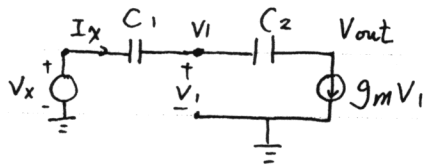


Chapter 6

6.1 (a)

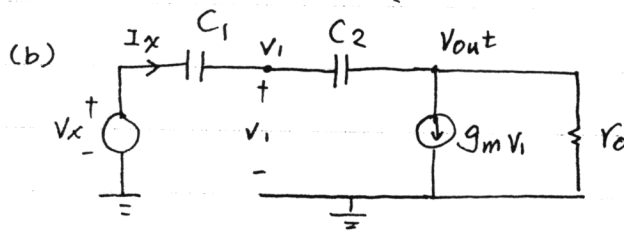
 g_m : transconductance of M_1

$$I_x = sC_1(V_x - V_1) = sC_2(V_1 - V_{out}) = g_m V_1$$

$$\therefore sC_1 V_x = (g_m + sC_1)V_1 \Rightarrow V_1 = \left[\frac{sC_1}{g_m + sC_1} \right] V_x$$

$$\Rightarrow I_x = g_m V_1 = \left[\frac{g_m sC_1}{g_m + sC_1} \right] V_x$$

$$\Rightarrow Z_{in} = \frac{V_x}{I_x} = \frac{g_m + sC_1}{g_m sC_1} *$$



$$g_m = g_{m1} + g_{m2}$$

$$r_o = r_{o1} \parallel r_{o2}$$

 g_{m1}, g_{m2} : transconductance for M_1, M_2 r_{o1}, r_{o2} : output resistance for M_1, M_2

$$\therefore I_x = \overbrace{sC_1(V_x - V_1)}^{(2)} = \underbrace{sC_2(V_1 - V_{out}) + g_m V_1}_{(1)} + \frac{V_{out}}{r_o}$$

$$\text{from (1):} \quad \frac{V_{out}}{V_1} = \frac{sC_2 - g_m}{sC_2 + \frac{1}{r_o}}$$

$$\begin{aligned} \text{from (2):} \quad (sC_1 + sC_2)V_1 &= sC_1 V_x + sC_2 V_{out} \\ &= sC_1 V_x + \frac{s^2 C_2^2 - g_m sC_2}{sC_2 + \frac{1}{r_o}} V_1 \end{aligned}$$

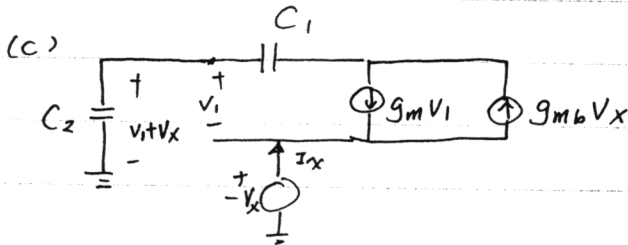
$$\Rightarrow \left[sC_1 + sC_2 - \frac{s^2 C_2^2 - g_m sC_2}{sC_2 + \frac{1}{r_o}} \right] V_1 = sC_1 V_x$$

$$\Rightarrow \left[\frac{s^2 C_1 C_2 + \frac{s C_1}{r_o} + \frac{s C_2}{r_o} + g_m s C_2}{s C_2 + \frac{1}{r_o}} \right] V_1 = s C_1 V_x$$

$$\therefore V_1 = \left[\frac{s C_1 C_2 + \frac{C_1}{r_o}}{s C_1 C_2 + \frac{C_1}{r_o} + \frac{C_2}{r_o} + g_m C_2} \right] V_x$$

$$I_x = s C_1 (V_x - V_1) = s C_1 \cdot \left[\frac{\frac{C_2}{r_o} + g_m C_2}{s C_1 C_2 + \frac{C_1}{r_o} + \frac{C_2}{r_o} + g_m C_2} \right] V_x$$

$$Z_{in} = \frac{V_x}{I_x} = \frac{s C_1 C_2 + \frac{C_1}{r_o} + \frac{C_2}{r_o} + g_m C_2}{s C_1 C_2 \left(\frac{1}{r_o} + g_m \right)}$$



$$s C_2 (V_1 + V_x) + g_m V_1 = g_{mb} V_x$$

$$\Rightarrow (s C_2 + g_m) V_1 = (g_{mb} - s C_2) V_x$$

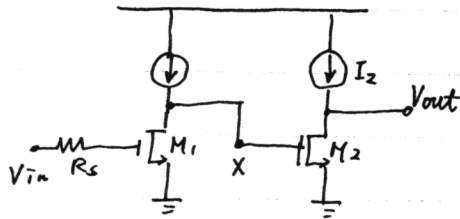
$$\frac{V_x}{V_1} = \frac{s C_2 + g_m}{g_{mb} - s C_2}$$

$$I_x = -g_m V_1 + g_{mb} V_x$$

$$= \left[-g_m \cdot \frac{g_{mb} - s C_2}{s C_2 + g_m} + g_{mb} \right] V_x = \left[\frac{(g_m + g_{mb}) s C_2}{s C_2 + g_m} \right] V_x$$

$$Z_{in} = \frac{V_x}{I_x} = \frac{s C_2 + g_m}{s C_2 (g_m + g_{mb})}$$

6.2 (a)



There are three poles associated with this circuit.

