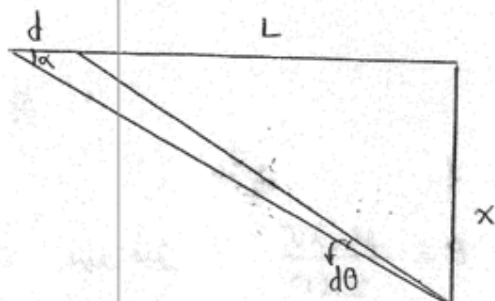


دوره ششم نهم

(1)

(الف)



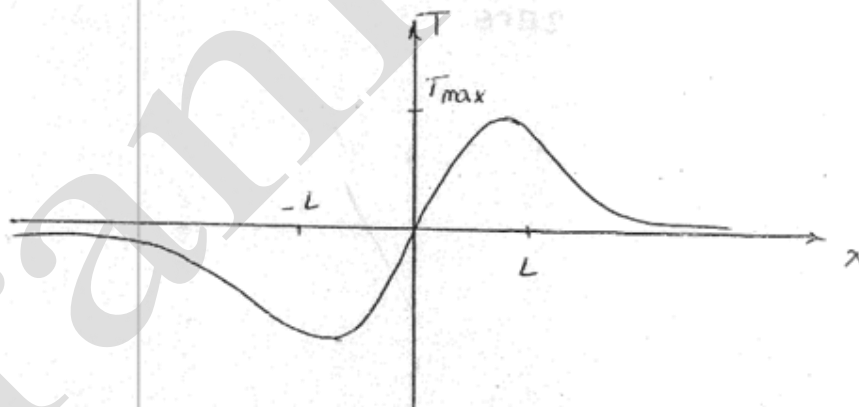
قضیه سینوس:  $\sqrt{L^2+x^2} d\theta = (d) \sin \alpha$

$$\sin \alpha = \frac{x}{\sqrt{x^2+(L+d)^2}} \Rightarrow$$

چون  $\frac{d}{L} \ll 1$  پس  $\frac{d}{L}$  را امر بی‌اهمیت می‌دانیم

$$d\theta \sqrt{L^2+x^2} = \frac{x d}{\sqrt{x^2+L^2}} \Rightarrow d\theta = \frac{x d}{x^2+L^2}$$

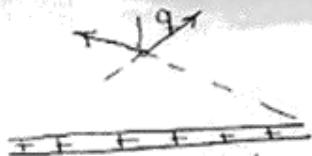
$$d\theta = \omega T \Rightarrow T = \frac{x d}{\omega (x^2+L^2)}$$



$$\frac{dT}{dx} = 0 \Rightarrow \frac{dT}{dx} = \frac{d}{\omega} \left( \frac{L^2+x^2-2x^2}{(L^2+x^2)^2} \right) = \frac{d}{\omega} \left( \frac{L^2-x^2}{L^2+x^2} \right) = 0 \Rightarrow x = \pm L$$

$$ب) T_{\max} = \frac{dL}{2\omega L^2} = \frac{d}{2\omega L} = \frac{1}{30 \times 2 \times 6} = \frac{1}{360} \approx 0.003 \text{ s}$$

الف) 2)



در جهت +y

$$ب) \vec{F}_E = \frac{q\lambda}{2\pi\epsilon_0 r}$$

$$ج) I = \lambda v$$

$$د) 2\pi r B = \mu I \rightarrow B = \frac{\mu \lambda v}{2\pi r} \quad \text{بسیار بیرون سنه}$$

$$ه) \vec{F}_B = q \vec{v} \times \vec{B} = - \frac{q v \mu \lambda v}{2\pi r} \hat{y} = - \frac{q \mu \lambda v^2}{2\pi r} \hat{y}$$

$$و) \vec{F} = \vec{F}_E + \vec{F}_B = \frac{q}{2\pi r} \left( \frac{\lambda}{\epsilon_0} - \mu \lambda v^2 \right) \hat{y}$$

$$= \frac{q\lambda}{2\pi r} \left( \frac{1}{\epsilon_0} - \mu v^2 \right) \hat{y}$$

$$ز) \frac{F}{F_E} = \frac{\frac{q\lambda}{2\pi r \epsilon_0} (1 - \mu \epsilon_0 v^2) \hat{y}}{\frac{q\lambda}{2\pi r \epsilon_0}} = 1 - \mu \epsilon_0 v^2$$

3)

