* \sin\theta \, d\theta \, d\varphi = d\Omega$$

$$** \int d\Omega = 4\pi$$

$$= \frac{4\pi\alpha}{\epsilon_0} \frac{r^4}{4}$$

$$\Rightarrow 4\pi r^2 E = \frac{4\pi\alpha}{\epsilon_0} \frac{r^4}{4} \Rightarrow E = \frac{\alpha}{4\epsilon_0} r^2$$

خارج:  $E \int da = \frac{1}{\epsilon_0} \int_0^R \rho(r) \, d\tau$

$$4\pi r^2 E = \frac{1}{\epsilon_0} \int_0^R \alpha r \, r^2 \, dr \, d\Omega = \frac{\alpha}{\epsilon_0} (4\pi) \frac{R^4}{4}$$

$$\Rightarrow E = \frac{\alpha R^2}{\epsilon_0 4 r^2}$$

$$b) \nabla \times B = \mu_0 \vec{J}$$

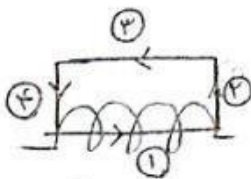
با استفاده از استوکس

$$\int \nabla \times B \cdot d\vec{a} = \oint B \cdot d\vec{l}$$

$$\int \nabla \times B \cdot d\vec{a} = \mu_0 \int \vec{J} \cdot d\vec{a} = \mu_0 I$$

$$\oint B \cdot d\vec{l} = \mu_0 I$$

سیم نوله با  $N$  دور



$$B_1 l + 0 + B_3 l + 0 = B l = \mu N I$$

$$\Rightarrow B = \frac{\mu N I}{l}$$

به مسیر بسته دلخواه انتخاب کنیم و  
انگزال مسیر بسته را در نظر بگیریم:

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5. سوال ایضاً 40

$$\vec{G} = \frac{\sqrt{x^2 + y^2 + z^2}}{\sqrt{x^2 + y^2}} [(x-y)\hat{i} + (x+y)\hat{j}]$$

استقلال از عمل مستطیل در روی این استرالک در پیم یک محاسبه و تعیین است پس بر این بار آن است که  $\vec{G}$ .

$$\begin{cases} x = r \sin\theta \cos\varphi \\ y = r \sin\theta \sin\varphi \\ z = r \cos\theta \end{cases}$$

دستگاه مختصات روی این.

با استفاده از این روابط  $\vec{G}$  را بدست

$$\begin{cases} \hat{i} = \sin\theta \cos\varphi \hat{r} + \cos\theta \cos\varphi \hat{\theta} - \sin\varphi \hat{\phi} \\ \hat{j} = \sin\theta \sin\varphi \hat{r} + \cos\theta \sin\varphi \hat{\theta} + \cos\varphi \hat{\phi} \\ \hat{z} = \cos\theta \hat{r} - \sin\theta \hat{\theta} \end{cases}$$

جواب

$$\vec{G} = \frac{\sqrt{(r \sin\theta \cos\varphi)^2 + (r \sin\theta \sin\varphi)^2 + (r \cos\theta)^2}}{\sqrt{(r \sin\theta \cos\varphi)^2 + (r \sin\theta \sin\varphi)^2}} [(x-y)\hat{i} + (x+y)\hat{j}] = \frac{r}{r \sin\theta} [(x-y)\hat{i} + (x+y)\hat{j}]$$

$$= \frac{1}{\sin\theta} [(r \sin\theta \cos\varphi - r \sin\theta \sin\varphi)\hat{i} + (r \sin\theta \cos\varphi + r \sin\theta \sin\varphi)\hat{j}]$$

$$= r [( \cos\varphi - \sin\varphi )\hat{i} + ( \cos\varphi + \sin\varphi )\hat{j}]$$

$$= r [(\cos\varphi - \sin\varphi)(\sin\theta \cos\varphi \hat{r} + \cos\theta \cos\varphi \hat{\theta} - \sin\varphi \hat{\phi}) + (\cos\varphi + \sin\varphi)(\sin\theta \sin\varphi \hat{r} + \cos\theta \sin\varphi \hat{\theta} + \cos\varphi \hat{\phi})]$$

$$= r [\underbrace{\sin\theta \cos^2\varphi \hat{r}} - \cancel{\sin\theta \cos\varphi \sin\varphi \hat{r}} + \cos\theta \cos^2\varphi \hat{\theta} - \cancel{\cos\theta \sin\varphi \cos\varphi \hat{\theta}} - \cancel{\cos\varphi \sin\varphi \hat{\phi}} + \sin^2\varphi \hat{\phi}]$$

$$+ \cancel{\sin\theta \sin\varphi \cos\varphi \hat{r}} + \underbrace{\sin\theta \sin^2\varphi \hat{r}} + \cos\theta \cancel{\cos\varphi \sin\varphi \hat{\theta}} + \cos\theta \sin^2\varphi \hat{\theta} + \cos^2\varphi \hat{\phi} + \cancel{\sin\varphi \cos\varphi \hat{\phi}]$$