The first pole @ V_{out}

$$\omega_{pout} = \frac{1}{r_{o2} \cdot (C_{gd2} + C_{db2})}$$

The pole @ the input

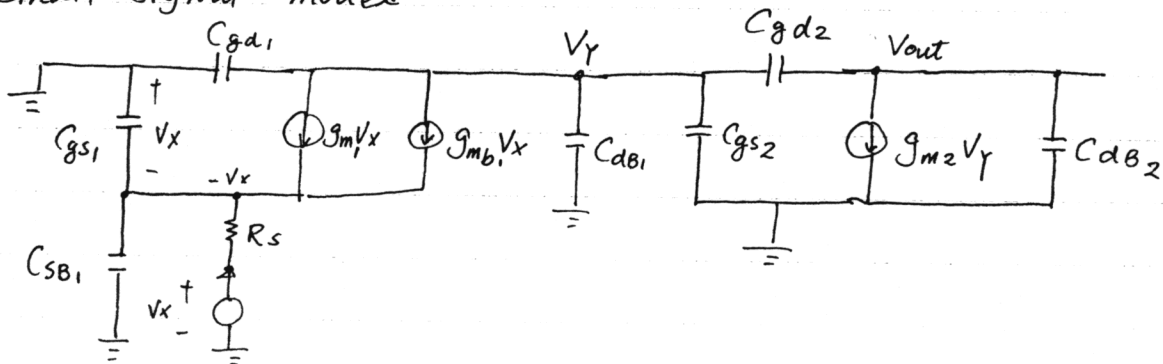
$$\omega_{p, in} = \frac{1}{R_s \cdot [(1 + g_{m1} r_{o1}) C_{gd1} + C_{gs1}]}$$

The pole @ node X

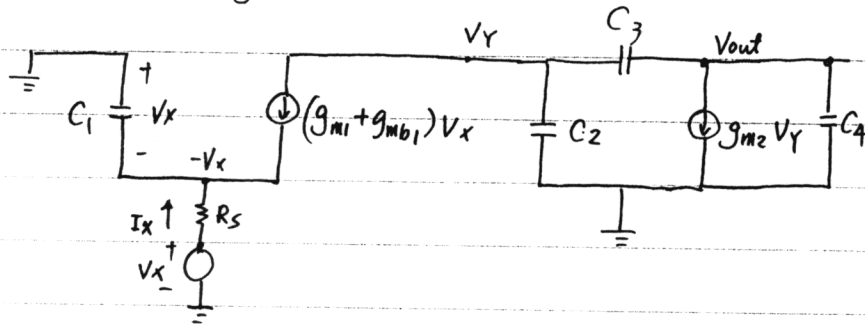
$$\omega_{p, X} = \frac{1}{r_{o1} \cdot [(C_{gd1} + C_{db1} + C_{gs2}) + (1 + g_{m2} r_{o2}) \cdot C_{gd2}]}$$

Please note that the above approximation is based on Miller effect. In order to get more accuracy approximation, transfer function has to be derived.

(b) Small signal model



Redraw small signal model



where,

$$C_1 = C_{gs1} + C_{SB1}$$

$$C_2 = C_{gs2} + C_{dB1} + C_{gd1}$$

$$C_3 = C_{gd2}$$

$$C_4 = C_{dB2}$$

$$\text{KCL @ } V_{out} : S C_3 (V_Y - V_{out}) = g_{m2} V_Y + S C_4 V_{out}$$

$$\Rightarrow \frac{V_{out}}{V_Y} = \frac{-g_{m2} + S C_3}{S (C_3 + C_4)}$$

$$\text{KCL @ } V_Y : (g_{m1} + g_{mb1}) V_X + S C_2 V_Y + S C_3 (V_Y - V_{out}) = 0$$

$$(g_{m1} + g_{mb1}) V_X = -V_Y \left(S C_2 + \frac{S^2 C_3 C_4 + S C_3 g_{m2}}{S (C_3 + C_4)} \right)$$

$$\frac{V_Y}{V_X} = - \frac{g_{m1} + g_{mb1}}{\left[S (C_2 C_3 + C_2 C_4 + C_3 C_4) + C_3 g_{m2} \right] / (C_3 + C_4)}$$

$$\text{KCL @ } V_X : \frac{V_{in} + V_X}{R_S} + S C_1 V_X + (g_{m1} + g_{mb1}) V_X = 0$$

$$\frac{V_X}{V_{in}} = - \frac{1}{S C_1 R_S + (1 + (g_{m1} + g_{mb1}) \cdot R_S)}$$