الف)  $F = +NK(\Delta x - \Delta z)$

ب)  $\Delta x = \frac{L}{N} \rightarrow N = \frac{L}{\Delta x}$

$$F = +NK(\Delta x - \Delta z) = +LK + \frac{LK\Delta z}{\Delta x}$$

$$\lim_{n \rightarrow \infty} F = -KL \left( \frac{dz}{dx} - 1 \right)$$

ج)  $(L-x)\omega = -KL \left( \frac{dz}{dx} - 1 \right)$

$$\frac{dz}{dx} = -\frac{(L-x)\omega}{KL} + 1$$

$$\rightarrow \int dz = \int \left( -\frac{L-x}{KL}\omega + 1 \right) dx$$

$$z = \left( -\frac{\omega}{K} + 1 \right)x + \frac{\omega x^2}{2KL}$$

د)  $x=L \rightarrow z(L) = \left( -\frac{\omega}{K} + 1 \right)L + \frac{\omega L^2}{2KL} = L \left( 1 - \frac{\omega}{2K} \right)$

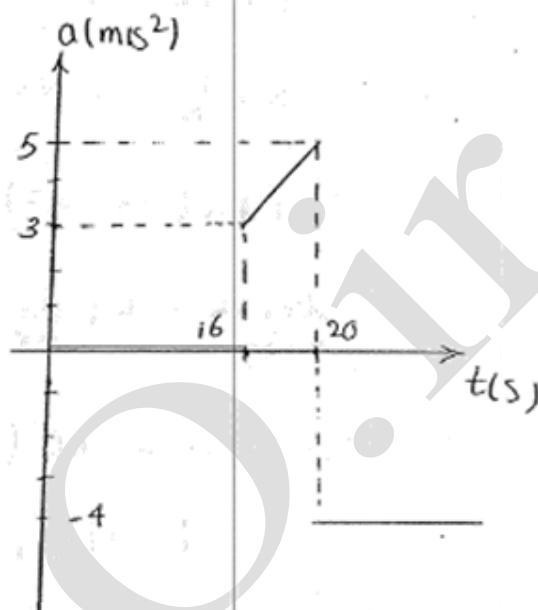
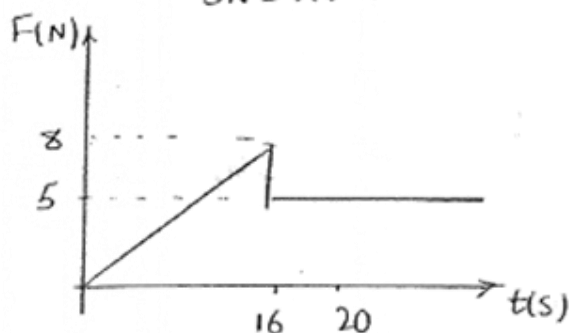
$$\Delta = L - z(L) = \frac{\omega L}{2K}$$

ه)  $\omega L = K\Delta L \rightarrow \Delta L = \frac{\omega L}{K}$

4)

الف)  $f_s = 0.8 \times 19 = 8 \text{ N}$

$$8 \text{ N} = \alpha t \rightarrow t = 16 \text{ s}$$

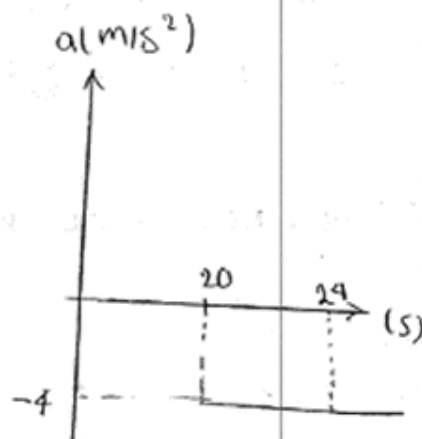
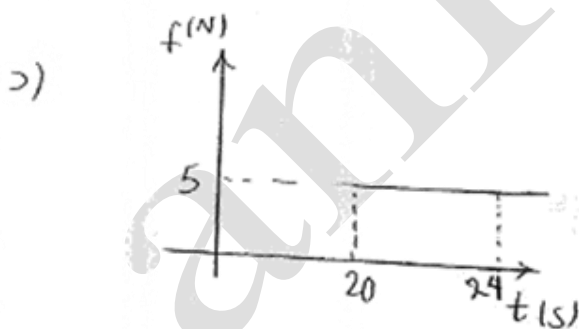


سأب از ثانیه 20 تا 16  $a = \alpha t - 5$

سأب بعد از ثانیه 20  $a = 1 - 5 = -4 \text{ m/s}^2$

ب)  $v = \frac{(5+3) \times 4}{2} = 16 \text{ m/s}$

ج)  $16 = 4(t - 20) \rightarrow t = 24 \text{ s}$



5)

