

Theory of Computer Science

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Complexity Theory

another topic ...

Mining Massive Datasets

Computational Learning Theory

Parameterized Algorithms

- Church-Turing thesis, Turing machine & its variations
- exploring the limits of algorithmic solvability
- reducibility as a key method to prove unsolvability
- recursive/partial recursive functions
- decidability in terms of recursion
- arriving at Turing machines
- decidability of logical theories
- Turing reducibilities

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[S12] Sipser, Michael. **Introduction to the Theory of Computation**, 3rd edition. Cengage Learning, 2012. (Chapters 3 to 6)



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[DSW94] Davis, Martin, Ron Sigal, and Elaine J. Weyuker. **Computability, Complexity, and Languages: Fundamentals of Theoretical Computer Science**. Newnes, 1994. (Chapters 2 to 6)



Course note based on *Computability, Complexity, and Languages: Fundamentals of Theoretical Computer Science*, 2nd edition, authored by Martin Davis, Ron Sigal, and Elaine J. Weyuker.

course note prepared by

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Week 1, Spring 2010

Textbook

Martin Davis, Ron Sigal, and Elaine J. Weyuker. *Computability, Complexity, and Languages: Fundamentals of Theoretical Computer Science*, 2nd edition. February 1994, Morgan Kaufmann. ISBN: 0122063821.

- Written for people who may know programming, but from a mathematical view of the subjects. Enjoyably readable but very rigorous.
- "It is our purpose ... to provide an introduction to the various aspects of theoretical computer science for undergraduate and graduate students that is sufficiently comprehensive that ... research papers will become accessible to our readers." (the authors)

• We will cover just one half of the materials in the book.

Outline of Today's Lecture

- Review some preliminary materials.
- Define an abstract programming language S that is extremely simple.

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▶ Write some programs in 𝒴.

Cartesian Product

- ▶ If $S_1, S_2, ..., S_n$ are given sets, then we write $S_1 \times S_2, \times \cdots \times S_n$ for the set of all *n*-tuples $(a_1, a_2, ..., a_n)$ such that $a_1 \in S_1, a_2 \in S_2, ..., a_n \in S_n$.
- $S_1 \times S_2, \times \cdots \times S_n$ is called the *Cartesian product* of S_1, S_2, \ldots, S_n .
- In case S₁ = S₂ = ··· = S_n = S we write Sⁿ for the Cartesian product S₁ × S₂, × ··· × S_n.

Sets, *n*-tuples, and functions (1.1, 1.2) Predicates (1.4) Quantifiers (1.5) Proofs (1.6, 1.7)

Functions

A function f is a set whose members are ordered pairs (i.e., 2-tuples) and has the special property

 $(a,b) \in f$ and $(a,c) \in f$ implies b = c.

We write f(a) = b to mean that $(a, b) \in f$.

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- A partial function on a set S is a function whose domain is a subset of S. If a partial function on S has the domain S, then it is called a *total function*.

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- We write f(a) ↓ and say that f(a) is defined if a is in the domain of f; if a is not in the domain of f, we write f(a) ↑ and say that f(a) is undefined.

Sets, n-tuples, and functions (1.1, 1.2) Predicates (1.4) Quantifiers (1.5) Proofs (1.6, 1.7)

Examples of Functions

Let f be the set of ordered pairs (n, n²) for n ∈ N. Then, for each n ∈ N, f(n) = n². The domain of f is N. The range of f is the set of perfect squares. f is a total function.

Sets, n-tuples, and functions (1.1, 1.2) Predicates (1.4) Quantifiers (1.5) Proofs (1.6, 1.7)

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- ▶ Let f be the set of ordered pairs (n, n^2) for $n \in N$. Then, for each $n \in N$, $f(n) = n^2$. The domain of f is N. The range of f is the set of perfect squares. f is a total function.
- Assuming N is our universe, an example of a partial function on N is given by g(n) = √n. The domain of g is the set of perfect squares. The range of g is N. g is not a total function.

