

✓  $T_s < \frac{1}{2f_m}$   $f_s > 2f_m$

✓  $I_A = -\log P_A$

✓  $H = \lim_{N \rightarrow \infty} \frac{I_{total}}{N} = \sum_{i=1}^M p_i \log \frac{1}{p_i}$  bits/symbol

✓  $R (\frac{bit}{sec}) = f_s (\frac{symbol}{sec}) \times H$

✓  $P_1 P_2 = P_3 P_3 + P_1 P_1$  مربوط به استقلال

$H_1 = p \log \frac{1}{p} + (1-p) \log \frac{1}{1-p} \rightarrow H = p_1 H_1 + p_2 H_2$

✓  $e = \frac{H}{H_{max}} = \frac{H}{\log 2} \quad p = 1 - e$

✓  $e' = \frac{H'}{\log 2} = H' \rightarrow H' = \frac{H}{n}$

$\frac{e'}{e} = \frac{H_n}{H/\log 2} = \frac{\log 2^n}{n}$

✓  $I_{s_i} = \log \frac{1}{p_i} = n_i$

$\bar{n} = \sum_{i=1}^M p_i n_i = \sum_{i=1}^M p_i \log \frac{1}{p_i} = H$

$H' = \frac{H}{n} = 1 \frac{bit}{n \text{ unite}} \quad \frac{e'}{e} = e, p' = 0$

$e' = \frac{H'}{\log 2}$

✓  $p_i^r = P\{x=i\} \quad P_i^r = P\{y=i\}$

✓  $p_{ij} = P\{y=j|x=i\}$

✓  $P\{x=i, y=j\} = P\{y=j|x=i\} \cdot P\{x=i\} = p_{ij} p_i^r$

✓  $p_j^r = \sum_{i=1}^M p_{ij} p_i^r$

✓  $H(x) = \sum_{i=1}^M p_i^r \log \frac{1}{p_i^r} \quad H(y) = \sum_{j=1}^M p_j^r \log \frac{1}{p_j^r}$

✓  $H(x, y) = \sum_{i=1}^M \sum_{j=1}^M P\{x=i, y=j\} \log \frac{1}{P\{x=i, y=j\}}$

✓  $H(y|x) = \sum_{j=1}^M \sum_{i=1}^M p(x=i, y=j) \log \frac{1}{p(y=j|x=i)}$

✓  $H(x|y) = \sum_{i=1}^M \sum_{j=1}^M p(x=i, y=j) \log \frac{1}{p(x=i|y=j)}$

✓  $H(x \rightarrow y) = H(x) - H(x|y) = H(y) - H(y|x)$

✓  $P_0^r = P_0 \alpha + P_0 \beta$

✓  $P_0^r = P_0 \alpha + P_0 \beta = 1 - P_0^r$

$H(y) = f_{p_0^r} \quad H(y|x) = P_0 \alpha + P_0 \beta$

✓  $D_c = f_s H(x \rightarrow y)$  میان اطلاعات انتقال یافته و نویز

✓  $C = f_s H_{max}(x \rightarrow y)$

✓ در این سیستم  $p = \frac{1}{2^{1-\beta}} \left( \frac{1}{1 + 2^{1-\alpha-\beta}} - 1 \right)$

✓  $f_s = 2B \rightarrow$  نظریه کدینگ

$H(x) = \int_{-\infty}^{+\infty} f(x) \log \frac{1}{f(x)} dx$

$\sigma_n^2 = \int_{-\infty}^{+\infty} (x-\mu)^2 f(x) dx$

$H(x) = \ln \sqrt{2\pi e \sigma_n^2}$  nat/symbol

✓  $\sigma_n^2 = N = \frac{n}{2} \times B \times 2 = nB$

$C = f_s H_{max}(x \rightarrow y) = 2B (H(y) - H(y|x))$

$C = B \log_2 \left( 1 + \frac{S}{N} \right)$

$\frac{S}{N} \rightarrow \log \frac{S}{N}$

PAM, PWM, PPM

$z(t) = \sum_{k=-\infty}^{\infty} a_k h(t-kT) = [\sum a_k \delta(t-kT)] * h(t)$

$R_z(f) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T E\{z(t)z^*(t-\tau)\} d\tau$