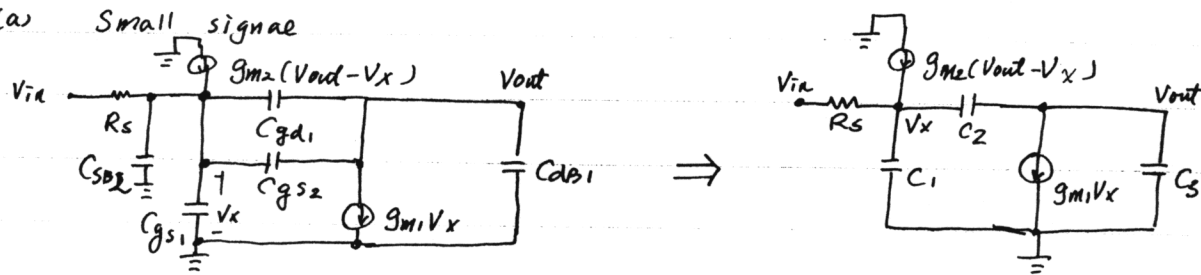
Thus, there are three poles

$$\omega_{p0} = 0$$

$$\omega_{p1} = \frac{-C_3 g_{m2}}{C_2 C_3 + C_2 C_4 + C_3 C_4} \quad *$$

$$\omega_{p2} = \frac{-(1 + (g_{m1} + g_{mb1}) \cdot R_S)}{C_1 R_S} \quad *$$

6.3 (a)



$$C_1 = C_{gs1} + C_{sb2}$$

$$C_2 = C_{gd1} + C_{gs2}$$

$$C_3 = C_{db1}$$

KCL @ Vout :

$$SC_2(V_X - V_{out}) = g_{m1}V_X + SC_3V_{out}$$

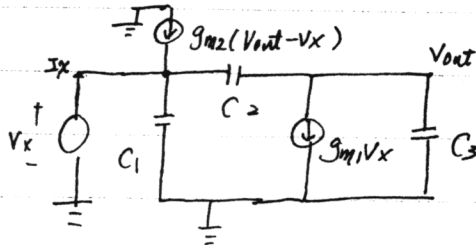
$$\therefore \frac{V_{out}}{V_X} = \frac{SC_2 - g_{m1}}{S(C_2 + C_3)} \quad \text{--- } \textcircled{D}$$

$$\text{KCL @ } V_X: \frac{V_{in} - V_X}{R_S} + g_{m2}(V_{out} - V_X) = SC_1V_X + SC_2(V_X - V_{out})$$

$$\Rightarrow \frac{V_X}{R_S} = V_X \left(\frac{1}{R_S} + g_{m2} + SC_1 + SC_2 \right) - (g_{m2} + SC_2) \cdot \left[\frac{SC_2 - g_{m1}}{S(C_2 + C_3)} \right] V_X$$

$$= V_X \cdot \frac{S^2(C_1C_2 + C_2C_3 + C_1C_3) + S \left(\frac{1}{R_S}(C_2 + C_3) + g_{m1}C_2 + g_{m2}C_2 \right) + g_{m1}g_{m2}}{S(C_2 + C_3)}$$

$$\therefore \frac{V_{out}}{V_{in}} = \frac{V_{out}}{V_X} \cdot \frac{V_X}{V_{in}} = \frac{\frac{1}{R_S}(SC_2 - g_{m1})}{S^2(C_1C_2 + C_2C_3 + C_1C_3) + S \left[\frac{1}{R_S}(C_2 + C_3) + g_{m1}C_2 + g_{m2}C_3 \right] + g_{m1}g_{m2}} \quad \star$$



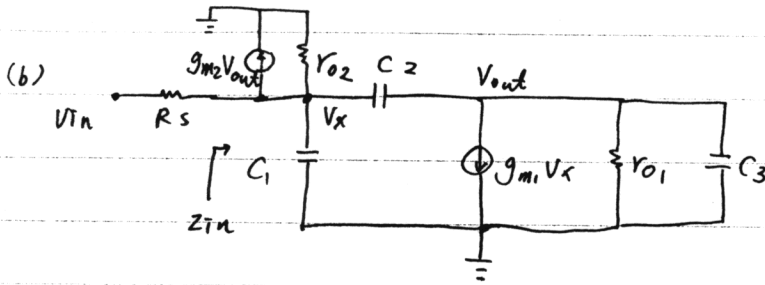
$$I_X = SC_1V_X + SC_2(V_X - V_{out}) + g_{m2}(V_X - V_{out})$$

$$\text{from } \textcircled{D}: V_X - V_{out} = \left(\frac{SC_3 + g_{m1}}{S(C_2 + C_3)} \right) V_X$$

$$\therefore I_X = \left[SC_1 + \frac{S^2C_2C_3 + g_{m1}SC_2 + g_{m2}SC_3 + g_{m1}g_{m2}}{S(C_2 + C_3)} \right] V_X$$

$$= \left[\frac{S^2(C_1C_2 + C_2C_3 + C_1C_3) + S(g_{m1}C_2 + g_{m2}C_3) + g_{m1}g_{m2}}{S(C_2 + C_3)} \right] V_X$$

$$Z_{in} = \frac{V_X}{I_X} = \frac{S(C_2 + C_3)}{S^2(C_1C_2 + C_2C_3 + C_1C_3) + S(g_{m1}C_2 + g_{m2}C_3) + g_{m1}g_{m2}} \quad \star$$



$$C_1 = C_{gs1} + C_{db2}$$

$$C_2 = C_{gd1} + C_{gd2}$$

$$C_3 = C_{db1} + C_{gs2}$$

$$\text{KCL @ } V_{out} : S C_2 (V_X - V_{out}) = g_{m1} V_X + V_{out} \left(\frac{1}{r_{o1}} + S C_3 \right)$$

