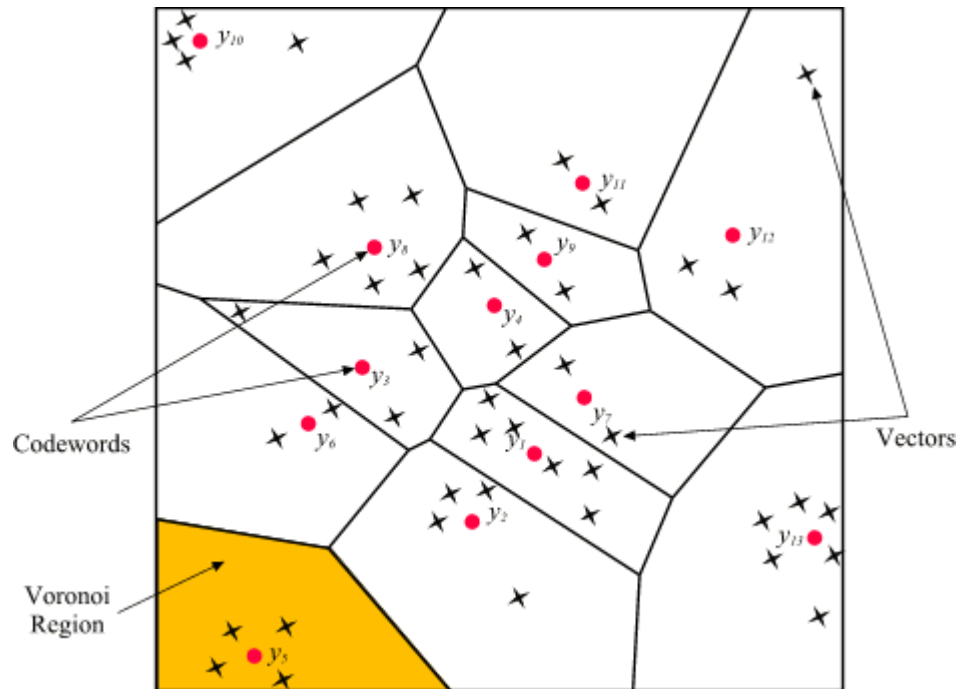


Neural Networks

Learning Vector Quantization



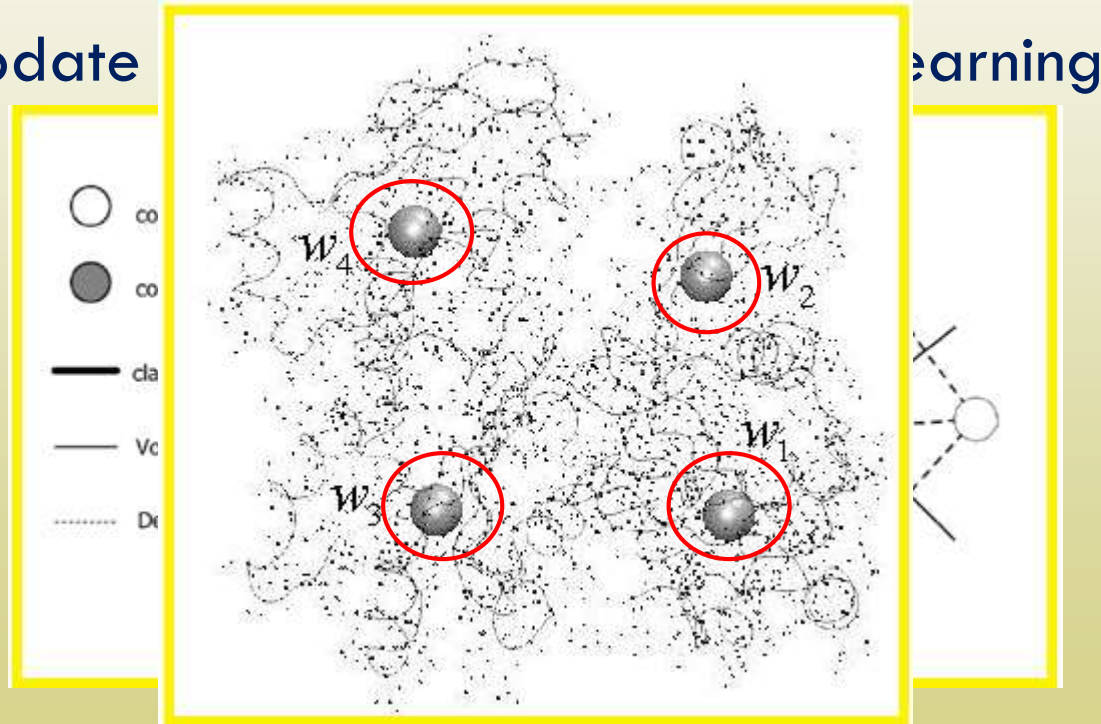
Introduction

2

□ General idea

▣ Assign some prototypes for each class

▣ Update



Learning Vector Quantization (LVQ)