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$$\Rightarrow \vec{G}(r, \theta, \varphi) = r \sin \theta \hat{r} + r \cos \theta \hat{\theta} + r \hat{\varphi}$$

$$\oint \vec{G} \cdot d\vec{l} = ? \quad d\vec{l} = dr \hat{r} + r d\theta \hat{\theta} + r \sin \theta d\varphi \hat{\varphi} \quad (\text{الف})$$

$$\vec{G} \cdot d\vec{l} = r \sin \theta dr + r^2 \cos \theta d\theta + r^2 \sin \theta d\varphi$$

$r = cte = 2 \Rightarrow dr = 0$        $\theta = cte = \frac{\pi}{6} \Rightarrow d\theta = 0$

$$\oint \vec{G} \cdot d\vec{l} = \int r^2 \sin \theta d\varphi = (2)^2 \sin \frac{\pi}{6} \int_0^{2\pi} d\varphi = 4 \times \frac{1}{2} \times 2\pi = \underline{\underline{4\pi}}$$

$$\int_{S_1} \vec{\nabla} \times \vec{G} \cdot d\vec{a} \quad \vec{\nabla} \times \vec{G} = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \hat{r} & r \hat{\theta} & r \sin \theta \hat{\varphi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \varphi} \\ r \sin \theta & r \cos \theta & r \sin \theta(r) \end{vmatrix} \quad (\text{ب})$$

$$\Rightarrow \vec{\nabla} \times \vec{G} = \frac{1}{r^2 \sin \theta} [ r^2 \cos \theta \hat{r} - 2r^2 \sin \theta \hat{\theta} + r^2 \sin \theta \cos \theta \hat{\varphi} ] = \cos \theta \hat{r} - 2\hat{\theta} + \cos \theta \hat{\varphi}$$

$$d\vec{a} = r^2 \sin \theta d\varphi d\theta \hat{r} + r dr d\theta \hat{\varphi} + r \sin \theta dr d\varphi \hat{\theta}$$

$$(\vec{\nabla} \times \vec{G}) \cdot d\vec{a} = r^2 \cos \theta d\varphi d\theta - 2r \sin \theta dr d\varphi + r \cos \theta dr d\theta$$

at  $S_1$ :  $r = cte = 2 \Rightarrow dr = 0$

$$\int_{S_1} (\vec{\nabla} \times \vec{G}) \cdot d\vec{a} = \int r^2 \cos \theta d\varphi d\theta = 4 \int_0^{\pi/6} \cos \theta d\theta \int_0^{2\pi} d\varphi = \underline{\underline{4\pi}}$$

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$$\text{از سمت اول: } (\nabla \times \vec{G}) \cdot d\vec{a} = r^2 \cos \theta d\varphi d\theta - 2r \sin \theta dr d\varphi + r \cos \theta dr d\theta \quad (8)$$

$$\theta = \text{cte} = \pi/6 \rightarrow d\theta = 0$$

$$\int_{S_2} (\nabla \times \vec{G}) \cdot d\vec{a} = \int (-2r \sin \theta dr d\varphi) = -2 \sin \frac{\pi}{6} \int_0^2 r dr \int_0^{2\pi} d\varphi = -\underline{\underline{9\pi}}$$

$$\int_{S_1} \vec{G} \cdot d\vec{a} \quad \vec{G} = r \sin \theta \hat{r} + r \cos \theta \hat{\theta} + r \hat{\varphi}$$

$$d\vec{a} = r^2 \sin \theta d\varphi d\theta \hat{r} + r \sin \theta dr d\varphi \hat{\theta} + r dr d\theta \hat{\varphi}$$

$$\vec{G} \cdot d\vec{a} = r^3 \sin^2 \theta d\varphi d\theta + r^2 \sin \theta \cos \theta dr d\varphi + r^2 dr d\theta$$

$$\text{at } S_1: r = \text{cte} = 2 \rightarrow dr = 0$$

$$\int_{S_1} \vec{G} \cdot d\vec{a} = \int r^3 \sin^2 \theta d\varphi d\theta = 8 \int_0^{\pi/6} \sin^2 \theta \int_0^{2\pi} d\varphi = \underline{\underline{2\pi(-\sqrt{3} + \frac{2\pi}{3})}}$$