$$\frac{V_{out}}{V_X} = \frac{S C_2 - g_{m1}}{S(C_2 + C_3) + \frac{1}{r_{o1}}}$$

$$\text{KCL @ } V_X : \frac{V_{in} - V_X}{R_S} = -g_{m2} V_{out} + V_X \left(\frac{1}{r_{o2}} + S C_1 \right) + S C_2 (V_X - V_{out})$$

$$\begin{aligned} \frac{V_{in}}{R_S} &= \left(S C_1 + S C_2 + \frac{1}{r_{o2}} + \frac{1}{R_S} \right) V_X - \frac{(-g_{m2} + S C_2)(S C_2 - g_{m1})}{S(C_2 + C_3) + \frac{1}{r_{o1}}} V_X \\ &= \frac{S^2(C_1 C_2 + C_1 C_3 + C_2 C_3) + S \left[\left(\frac{1}{r_{o2}} + \frac{1}{R_S} \right) (C_2 + C_3) + \frac{1}{r_{o1}} (C_1 + C_2) + g_{m1} C_2 + g_{m2} C_2 \right] - g_{m1} g_{m2} + \frac{1}{r_{o1}} \left(\frac{1}{r_{o2}} + \frac{1}{R_S} \right)}{S(C_2 + C_3) + \frac{1}{r_{o1}}} V_X \end{aligned}$$

$$\therefore \frac{V_{out}}{V_{in}} = \frac{-\frac{1}{R_S} (S C_2 - g_{m1})}{S^2(C_1 C_2 + C_1 C_3 + C_2 C_3) + S \left[\left(\frac{1}{r_{o2}} + \frac{1}{R_S} \right) (C_2 + C_3) + \frac{1}{r_{o1}} (C_1 + C_2) + g_{m1} C_2 + g_{m2} C_2 \right] - g_{m1} g_{m2} + \frac{1}{r_{o1}} \left(\frac{1}{r_{o2}} + \frac{1}{R_S} \right)}$$

For Z_{in}

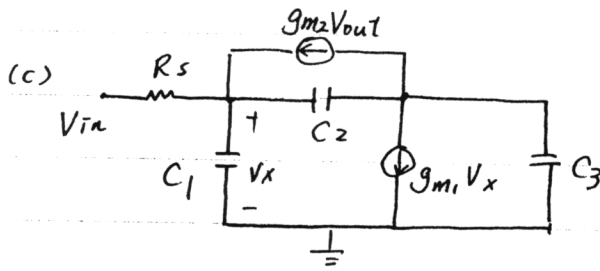
$$I_X = -g_{m2} V_{out} + V_X \left(\frac{1}{r_{o2}} + S C_1 \right) + S C_2 (V_X - V_{out})$$

$$= \left[\frac{S^2(C_1 C_2 + C_1 C_3 + C_2 C_3) + S \left[\frac{1}{r_{o2}} (C_2 + C_3) + \frac{1}{r_{o1}} (C_1 + C_2) + g_{m1} C_2 + g_{m2} C_2 \right] + (-g_{m1} g_{m2} + \frac{1}{r_{o1}} \frac{1}{r_{o2}})}{S(C_2 + C_3) + \frac{1}{r_{o1}}} \right] V_X$$

$$Z_{in} = \frac{V_X}{I_X} = \frac{S(C_2 + C_3) + \frac{1}{r_{o1}}}{S^2(C_1 C_2 + C_1 C_3 + C_2 C_3) + S \left[\frac{1}{r_{o2}} (C_2 + C_3) + \frac{1}{r_{o1}} (C_1 + C_2) + g_{m1} C_2 - g_{m2} C_2 \right] + (-g_{m1} g_{m2} + \frac{1}{r_{o1}} \frac{1}{r_{o2}})}$$

6.7

P87



$$C_1 = C_{gs1} + C_{db2} + C_{gd2}$$

$$C_2 = C_{gd1}$$

$$C_3 = C_{db1} + C_{sb2} + C_{gs2}$$

$$\text{KCL @ } V_{out} : S C_2 (V_x - V_{out}) = g_{m1} V_x + S C_3 V_{out} + g_{m2} V_{out}$$

$$\Rightarrow \frac{V_{out}}{V_x} = \frac{S C_2 - g_{m1}}{S (C_2 + C_3) + g_{m2}}$$

$$\text{KCL @ } V_x : \frac{V_{in} - V_x}{R_s} + g_{m2} V_{out} = S C_1 V_x + S C_2 (V_x - V_{out})$$

$$\frac{V_{in}}{R_s} = \left(\frac{1}{R_s} + S C_1 + S C_2 \right) V_x - (g_{m2} + S C_2) V_{out} = \left(\frac{1}{R_s} + S C_1 + S C_2 \right) V_x - \frac{(g_{m2} + S C_2)(S C_2 - g_{m1})}{S (C_2 + C_3) + g_{m2}}$$

$$\frac{V_{in}}{V} = \frac{S^2 (C_1 C_2 + C_2 C_3 + C_1 C_3) + S \left[\frac{1}{R_s} (C_2 + C_3) + g_{m2} C_1 + g_{m1} C_2 \right] + \left[\frac{g_{m2}}{R_s} + g_{m1} g_{m2} \right]}{S (C_2 + C_3) + g_{m2}}$$

$$\therefore \frac{V_{out}}{V_{in}} = \frac{V_{out}}{V_x} \cdot \frac{V_x}{V_{in}}$$

$$= \frac{\frac{1}{R_s} [S C_2 - g_{m1}]}{S^2 (C_1 C_2 + C_2 C_3 + C_1 C_3) + S \left[\frac{1}{R_s} (C_2 + C_3) + g_{m2} C_1 + g_{m1} C_2 \right] + \left(\frac{g_{m2}}{R_s} + g_{m1} g_{m2} \right)}$$