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- For a partial function f on a Cartesian product $S_1 \times S_2, \times \cdots \times S_n$, we write $f(a_1, \ldots, a_n)$ rather than $f((a_1, \ldots, a_n))$.

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- A partial function f on a set Sⁿ is called an *n-ary* partial function on S, or a function of n variables on S. We use *unary* and *binary* for 1-ary and 2-ary, respectively.

Predicate

A predicate, or a Boolean-valued function, on a set S is a total function P on S such that for each $a \in S$, either

P(a) = TRUE or P(a) = FALSE

We also identify the truth value TRUE with number 1 and the truth value FALSE with number 0.

Sets, *n*-tuples, and functions (1.1, 1.2) **Predicates (1.4)** Quantifiers (1.5) Proofs (1.6, 1.7)

Logic Connectives

The three *logic connectives*, or *propositional connectives*, \sim , \lor , & are defined by the two tables below.

р	\sim p	-	р	q	p&q	$p \lor q$
0	1	-	1	1	1	1
1	0		0	1	0	1
		-	1	0	0	1
			0	0	0	0

Sets, *n*-tuples, and functions (1.1, 1.2)**Predicates (1.4)** Quantifiers (1.5)Proofs (1.6, 1.7)

Characteristic Function

Given a predicate *P* on a set *S*, there is a corresponding subset *R* of *S* consisting of all elements $a \in S$ for which P(a) = 1. We write

 $R = \{a \in S \mid P(a)\}.$

Sets, *n*-tuples, and functions (1.1, 1.2) **Predicates (1.4)** Quantifiers (1.5) Proofs (1.6, 1.7)

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Conversely, given a subset *R* of a given set *S*, the expression $x \in R$ defines a predicate *P* on S:

$$P(x) = \begin{cases} 1 & \text{if } x \in R \\ 0 & \text{if } x \notin R. \end{cases}$$

The predicate P is called the *characteristic function* of the set R.

Sets, *n*-tuples, and functions (1.1, 1.2) **Predicates (1.4)** Quantifiers (1.5) Proofs (1.6, 1.7)

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 $\{x \in S \mid P(x) \& Q(x)\} = \{x \in S \mid P(x)\} \cap \{x \in S \mid Q(x)\}, \\ \{x \in S \mid P(x) \lor Q(x)\} = \{x \in S \mid P(x)\} \cup \{x \in S \mid Q(x)\}, \\ \{x \in S \mid \sim P(x)\} = S - \{x \in S \mid P(x)\}.$

Sets, *n*-tuples, and functions (1.1, 1.2)Predicates (1.4)Quantifiers (1.5)Proofs (1.6, 1.7)

Bounded Existential Quantifier

Let $P(t, x_1, ..., x_n)$ be a (n + 1)-ary predicate. Let predicate $Q(y, x_1, ..., x_n)$ be defined by

$$Q(y, x_1, \dots, x_n) = P(0, x_1, \dots, x_n)$$

$$\lor P(1, x_1, \dots, x_n)$$

$$\lor \dots$$

$$\lor P(y, x_1, \dots, x_n)$$

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That is, $Q(y, x_1, ..., x_n)$ is true if there is a value $t \le y$ such that $P(t, x_1, ..., x_n)$ is true. We write this predicate Q as

 $(\exists t)_{\leq y} P(t, x_1, \ldots, x_n)$

" $(\exists t)_{<_{y}}$ " is called a *bounded existential quantifier*.

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Bounded Universal Quantifier

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- Instructions:

 $V \leftarrow V + 1$ Increase by 1 the value of the variable V.

 $V \leftarrow V - 1$ If the value of V is 0, leave it unchanged; otherwise decrease by 1 the value of V.

IF $V \neq 0$ GOTO L If the value of V is nonzero, perform the instruction with label L next; otherwise proceed to the next instruction in the list.