$F\{R_z(f)\} = S_z(f) \quad S_y(f) = S_x(f) |H(f)|^2$

$S_z(f) = S_g(f) |H(f)|^2$

$R_i = E\{a_k a_{k+i}^*\} \rightarrow R_g(\omega) = \frac{1}{T} \sum_{i=-\infty}^{\infty} R_i \delta(\omega - iT)$

$S_g(f) = \frac{1}{T} R_i e^{-j2\pi f i T} = \frac{R_0}{T} + \frac{1}{T} \sum_{i=1}^{\infty} 2R_i \cos(2\pi f i T)$

مجموعه توان:  $\int_{-\infty}^{\infty} S_z(f) df$

$f: \sum p(f - \frac{k}{T}) = T$

$p(f): B < \frac{1}{2T} \rightarrow$  ISI

$B = \frac{1}{2T} \rightarrow p(f) = \text{rect}$

$\frac{1}{2T} < B < \frac{1}{T} \rightarrow$  نویز

PAM  $R_b = \frac{R_s}{2} = \frac{1}{2T}$

2-PAM  $R_b = 2R_s$



$$y(nT) = \sum a_k P_r((n-k)T) - n(nT)$$

$$\text{معمولاً} \rightarrow y_n = a_n P_r(0) + n(nT)$$

$$P_e = P_e|a_n=a + P_e|a_n=-a$$

$$Q(n) = \int_0^\infty \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(n-x)^2}{2\sigma^2}} dx$$

$$M-PAM \rightarrow P_e|a_n=a = 2Q\left(\frac{k_a}{\sigma}\right)$$

$$P_e = 2\left(1 - \frac{1}{M}\right) Q\left(\frac{k_a}{\sigma}\right)$$

$$Q(x) = \begin{cases} 0.4 e^{-\frac{x^2}{2}} & x > 3 \\ 0.2 [\sqrt{x^2+4} e^{-\frac{x^2}{2}}] & x > 1/2 \end{cases}$$

$$x = \sqrt{-2 \ln(8Q)} \quad 10^{-9} < Q < 10^{-2}$$

$$\text{در حالت کلی} P_r(\tau) = P_b(\tau) * h_r(\tau) * h_c(\tau) * h_k(\tau)$$

$$H_T(f) H_R(f) = \frac{L P_r(f)}{P_b(f)}$$

$$\text{صاف PAM} : \frac{a_2}{T} |P_b(f)|^2$$

$$\text{صاف PAM} : \frac{a_2}{T} |P_b(f)|^2 |H_T(f)|^2 \quad \text{و } a_2 = \frac{M^2-1}{3} a^2$$

$$S_T = \frac{M^2-1}{3T} a^2 \int_{-\infty}^{\infty} |P_b(f) H_T(f)|^2 df$$

$$K = P_r(0) = \int_{-\infty}^{\infty} P_r(f) df = \int_{-\infty}^{\infty} \frac{1}{T} P_b(f) |H_T(f)|^2 df$$

$$\sigma^2 = \int_{-\infty}^{\infty} G_n(f) |H_c(f)|^2 df$$

$$\left| \int_{-\infty}^{\infty} u(f) v^*(f) df \right|^2 \leq \int_{-\infty}^{\infty} |u(f)|^2 df \int_{-\infty}^{\infty} |v(f)|^2 df$$

$$u(f) = k_0 v^*(f)$$

$$|H_R(f)|^2 = \frac{L}{k_0} P_r(f) \quad |H_T(f)| = k_0 \frac{P_r(f)}{|P_b(f)|^2}$$

$$P_e = 2\left(1 - \frac{1}{M}\right) Q\left(\sqrt{\frac{6SRT}{(M^2-1)N}}\right)$$

$$\text{صاف PAM} : |H_R(f)|^2 = \frac{1}{k_0} \left| \frac{P_r(f)}{H_c(f)} \right| \times \frac{1}{\sqrt{G_n(f)}}$$

$$|H_T(f)| = k_0 \left| \frac{P_r(f)}{H_c(f)} \right| \times \frac{\sqrt{G_n(f)}}{|P_b(f)|^2}$$

$$P_e = 2\left(1 - \frac{1}{M}\right) Q\left(\sqrt{\frac{6SRT}{M^2-1} \left[ \frac{\int_{-\infty}^{\infty} P_r(f) df}{P_r(f) \sqrt{G_n(f) H_c(f)}} \right]}\right)$$