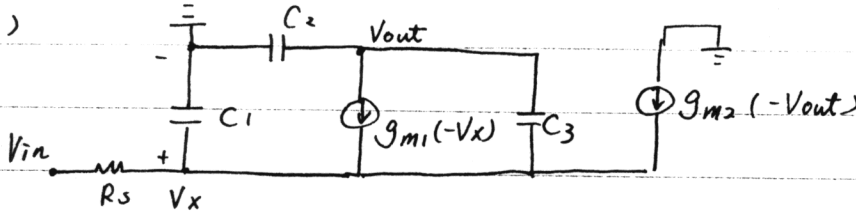
For Z_{in}

$$I_x = S C_1 V_x - g_{m2} V_{out} + S C_2 (V_x - V_{out})$$

$$= \left[\frac{S^2 (C_1 C_2 + C_2 C_3 + C_1 C_3) + S (g_{m2} C_1 + g_{m1} C_2) + g_{m1} g_{m2}}{S (C_2 + C_3) + g_{m2}} \right] V_x$$

$$Z_{in} = \frac{S (C_2 + C_3) + g_{m2}}{S^2 (C_1 C_2 + C_2 C_3 + C_1 C_3) + S (g_{m2} C_1 + g_{m1} C_2) + g_{m1} g_{m2}}$$

(d)



$$C_1 = C_{gs1} + C_{sb1} + C_{DB2}$$

$$C_2 = C_{gd1} + C_{gs2} + C_{db1}$$

$$C_3 = C_{gd2}$$

$$\text{KCL @ } V_{out} : -sC_2 V_{out} = -g_{m1} V_x + sC_3 (V_{out} - V_x)$$

$$\frac{V_{out}}{V_x} = \frac{sC_3 + g_{m1}}{s(C_2 + C_3)}$$

$$\text{KCL @ } V_x : \frac{V_{in} - V_x}{R_s} = sC_1 V_x + g_{m1} V_x + sC_3 (V_x - V_{out}) + g_{m2} V_{out}$$

$$\begin{aligned} \frac{V_{in}}{R_s} &= \left[\frac{1}{R_s} + s(C_1 + C_3) + g_{m1} \right] V_x + \frac{(sC_3 + g_{m1})(g_{m2} - sC_3)}{s(C_2 + C_3)} V_x \\ &= V_x \left[\frac{s^2(C_1 C_2 + C_2 C_3 + C_1 C_3) + s \left[\frac{C_2}{R_s} + \frac{C_3}{R_s} + g_{m1} C_2 + g_{m2} C_3 \right] + g_{m1} g_{m2}}{s(C_2 + C_3)} \right] \end{aligned}$$

$$\therefore \frac{V_{out}}{V_{in}} = \frac{sC_3 + g_{m1}}{s^2 R_s (C_1 C_2 + C_2 C_3 + C_1 C_3) + s[C_2 + C_3 + R_s(g_{m1} C_2 + g_{m2} C_3)] + g_{m1} g_{m2} R_s}$$

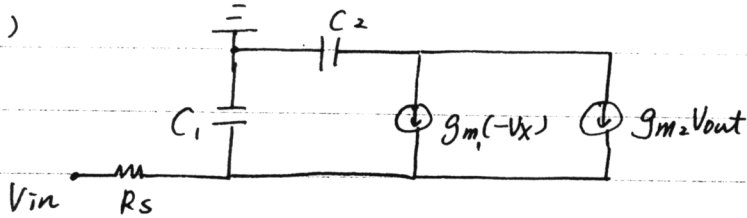
For Z_{in}

$$I_x = sC_1 V_x + g_{m1} V_x + sC_3 (V_x - V_{out}) - g_{m2} V_{out}$$

$$= \left[\frac{s^2(C_1 C_2 + C_2 C_3 + C_1 C_3) + s(g_{m1} C_2 + g_{m2} C_3) + g_{m1} g_{m2}}{s(C_2 + C_3)} \right] V_x$$

$$\therefore Z_{in} = \frac{s(C_2 + C_3)}{s^2(C_1 C_2 + C_2 C_3 + C_1 C_3) + s(g_{m1} C_2 + g_{m2} C_3) + g_{m1} g_{m2}}$$