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- IF $V \neq 0$ GOTO L If the value of V is nonzero, perform the instruction with label L next; otherwise proceed to the next instruction in the list.
- ▶ Labels: *A*₁, *B*₁, *C*₁, *D*₁, *E*₁, *A*₂, *B*₂, *C*₂, *D*₂, *E*₂, *A*₃, ...
- Exit label: E.

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- Labels: $A_1, B_1, C_1, D_1, E_1, A_2, B_2, C_2, D_2, E_2, A_3, \dots$
- Exit label: *E*.
- ► All variables and labels are in the global scope.

Programming in ${\mathscr S}$

- A program is a list (i.e., a finite sequence) of instructions.
- The output variable Y and the local variables Z_i initially have the value 0.
- A program halts when there is no more instruction to execute.
- ► A program also halts if an instruction labeled *L* is to be executed, but there is no instruction with that label.

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- ► A program also halts if an instruction labeled *L* is to be executed, but there is no instruction with that label.
- What does this program do?

$$\begin{array}{ll} [A] & X \leftarrow X - 1 \\ & Y \leftarrow Y + 1 \\ & \mathsf{IF} \ X \neq 0 \ \mathsf{GOTO} \ A \end{array}$$

A Programming Language (2.1) Some Examples of Programs (2.2)

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A Bug?

What does this program do?

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$$\begin{array}{ll} [A] & X \leftarrow X - 1 \\ & Y \leftarrow Y + 1 \\ & \mathsf{IF} \ X \neq 0 \ \mathsf{GOTO} \ A \end{array}$$

▶ The above program *computes* the function

$$f(x) = \begin{cases} 1 & \text{if } x = 0 \\ x & \text{otherwise.} \end{cases}$$

A Programming Language (2.1) Some Examples of Programs (2.2)

A Program That Computes f(x) = x

 $[A] \quad IF \ X \neq 0 \ GOTO \ B$ $Z \leftarrow Z + 1$ $IF \ Z \neq 0 \ GOTO \ E$ $[B] \quad X \leftarrow X - 1$ $Y \leftarrow Y + 1$ $Z \leftarrow Z + 1$ $IF \ Z \neq 0 \ GOTO \ A$

A Programming Language (2.1) Some Examples of Programs (2.2)

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What does Z actually do?

A Programming Language (2.1) Some Examples of Programs (2.2)

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A Program That Computes f(x) = x

$$\begin{bmatrix} A \end{bmatrix} \quad \text{IF } X \neq 0 \text{ GOTO } B \\ Z \leftarrow Z + 1 \\ \text{IF } Z \neq 0 \text{ GOTO } E \\ \begin{bmatrix} B \end{bmatrix} \quad X \leftarrow X - 1 \\ Y \leftarrow Y + 1 \\ Z \leftarrow Z + 1 \\ \text{IF } Z \neq 0 \text{ GOTO } A \\ \end{bmatrix}$$

What does Z actually do?
 What does the following do?
 Z ← Z + 1
 IF Z ≠ 0 GOTO L

A Programming Language (2.1) Some Examples of Programs (2.2)

A Program That Computes f(x) = x

$$\begin{bmatrix} A \end{bmatrix} \quad \text{IF } X \neq 0 \text{ GOTO } B \\ Z \leftarrow Z + 1 \\ \text{IF } Z \neq 0 \text{ GOTO } E \\ \begin{bmatrix} B \end{bmatrix} \quad X \leftarrow X - 1 \\ Y \leftarrow Y + 1 \\ Z \leftarrow Z + 1 \\ \text{IF } Z \neq 0 \text{ GOTO } A \\ \end{bmatrix}$$

What does Z actually do?

What does the following do?