$$r_s = \frac{r_b}{\log_2 M} \quad T = \frac{1}{r_s} = \frac{\log_2 M}{r_b}$$

$$B_w > \frac{r_s}{2}$$

$$\frac{B_w}{B_w} \frac{M-PAM}{\text{binary-PAM}} = \frac{1}{\log_2 M}$$

$$\text{در حالت کلی} P_e \rightarrow \frac{M-\text{ary توان}}{\text{binary توان}} = \frac{M^2-1}{3 \log_2 M}$$

$$P_{eN} = 2\left(1 - \frac{1}{M}\right) Q\left(\sqrt{\frac{6SRT}{(M^2-1)N}}\right)$$

$$P_{eN} = 1 - (1 - P_e)^N = 1 - (1 - N P_e) = N P_e$$

$$\text{در حالت کلی} : G_2(f) = G_1(f) |P(f)|^2$$

$$\downarrow$$

$$a_k \delta(t - kT)$$

$$G_1(f) = \frac{1}{T} \sum_{n=-\infty}^{\infty} R_n e^{j2\pi n f T}$$

$$\text{در حالت کلی} : \text{Bipolar} \rightarrow \frac{1}{T} \sum_{n=-\infty}^{\infty} R_n e^{j2\pi n f T}$$

$$\text{در حالت کلی} : \text{HDB3} : 0000 \leq \frac{0000}{1000}$$

$$\text{در حالت کلی} : \text{4B3T} \rightarrow \text{زیر کلاس 4 بیت 3 تایی}$$

$$\text{در حالت کلی} : f(t) = c_2 \delta(t) + c_1 \delta(t-T) + c_0 \delta(t-2T) + \dots$$

$$f(t) = \sum_{n=-N}^N c_n \delta(t - nT)$$

$$F(f) = \sum_{n=-N}^N c_n e^{-j2\pi n f T}$$

$$P_{eq}(t) = \sum_{n=-N}^N c_n P_r(t - nT) \rightarrow P_{eq}(T) = 0$$

$$\text{در حالت کلی} : T = \frac{\ln \frac{1-P}{1-P}}{2k_0}$$

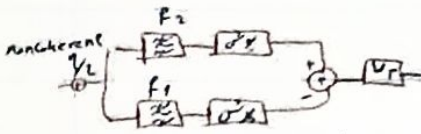
$$P_r(f) = \begin{cases} T & |f| < \frac{r_s}{2} - \beta \\ T \cos \frac{2\pi}{4\beta} \left( |f| - \frac{r_s}{2} + \beta \right) & \frac{r_s}{2} - \beta < |f| \leq \frac{r_s}{2} \\ 0 & |f| > \frac{r_s}{2} + \beta \end{cases}$$

$$0 < \beta < \frac{r_s}{2} \rightarrow P_r(t) = \frac{6SRT\beta}{1 - (4\beta T)^2} \left( \frac{\sin \pi f T}{\pi f T} \right)$$

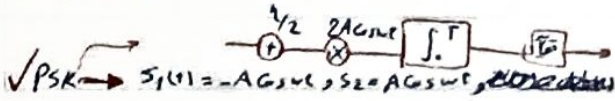
$dBW = 10 \log P$ ,  $48m = dBW + 30db$



$P_e = Q(\sqrt{\frac{E}{2\eta}})$



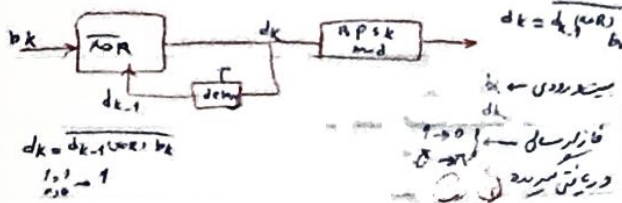
$P_e = \frac{1}{2} e^{-\frac{SRT}{4\eta}}$



$Z(t) = A b(t) \cos \omega_c t$ ,  $b(t) = \sum_k a_k \text{rect}(\frac{t-kT}{T})$ ,  $a_k = \pm 1$