aim:

classification of data

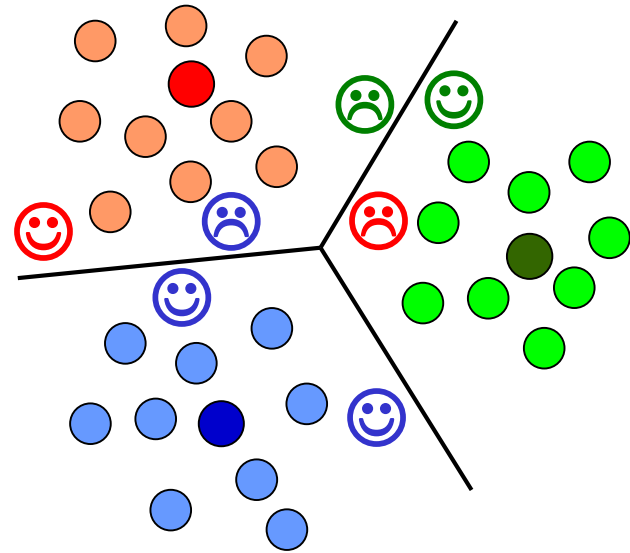
learning from examples

example situation:

3 classes , 3 prototypes

classification:

assignment of a vector ξ
to the class of the closest
prototype w



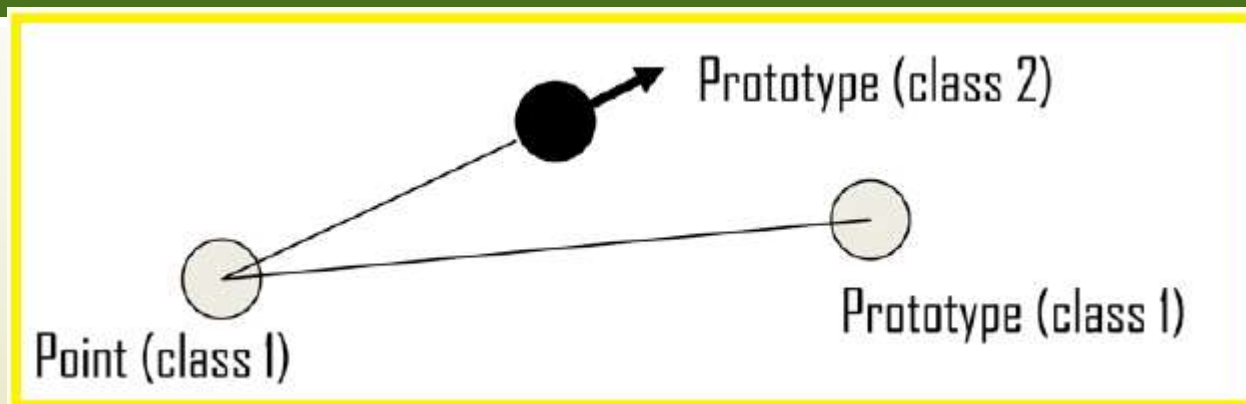
Learning: choice of prototypes according to example data

aim : **generalization ability**, i.e. correct classification
of *novel* data after training

LVQ Algorithms

4

□ LVQ 1



$$c = \operatorname{argmin}(\|x^q - w^m\|)$$
$$w^c(t+1) = w^c(t) + a(t)s(t)[x^q - w^c(t)]$$
$$0 < a(t) < 1$$

$$s(t) = \begin{cases} +1 & \text{if classification is correct} \\ -1 & \text{if classification is wrong} \end{cases}$$