 $Z \leftarrow Z + 1$ IF $Z \neq 0$ GOTO L

That is an unconditional goto!
 GOTO L

A *Macro* for Unconditional GOTO

- Before macro expansion:
 - $\begin{bmatrix} A \end{bmatrix} \quad \begin{array}{l} \mathsf{IF} \ X \neq 0 \ \mathsf{GOTO} \ B \\ \mathsf{GOTO} \ E \end{array}$

$$\begin{bmatrix} B \end{bmatrix} \quad \begin{array}{l} X \leftarrow X - 1 \\ Y \leftarrow Y + 1 \end{array}$$

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$$\begin{bmatrix} B \end{bmatrix} \quad \begin{array}{c} X \leftarrow X - 1 \\ Y \leftarrow Y + 1 \\ \text{GOTO } A \end{array}$$

After macro expansion:

$$\begin{array}{ll} [A] & \text{ IF } X \neq 0 \text{ GOTO } B \\ & Z_1 \leftarrow Z_1 + 1 \\ & \text{ IF } Z_1 \neq 0 \text{ GOTO } E \\ [B] & X \leftarrow X - 1 \\ & Y \leftarrow Y + 1 \\ & Z_2 \leftarrow Z_2 + 1 \\ & \text{ IF } Z_2 \neq 0 \text{ GOTO } A \end{array}$$

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After macro expansion:

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$$[B] \quad X \leftarrow X - 1$$

$$Y \leftarrow Y + 1$$

$$Z_2 \leftarrow Z_2 + 1$$

IF $Z_2 \neq 0$ GOTO A

Fresh local variables are always used during macro expansions. Sac

Copy The Value of Variable X to Variable Y

- ► [A] IF $X \neq 0$ GOTO B GOTO E [B] $X \leftarrow X - 1$
 - $\begin{bmatrix} B \end{bmatrix} \quad \begin{array}{c} X \leftarrow X 1 \\ Y \leftarrow Y + 1 \\ \text{GOTO } A \end{array}$

Copy The Value of Variable X to Variable Y

- $[A] \qquad IF \ X \neq 0 \ GOTO \ B \\ GOTO \ E$
 - $\begin{array}{ll} [B] & X \leftarrow X 1 \\ & Y \leftarrow Y + 1 \\ & \text{GOTO } A \end{array}$
- Anything wrong?

Copy The Value of Variable X to Variable Y

- $\bullet [A] \qquad \mathsf{IF} \ X \neq 0 \ \mathsf{GOTO} \ B \\ \mathsf{GOTO} \ E$
 - $\begin{bmatrix} B \end{bmatrix} \quad \begin{array}{c} X \leftarrow X 1 \\ Y \leftarrow Y + 1 \\ \text{GOTO } A \end{array}$
- Anything wrong?
- The value of X is "destroyed" while copied to Y!

Copy The Value of Variable X to Variable Y, Continued

- ► [A] IF $X \neq 0$ GOTO B GOTO C
 - $\begin{bmatrix} B \end{bmatrix} \quad \begin{array}{c} X \leftarrow X 1 \\ Y \leftarrow Y + 1 \end{array}$
 - $Z \leftarrow Z + 1$

- $\begin{bmatrix} C \end{bmatrix} \quad IF \ Z \neq 0 \ GOTO \ D \\ GOTO \ E \end{bmatrix}$
- $\begin{bmatrix} D \end{bmatrix} \quad \begin{array}{c} Z \leftarrow Z 1 \\ X \leftarrow X + 1 \\ \end{array}$
 - GOTO C

Copy The Value of Variable X to Variable Y, Continued

- ► [A] IF $X \neq 0$ GOTO B GOTO C
 - $\begin{bmatrix} B \end{bmatrix} \quad \begin{array}{c} X \leftarrow X 1 \\ Y \leftarrow Y + 1 \end{array}$

$$Z \leftarrow Z + 1$$

- $\begin{bmatrix} C \end{bmatrix} \quad IF \ Z \neq 0 \ GOTO \ D \\ GOTO \ E \end{bmatrix}$
- $\begin{bmatrix} D \end{bmatrix} \quad \begin{array}{c} Z \leftarrow Z 1 \\ X \leftarrow X + 1 \\ \text{GOTO } C \end{array}$
- Anything wrong?