$G_2(f) = \frac{A^2 T}{4} [\text{sinc}^2(f-f_c)T + \text{sinc}^2(f+f_c)T]$

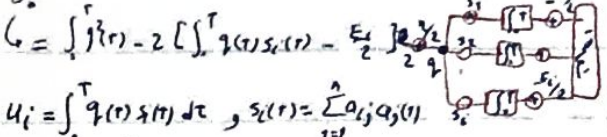
$\beta = \frac{2}{T}$ ,  $V_T = 0$ ,  $S_R = \frac{A^2}{2}$ ,  $P_e = Q(\sqrt{\frac{A^2 T}{2\eta}}) = Q(\sqrt{\frac{2E}{\eta}})$



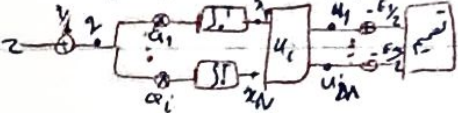
$\lambda = \log_2 \frac{M}{2}$ ,  $T = \frac{\lambda}{f_b} = \frac{\log_2 M}{f_b}$

$\frac{P_{min}}{P_{max}} = \frac{1}{T} = \frac{f_b}{1}$

$\int_0^T (q_1(t) - s_2(t))^2 dt \rightarrow \text{min} \rightarrow \text{optimal filter}$



$u_i = \int_0^T q(t) s(t) dt$ ,  $s_2(t) = \sum_{j=1}^N a_j s_j(t)$



$\sqrt{M-PSK} \rightarrow S_1(t) = A \cos(\omega_c t - \frac{2\pi}{M})$

$A \cos \frac{2\pi}{M} \cos \omega_c t = A \sin \frac{2\pi}{M} \sin \omega_c t$

$Z(t) = A B_1(t) \cos \omega_c t + A B_2(t) \sin \omega_c t$

$B_j(t) = \sum_k a_k \text{rect}(\frac{t-kT}{T})$ ,  $a_k = \cos \frac{2\pi}{M}$ ,  $\cos \frac{4\pi}{M}$ ,  $\cos \frac{6\pi}{M}$

$\beta = \frac{2}{T}$

$\int_0^\infty x e^{-ax^2} dx = \frac{1}{2a^2}$ ,  $d_k = d_{k-1} + b_k$

$x = \begin{cases} S_1(t - (k-1)T) & b_k = 0 \\ S_2(t - (k-1)T) & b_k = 1 \end{cases}$   $(k-1)T \leq t < kT$

✓  $\text{binary ASK} = 0 / AG \cos(2\pi f_c t)$

$FSK \rightarrow AG \cos(2\pi(f_c - f_d)t) / AG \cos(2\pi(f_c + f_d)t)$

$PSK \rightarrow AG \cos(2\pi f_c t) / -AG \cos(2\pi f_c t)$

✓  $\text{فیلتر فضایی} \rightarrow H(f) = (P(f) e^{j2\pi f T})^n$ ,  $h(t) = P(t-t)$

✓  $y(t) = P(t) a h(t) + n(t)$ ,  $y(t) < \frac{P_c T}{2}$ ,  $y(t) > \frac{P_c T}{2}$

$[P_c^2(t)]_{min} = \frac{2E}{T}$ ,  $P_e = Q(\frac{P_c T}{2\sigma})$

$\sigma_n^2 = \int_{-\infty}^{\infty} \frac{1}{2} |H(f)|^2 df$

✓  $\text{Correlator} \rightarrow r(t) = \int p(\tau) n'(t-\tau) + h(t) = P(t-T)$

$y(t) = q(t) a h(t) = \int_{-\infty}^{\infty} q(t-\lambda) h(\lambda) d\lambda = \int_{-\infty}^{\infty} q(t-\lambda) P(T-\lambda) d\lambda$

$y(t) = \int_{-\infty}^{\infty} q(u) P(u) du = \langle q(t) P(t) \rangle$

$y(t) = \begin{cases} s_{10}(t) \\ s_{20}(t) \end{cases} + n(t)$ ,  $s_{10}(t) = s_1(t) a h(t)$ ,  $s_{20}(t) = s_2(t) a h(t)$

$\bar{y} = \frac{s_{10}(T) + s_{20}(T)}{2}$ ,  $P_e = Q(\frac{s_{20}(T) - s_{10}(T)}{2\sigma})$

$P_e(t) = s_{20}(t) - s_{10}(t) \rightarrow P_e = Q(\frac{P_c(t)}{2\sigma})$

$h(t) = s_2(T-t) - s_1(T-t) = P(T-t)$

✓  $\text{ASK} \rightarrow Z(t) = d(t) A \cos 2\pi f_c t$ ,  $d(t) = \frac{1}{2}(1 + b(t))$