(e)



$$C_1 = C_{gs1} + C_{SB1} + C_{dB2} + C_{gd2}$$

$$C_2 = C_{gd1} + C_{SB2} + C_{gs2} + C_{dB1}$$

$$\text{KCL @ } V_{out} \Rightarrow -sC_2 V_{out} = -g_{m1} V_x + g_{m2} V_{out}$$

$$\Rightarrow \frac{V_{out}}{V_x} = \frac{g_{m1}}{sC_2 + g_{m2}}$$

$$\text{KCL @ } V_x \Rightarrow \frac{V_{in} - V_x}{R_s} = sC_1 V_x + g_{m1} V_x - g_{m2} V_{out}$$

$$\Rightarrow \frac{V_{in}}{R_s} = \left[\frac{1}{R_s} + sC_1 + g_{m1} \right] V_x - \frac{g_{m1} g_{m2}}{(sC_2 + g_{m2})} V_x$$

$$= \frac{s^2 C_1 C_2 + s \left[\left(\frac{1}{R_s} + g_{m1} \right) C_2 + g_{m2} C_1 \right] + \frac{g_{m2}}{R_s}}{sC_2 + g_{m2}}$$

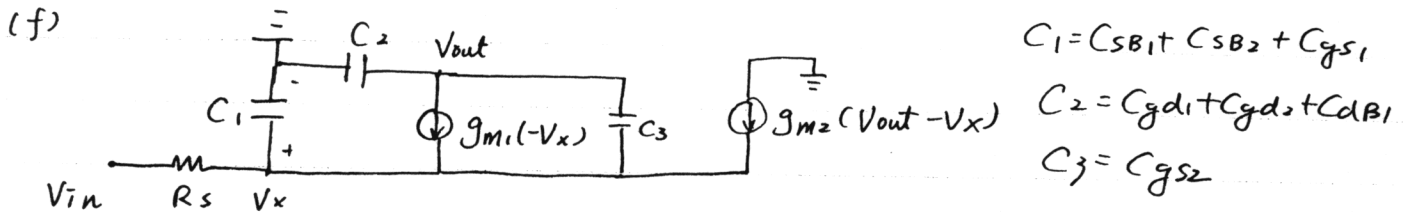
$$\therefore \frac{V_{out}}{V_{in}} = \frac{g_{m1}}{s^2 R_s C_1 C_2 + s \left[(1 + g_{m1} R_s) C_2 + g_{m2} R_s C_1 \right] + g_{m2}}$$

For Z_{in}

$$I_x = sC_1 V_x + g_{m1} V_x - g_{m2} V_{out}$$

$$= \left[\frac{s^2 C_1 C_2 + s [g_{m1} C_2 + g_{m2} C_1]}{sC_2 + g_{m2}} \right]$$

$$\therefore Z_{in} = \frac{sC_2 + g_{m2}}{s^2 C_1 C_2 + s (g_{m1} C_2 + g_{m2} C_1)}$$



$$\text{KCL @ } V_{out} : sC_2(-V_{out}) = g_{m1}(-V_x) + sC_3(V_{out} - V_x)$$

$$\Rightarrow \frac{V_{out}}{V_x} = \frac{g_{m1} + sC_3}{s(C_2 + C_3)}$$

$$\text{KCL @ } V_x : \frac{V_{in} - V_x}{R_s} + g_{m1}(-V_x) + g_{m2}(V_{out} - V_x) = sC_1 V_x + sC_3(V_x - V_{out})$$

$$\frac{V_{in}}{R_s} = V_x \left(\frac{1}{R_s} + g_{m1} + g_{m2} + sC_1 + sC_3 \right) - \frac{(g_{m2} + sC_3)(g_{m1} + sC_3)}{s(C_2 + C_3)} \cdot V_x$$

$$= \frac{s^2(C_1 C_2 + C_2 C_3 + C_1 C_3) + s \left[\frac{C_2}{R_s} + \frac{C_3}{R_s} + g_{m1} C_2 + g_{m2} C_2 \right] - g_{m1} g_{m2}}{s(C_2 + C_3)}$$

$$\frac{V_{out}}{V_{in}} = \frac{g_{m1} + sC_3}{s^2 R_s (C_1 C_2 + C_2 C_3 + C_1 C_3) + s [C_2 + C_3 + R_s (g_{m1} C_2 + g_{m2} C_2)] - g_{m1} g_{m2} R_s}$$

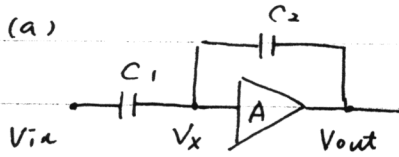
For Z_{in}

$$I_x = g_{m1} V_x + g_{m2}(V_x - V_{out}) + sC_1 V_x + sC_3(V_x - V_{out})$$

$$= \left[\frac{s^2(C_1 C_2 + C_2 C_3 + C_1 C_3) + s [g_{m1} C_2 + g_{m2} C_2] - g_{m1} g_{m2}}{s(C_2 + C_3)} \right] V_x$$

$$Z_{in} = \frac{V_x}{I_x} = \frac{s(C_2 + C_3)}{s^2(C_1 C_2 + C_2 C_3 + C_1 C_3) + s(g_{m1} C_2 + g_{m2} C_2) - g_{m1} g_{m2}}$$