Copy The Value of Variable X to Variable Y, Continued

- ► [A] IF $X \neq 0$ GOTO B GOTO C
 - $\begin{bmatrix} B \end{bmatrix} \quad \begin{array}{c} X \leftarrow X 1 \\ Y \leftarrow Y + 1 \end{array}$

$$Z \leftarrow Z + 1$$

- $\begin{bmatrix} C \end{bmatrix} \quad IF \ Z \neq 0 \ GOTO \ D \\ GOTO \ E \end{bmatrix}$
- $\begin{array}{ll} [D] & Z \leftarrow Z 1 \\ & X \leftarrow X + 1 \\ & \text{GOTO } C \end{array}$
- Anything wrong?
- This program is correct only when Y and Z are initialized to the value 0. It cannot be used as a macro.

A Macro for $V \leftarrow V'$

$$V \leftarrow 0$$
[A] IF $V' \neq 0$ GOTO B
GOTO C
[B] $V \leftarrow V' - 1$
 $V \leftarrow V + 1$
 $Z \leftarrow Z + 1$
GOTO A
[C] IF $Z \neq 0$ GOTO D
GOTO E
[D] $Z \leftarrow Z - 1$
 $V' \leftarrow V' + 1$
GOTO C

A Macro for $V \leftarrow V'$

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$$V \leftarrow 0$$
[A] IF $V' \neq 0$ GOTO B
GOTO C

$$\begin{bmatrix} B \end{bmatrix} \quad V \leftarrow V' - 1 \\ V \leftarrow V \pm 1 \end{bmatrix}$$

$$Z \leftarrow Z + 1$$

C] IF
$$Z \neq 0$$
 GOTO D

GOTO E

$$\begin{array}{ll} [D] & Z \leftarrow Z - 1 \\ & V' \leftarrow V' + 1 \\ & \text{GOTO } C \end{array}$$

Anything wrong?

A Macro for $V \leftarrow V'$

$$V \leftarrow 0$$

$$[A] \qquad IF V' \neq 0 \text{ GOTO } B$$

$$GOTO C$$

$$\begin{bmatrix} B \end{bmatrix} \quad V \leftarrow V' - 1 \\ V \leftarrow V + 1 \end{bmatrix}$$

$$Z \leftarrow Z + 1$$

GOTO A

$$\begin{bmatrix} C \end{bmatrix} \quad \text{IF } Z \neq 0 \text{ GOTO } D \\ \text{GOTO } E \end{bmatrix}$$

$$\begin{array}{ll} [D] & Z \leftarrow Z - 1 \\ & V' \leftarrow V' + 1 \\ & \text{GOTO } C \end{array}$$

- Anything wrong?
- $V \leftarrow 0$ is not an instruction in \mathscr{S} .

A Programming Language (2.1) Some Examples of Programs (2.2)

A Macro for $V \leftarrow 0$

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A Programming Language (2.1) Some Examples of Programs (2.2)

A Macro for $V \leftarrow 0$

$$\begin{bmatrix} L \end{bmatrix} \quad \begin{array}{c} V \leftarrow V - 1 \\ \text{IF } V \neq 0 \text{ GOTO } L \end{array}$$

A Programming Language (2.1) Some Examples of Programs (2.2)

A Program That Computes $f(x_1, x_2) = x_1 + x_2$

$$Y \leftarrow X_1$$

$$Z \leftarrow X_2$$

$$[B] \quad \text{IF } Z \neq 0 \text{ GOTO } A$$

$$\text{GOTO } E$$

$$[A] \quad Z \leftarrow Z - 1$$

$$Y \leftarrow Y + 1$$

$$\text{GOTO } B$$

Note that Z is used to preserve the value of X_2 so that it will not be destroyed during the computation.