(الف) برای هر همسایه‌ای به همسایه‌های مجاورش  $-\frac{v}{2}$  انرژی می‌دهد

$$\Rightarrow E = -\frac{NV}{2}$$

ب)  $TS = -a \ln(-\frac{NV}{2}) \Rightarrow T = \frac{anNV}{2}$

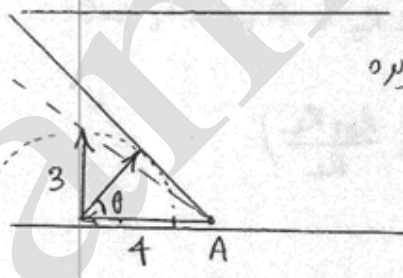
ج)  $Q = -m \times \frac{1}{f} \times n \times (-\frac{NV}{2}) = \frac{mnNV}{2f}$

د) 
$$\begin{cases} 7 \times 10^{-2} = \frac{anNV}{2} \\ 2000 \times 10^3 = \frac{mnNV}{2f} \end{cases} \Rightarrow \begin{cases} 7 \times 10^{-2} = 2000 \times 10^3 \times 10^3 \times a \\ a = 3.5 \times 10^{-11} \text{ m} \end{cases}$$

6)

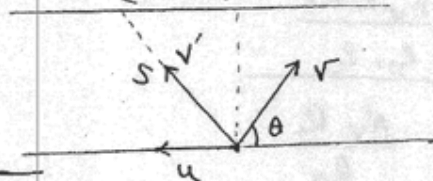
(الف) چون که کوتاه‌ترین مسیر مستقیم است که مورد بردارنده است.  $3 \sin \theta = 2 \Rightarrow \theta = \arcsin \frac{2}{3}$

ب) راه اول: کوتاه‌ترین مسیر برای معادلی است که بر نیم دایره به شعاع 3 برخورد می‌کند



$$\theta = \arccos \frac{3}{4}$$

راه دوم:



$$\begin{aligned} S^2 &= x^2 + d^2 \\ \Rightarrow \frac{dS}{d\theta} \times rS &= 0 \Rightarrow r u \frac{dx}{d\theta} = 0 \\ &\Rightarrow \frac{dx}{d\theta} = 0 \end{aligned}$$

$$v' = \sqrt{v^2 + u^2} - r u \cos \theta$$

$$u - v \cos \theta = \frac{x}{t} \Rightarrow (u - v \cos \theta) t = x$$

$$(v \sin \theta) t = d \Rightarrow t = \frac{d}{v \sin \theta}$$

$$\Rightarrow x = \frac{(u - v \cos \theta) d}{v \sin \theta}$$

$$\Rightarrow \frac{dx}{d\theta} = 0 \Rightarrow v d \sin^2 \theta - v u d \cos \theta + v^2 d \cos^2 \theta = 0 \Rightarrow v = u \cos \theta$$

7) الف)  $A_f = \frac{x_o}{x_s} \quad A = \frac{x_o}{x_i} \quad x_i = x_s - x_f$

$x_i = \frac{x_o}{A} \rightarrow \frac{x_o}{A} = x_s - \beta x_o \rightarrow x_s = x_o \left( \beta + \frac{1}{A} \right)$

$\rightarrow A_f = \frac{A}{1 + \beta A}$



$x_f = \beta x_o$

$v_i = i_i R_i$

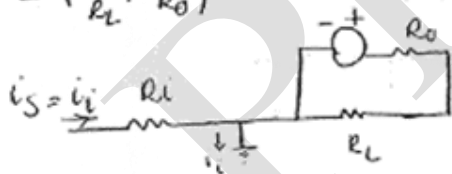
$i_f = \beta V_o$

$A'_v v_i + R_o i_i = V_o$

$i_f = - \left( \frac{V_o}{R_L} + i_i \right) = \beta V_o$

$\Rightarrow - \left( \frac{V_o}{R_L} + \frac{V_o - A'_v v_i}{R_o} \right) = \beta V_o \Rightarrow \beta = - \left( \frac{1}{R_L} + \frac{1}{R_o} \right) + \frac{A'_v}{R_o} \left( \frac{v_i}{V_o} \right)$

$\Rightarrow \beta = - \left( \frac{1}{R_L} + \frac{1}{R_o} \right)$



$\begin{cases} A_f = \frac{A}{1 + \beta A} \\ \beta = - \left( \frac{1}{R_L} + \frac{1}{R_o} \right) \end{cases}$

$A = \frac{V_o}{i_i} \quad -V_o - \frac{V_o}{R_L} R_o + A'_v R_i i_i = 0$

$A'_v R_i i_i = V_o \left( \frac{R_o + R_L}{R_L} \right)$

$A = \frac{A'_v R_i R_L}{R_o + R_L}$

$A'_v = \frac{A}{1 + \beta A} = \frac{\frac{A'_v R_i R_L}{R_o + R_L}}{1 - \frac{A'_v R_i}{R_o}}$