$$\vec{G} \cdot d\vec{a} = r^3 \sin^2 \theta d\varphi d\theta + r^2 \sin \theta \cos \theta dr d\varphi + r^2 dr d\theta \quad (9)$$

$$\text{at } S_2: \theta = \text{cte} = \pi/6 \Rightarrow d\theta = 0$$

$$\int_{S_2} \vec{G} \cdot d\vec{a} = \int r^2 \sin \theta \cos \theta dr d\varphi = \sin \frac{\pi}{6} \cos \frac{\pi}{6} \int_0^2 r^2 dr \int_0^{2\pi} d\varphi = \underline{\underline{4\sqrt{3} \frac{\pi}{3}}}$$

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$$\int_V \vec{\nabla} \cdot \vec{G} \, d\tau \quad \vec{\nabla} \cdot \vec{G} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 G_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta G_\theta) + \frac{1}{r \sin \theta} \frac{\partial G_\phi}{\partial \phi} \quad 19$$

$$\Rightarrow \vec{\nabla} \cdot \vec{G} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 (r \sin \theta)) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta r \cos \theta) + \frac{1}{r \sin \theta} \frac{\partial r}{\partial \phi}$$

$$\Rightarrow \vec{\nabla} \cdot \vec{G} = 3 \sin \theta + \frac{\cos 2\theta}{\sin \theta}$$

$$d\tau = r^2 \sin \theta \, dr \, d\theta \, d\phi$$

$$\int_V \vec{\nabla} \cdot \vec{G} \, d\tau = \int (3 \sin \theta + \frac{\cos 2\theta}{\sin \theta}) r^2 \sin \theta \, dr \, d\theta \, d\phi$$

$$= 3 \int_0^2 r^2 \, dr \int_0^{\pi/6} \sin^2 \theta \, d\theta \int_0^{2\pi} d\phi + \int_0^2 r^2 \, dr \int_0^{\pi/6} \frac{\cos 2\theta}{\sin \theta} \sin \theta \, d\theta \int_0^{2\pi} d\phi = 2\pi \left( -\frac{1}{\sqrt{3}} + \frac{2\pi}{3} \right)$$

۱- در واقع این سوال برای بررسی تفهیم استولس و دیورانس است

$$\int \vec{\nabla} \times \vec{v} \cdot d\vec{a} = \oint \vec{v} \cdot d\vec{l} \quad \text{تفصیل استولس باید باشد:}$$

استولس است نسبت به وجه هر کدام سطح متفاوت برای سمت چپ و راست هستند.

تفصیلی استولس برقرار است  $\rightarrow 4\pi =$  نسبت برای  $S_1$  و  $4\pi =$  نسبت الف

تفصیلی استولس برقرار است چون سطح اختیاری  $\rightarrow -4\pi =$  نسبت برای  $S_2$  و  $4\pi =$  نسبت الف

بوده و برای علامه یادداشت کردن هر یک یک فنش ظاهر شده است.

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پس دیدیم برآیند محاسبه میدان برداری جیتی مانند  $\vec{G}$  در روی سطح باقیمانده می توانیم بویوم در آن ارضن قضیه استوارس روی مرز

سطح حساب کنیم در مرز  $\vec{G}$  نماند

$$\int_V \vec{\nabla} \cdot \vec{v} \, d\tau = \oint_{\partial V} \vec{v} \cdot d\vec{a}$$

در قسمت "دو" و "سه" قضیه دیورانس را می بینیم:

$$\oint_S \vec{G} \cdot d\vec{a} = \int_{S_1} \vec{G} \cdot d\vec{a} + \int_{S_2} \vec{G} \cdot d\vec{a}$$

$$= 2\pi \left( -\sqrt{3} + \frac{2\pi}{3} \right) + 4\sqrt{3} \frac{\pi}{3}$$

$$= 2\pi \left( -\frac{1}{\sqrt{3}} + \frac{2\pi}{3} \right)$$

$\leftarrow$  قضیه دیورانس برقرار است.

$$2\pi \left( -\frac{1}{\sqrt{3}} + \frac{2\pi}{3} \right) = \text{قیمت "دو" هم سمت چپ معادله است}$$

پس دیدیم برآیند محاسبه میدان برداری جیتی مانند  $\vec{G}$  در داخل حجم در روی  $\vec{G}$  از محاسبه کنیم می توانیم بویوم در آن سطح را محاسبه

کنیم.