LVQ 2.1

5

- Concurrent update of the two nearest prototypes

- Three conditions must be met for update:
 - Nearest prototype (m_i) is from wrong class
 - The second nearest one (m_j), is from the correct class
 - The input vector is sufficiently close to the decision boundary between m_i and m_j :

$$0.4 < S < 0.8 \quad \min\left(\frac{d_i}{d_j}, \frac{d_j}{d_i}\right) \geq S$$

d_i, d_j : distance between input and prototype



$$m_j(t + 1) = m_j(t) + a(t)[x(t) - m_j(t)]$$

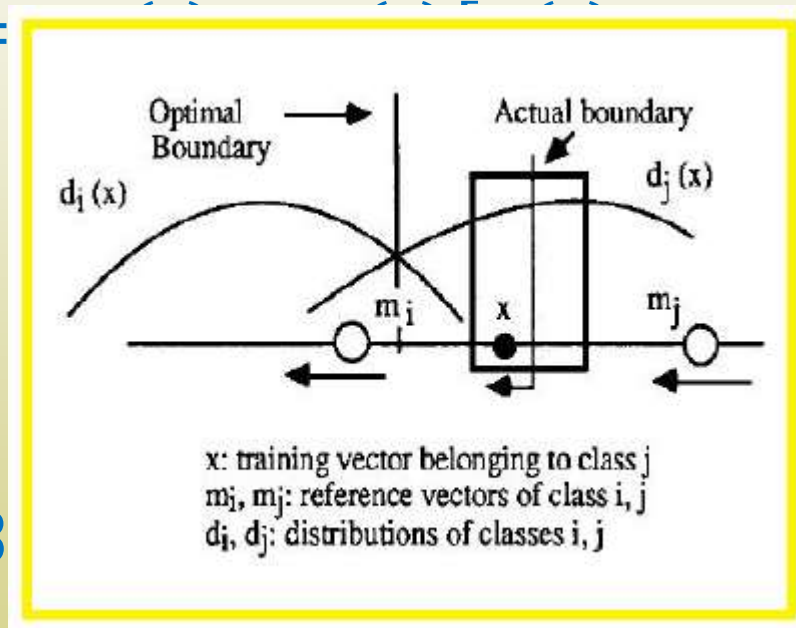
$$m_i(t + 1) = m_i(t) + a(t)[x(t) - m_i(t)]$$



$$i = 1, \dots, N$$



$$a(0) = 0.08$$

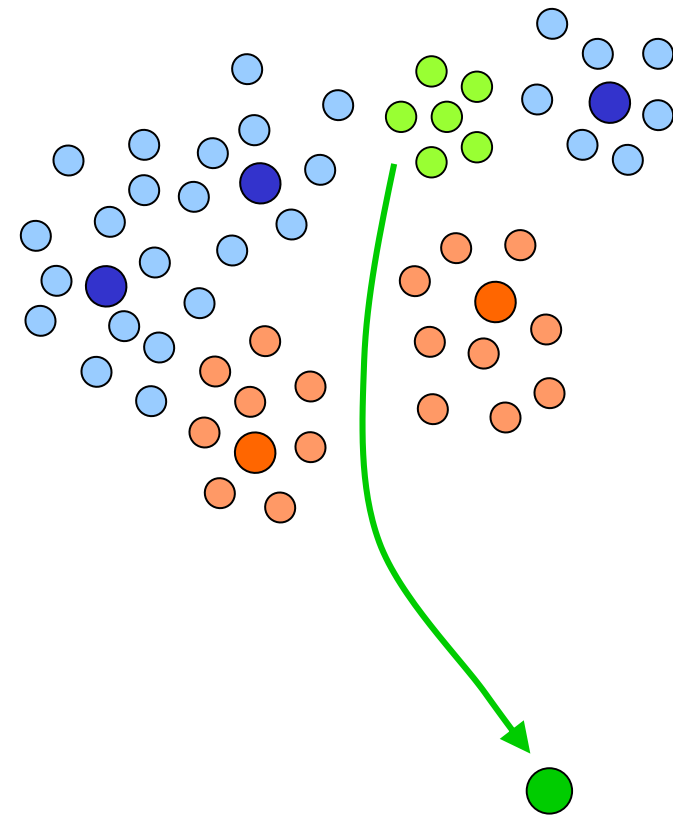

 $\frac{i}{N}$
 i

mostly: **heuristically** motivated variations of **competitive learning**

prominent example [Kohonen]: “LVQ 2.1.”

- initialize prototype vectors (for different classes)
- present a single example
- identify the closest *correct* and the closest *wrong* prototype
- move the corresponding *winner* towards / away from the example

known convergence / stability problems,
e.g. for infrequent classes



LVQ As A Neural Net

8

- One hidden layer can be assumed