$AG \cos(2\pi f_c t) \xrightarrow{f} \frac{A^2}{4} [\delta(f-f_c) + \delta(f+f_c)]$ ,  $\beta = \frac{2}{T} = 2R_s$

$\text{rect}(\frac{t}{T}) \xrightarrow{f} T \text{sinc}(fT)$ ,  $G_b(f) = \frac{1}{T} T^2 \text{sinc}^2(fT)$

$V_T = \frac{A^2 T}{4}$ ,  $P_e = Q(\sqrt{\frac{E}{2\eta}})$ ,  $E = \frac{A^2 T}{2}$ ,  $P_e = Q(\sqrt{\frac{A^2 T}{2\eta}})$

$P_e = Q(\sqrt{\frac{SRT}{\eta}})$ ,  $\text{PAM: } P_e = Q(\sqrt{\frac{2SRT}{\eta}})$

noncoherent  $\rightarrow$   $\text{BPF}$   $\rightarrow$   $\text{PAM}$

$P_e = \frac{1}{2} e^{-\frac{SRT}{4\eta}}$ ,  $S_R = \frac{A^2}{4} \Rightarrow AGC$

✓  $FSK \rightarrow Z(t) = \frac{A}{2} [1 + b(t)] \cos 2\pi f_1 t + \frac{A}{2} [1 + b(t)] \cos 2\pi f_2 t$

$f_1 = f_c - f_d$ ,  $f_2 = f_c + f_d$ ,  $\beta \approx 2f_d + \frac{2}{T}$

$S \cdot \rho(T) = \int_0^T s_1(t) [s_2(t) - s_1(t)] dt \rightarrow V_T = 0 \rightarrow AGC$

$P = Q(\sqrt{\frac{E}{2\eta}})$ ,  $E = \int_0^T [s_2(t) - s_1(t)]^2 dt$ ,  $E = A^2 T [1 - \text{sinc}(2(f_2 - f_1)T)]$

$P_e = Q(\sqrt{\frac{A^2 T [1 - \text{sinc}(2(f_2 - f_1)T)]}{2\eta}}) = Q(\sqrt{\frac{A^2 T}{2\eta} k})$

$S_R = \frac{A^2}{2} \times \frac{1}{2} + \frac{A^2}{2} \times \frac{1}{2} = \frac{A^2}{2}$

$Q(\sqrt{\lambda}) \approx \frac{1}{\sqrt{2\pi} \sqrt{\lambda}} e^{-\lambda}$



$$d(C, R) + d(C', R) \geq d(C, C')$$

$$d(C, C') \geq d_{min} \rightarrow C' + d(C', R) \geq d(C, C') \geq d_{min}$$

$$d(C', R) \geq d_{min} - C' \Rightarrow /$$

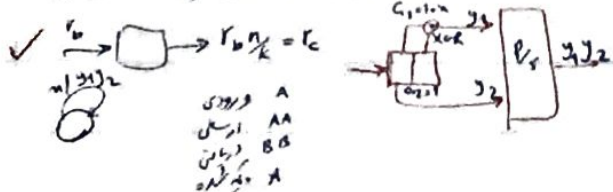
$$\Rightarrow d_{min} - C' \leq d(C', R) \leq d(C, R) = C' \rightarrow C' < \frac{d_{min}}{2}$$

$$\rightarrow N \gg k + \log_2 N^{k+1}$$

$$(12, 8) \rightarrow 2^4 - 1 - 4 = 11$$

S	C1	C2	C3	C2k
E1HT	E2	C2+E2	C3+E2	
E3HT	E3	C2+E3	C3+E3	
E2+E3HT	E2+E3	C2+E2+E3	C3+E2+E3	

$$R = C + E_2, S = RH^T = (C + E_2)H^T = E_2H^T$$



$$d_{min} \rightarrow \left[ \frac{d_{min} - 1}{2} \right], d_{min} - 1$$

$$\text{rect}(at) \rightarrow \frac{1}{|a|} \text{sinc}\left(\frac{f}{a}\right)$$

$$\text{sinc}(at) \rightarrow \frac{1}{|a|} \text{rect}\left(\frac{f}{a}\right)$$