6.4 (a)



$$A = -\infty$$

(i) At low frequency, V_x is like virtual ground

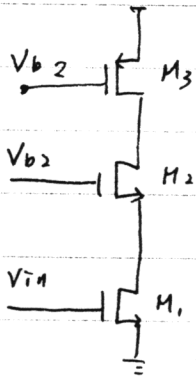
$$sC_1 V_{in} = -sC_2 V_{out}$$

$$\frac{V_{out}}{V_{in}} = -\frac{C_1}{C_2}$$

(ii) At high frequency, C_1, C_2 is like a short circuit

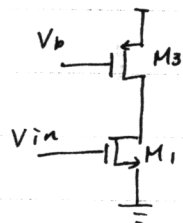
$$\frac{V_{out}}{V_{in}} = 1$$

(b) At low frequency, the equivalent circuit is shown as



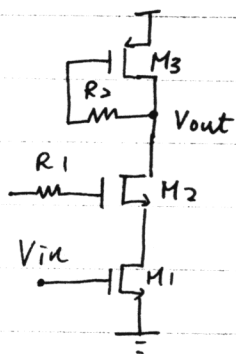
$$A_v \approx -g_{m1} r_{o3} \rightarrow \infty, \text{ if } \lambda = 0$$

(ii) At high frequency, the equivalent circuit

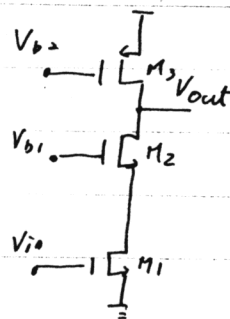


$$A_v = -g_{m1}(r_{o1} // r_{o3}) \rightarrow \infty \text{ if } \lambda = 0$$

(c) (i) At low frequency, the equivalent circuit



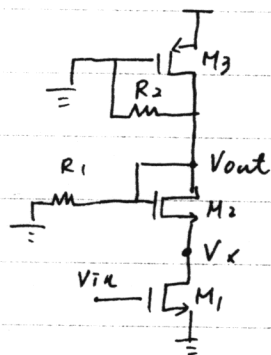
R_1, R_2 can be ignored
 $\Rightarrow$



The impedance @ $V_{out} = \frac{1}{g_{m3}}$

$$A_v \cong -g_{m1} \cdot \frac{1}{g_{m3}} = -\frac{g_{m1}}{g_{m3}}$$

(ii) At high frequency,



$$\frac{V_x}{V_{in}} = -g_{m1} \cdot \frac{1}{g_{m2}}$$

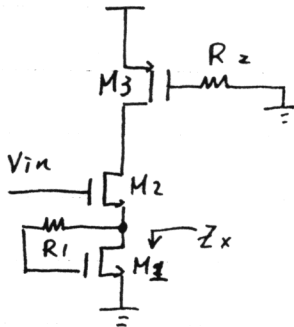
$\uparrow$ the impedance looking into V_x

The impedance @ $V_{out} = R_1 // R_2$

$$\therefore A_v = \left(-g_{m1} \cdot \frac{1}{g_{m2}} \right) \cdot g_{m2} \cdot (R_1 // R_2) = -g_{m1}(R_1 // R_2)$$

✱

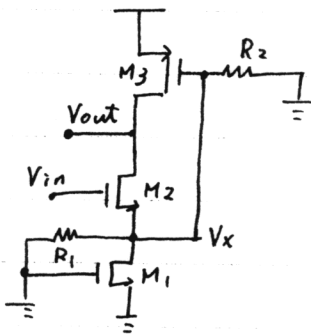
(d) (i) At low frequency, the equivalent circuit is



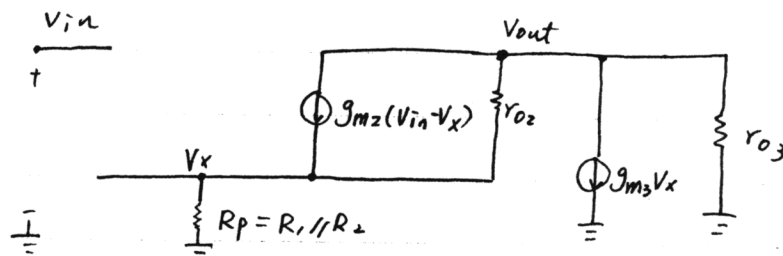
$$\frac{V_{out}}{V_{in}} = \frac{g_{m2}(r_{o3} \parallel (1 + g_{m2}r_{o2})Z_x)}{1 + g_{m2}Z_x} \approx \frac{g_{m2}(r_{o3} \parallel r_{o2})}{1 + \frac{g_{m2}}{g_{m1}}} \rightarrow \infty \text{ if } \lambda = 0$$

$$Z_x = \frac{1}{g_m}$$

(ii) At high frequency



Small-signal model



$$\text{KCL @ } V_x, V_{out} : \frac{V_x}{R_p} = g_{m2}(V_{in} - V_x) + \frac{V_{out} - V_x}{r_{o2}} = -\left(g_{m3}V_x + \frac{V_{out}}{r_{o3}}\right)$$