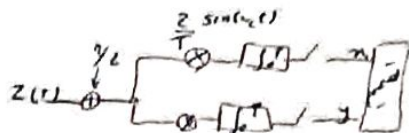
$$\text{sinc}^2(at) \rightarrow \frac{1}{|a|} \text{tri}\left(\frac{f}{a}\right)$$

$$\text{tri}(at) \rightarrow \frac{1}{|a|} \text{sinc}^2\left(\frac{f}{a}\right)$$

$$V_T = \frac{N}{2B} \log_2 \frac{P(0)}{P(1)}$$

$$\text{PSK} \rightarrow S_1 = -A^2 T_b, S_2 = A^2 T_b, N_s = 2A^2 T_b$$

$$B = A^2 T_b$$



$$\text{MPSK} \rightarrow z(t) = s_i(t) = A G_s(\omega_c t - \frac{2\pi n t}{M}) \rightarrow \text{sinc}\left(\frac{t}{T}\right)$$

$$x = \frac{2}{T} \int_0^T q(t) G_s(\omega_c t) dt = A G_s \frac{2A T}{M}, y = A \sin \frac{2\pi n t}{M}$$

$$n(t) \rightarrow \begin{cases} x = \frac{2}{T} \int_0^T n(t) G_s(\omega_c t) dt \\ y = \frac{2}{T} \int_0^T n(t) \sin(\omega_c t) dt \end{cases}$$

$$r_x = \frac{2}{T} \int_0^T n(t) G_s(\omega_c t) dt = \frac{2}{T} \int_0^T n(t) G_s(\omega_c t) dt$$

$$G_x^2 = \frac{4}{T^2} \left[ \int_0^T n(t) G_s(\omega_c t) dt \right]^2 = \frac{2T}{T} \times \frac{T}{2} = \frac{T}{T}$$

$$\text{4PSK} \rightarrow P_e = Q\left(\frac{A\sqrt{2}}{c}\right) + Q\left(\frac{A\sqrt{2}}{c}\right) - Q^2\left(\frac{A\sqrt{2}}{c}\right)$$

$$G_x^2 = \frac{2}{T}, \text{MPSK} \rightarrow P_e = 2Q\left(\frac{A \sin \frac{\pi}{M}}{c}\right)$$

$$r_b = T = \frac{\log_2 M}{r_b}, S_R = \frac{A^2}{2}, P_e = 2Q\left(\sqrt{\frac{2S_R \log_2 M}{2r_b}}\right)$$

$$B = \frac{2}{T} \cdot \frac{2r_b}{\log_2 M}$$

$$\text{MQAM, MASK/PSK} \rightarrow \dots$$

$$1/8 \rightarrow P_e = 4 \times \frac{1}{16} Q\left(\frac{A}{c}\right) + \frac{8}{16} \times 3 Q\left(\frac{A}{c}\right) + \frac{4}{16} \times 2 Q\left(\frac{A}{c}\right)$$

$$S_R = \frac{4}{16} \left(\frac{A^2}{2}\right) + \frac{8}{16} \left(\frac{A^2}{2}\right) + \frac{4}{16} \left(\frac{A^2}{2}\right) = SA^2$$

$$\text{MFSK} \rightarrow s_i(t) = A G_s \omega_c t$$



$$\int_0^T A^2 G_s(\omega_c t) G_s(\omega_c t) dt = 0 \rightarrow (\omega_1 - \omega_2)T = n\pi$$

$$B = \frac{M+3}{2T}, P_e = (M-1)Q\left(\frac{d}{8}\right) \rightarrow A\sqrt{2}$$

$$S_R = \frac{A^2}{2}, G_s = \sqrt{\frac{2}{T}}, T = \frac{\log_2 M}{r_b} \rightarrow P_e = (M-1)Q\left(\sqrt{\frac{S_R T}{2}}\right)$$

$$P_e = P\{d_k \neq \hat{d}_k\}, P_e = P\{b_k \neq \hat{b}_k\}$$

$$\dots$$

$$C = DG \rightarrow G = [I_{k \times k} \mid P_{k \times n-k}]_{k \times n}$$

$$H = \begin{bmatrix} P_{n-k \times k}^T & I_{n-k \times n-k} \end{bmatrix} \rightarrow GH^T = 0$$

$$CH^T = DGH^T = 0 \rightarrow \dots$$

$$S = RH^T = (C+E)H^T = EH^T \rightarrow H \text{ ستون}$$