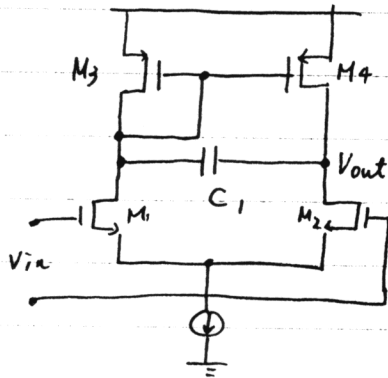
$$\frac{V_x}{R_p} = -\left(g_{m3}V_x + \frac{V_{out}}{r_{o3}}\right) \Rightarrow \frac{V_{out}}{V_x} = -r_{o3}\left(g_{m3} + \frac{1}{R_p}\right)$$

$$g_{m2}(V_{in} - V_x) + \frac{V_{out} - V_x}{r_{o2}} = \frac{V_x}{R_p} \Rightarrow g_{m2}V_{in} = \left(\frac{1}{R_p} + \frac{1}{r_{o2}} + g_{m2}\right)V_x + \frac{V_{out}}{r_{o2}}$$

$$\Rightarrow g_{m2}V_{in} = \left[-\left(\frac{1}{R_p} + \frac{1}{r_{o2}} + g_{m2}\right)\frac{1}{r_{o3}(g_{m3} + \frac{1}{R_p})} + \frac{1}{r_{o2}}\right]V_{out}$$

$$\Rightarrow \frac{V_{out}}{V_{in}} = \frac{-g_{m2}r_{o3}(g_{m3} + \frac{1}{R_p})}{\left(\frac{1}{R_p} + \frac{1}{r_{o2}} + g_{m2}\right) - \frac{r_{o3}(g_{m3} + \frac{1}{R_p})}{r_{o2}}} \rightarrow \infty \text{ if } \lambda = 0$$

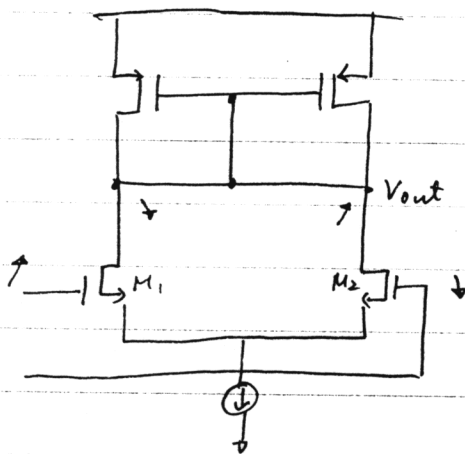
6.5(a) (i) At low frequency



C_1 is like an open circuit @ very low frequency

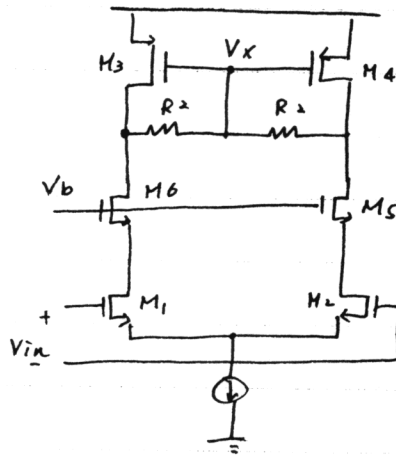
$$\Rightarrow \frac{V_{out}}{V_{in}} = -g_{m1}(r_{o2} \parallel r_{o4}) \rightarrow \infty \text{ if } \lambda = 0$$

(ii) At very high frequency, C_1 is like a short circuit

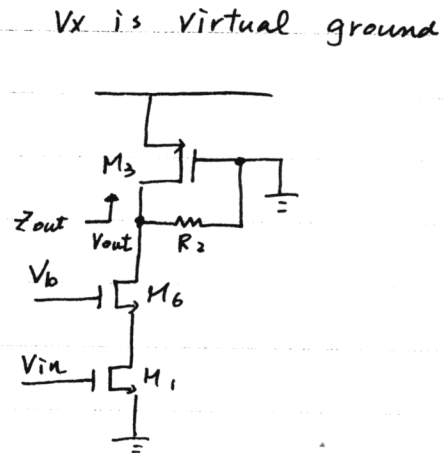


$$\text{Gain} = 0$$

(b) (i) At low frequency, the equivalent circuit is



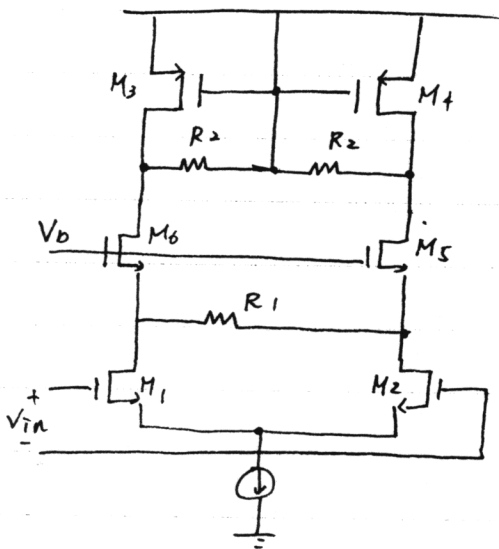
half circuit



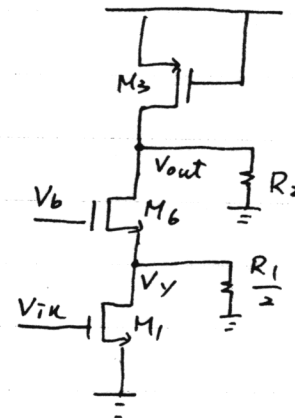
$$Z_{out} \cong r_{o3} \parallel R_2 \cong R_2$$

$$A_v = -g_{m1} \cdot (R_2 \parallel r_{o3}) \cong -g_{m1} R_2$$

(ii) At high frequency



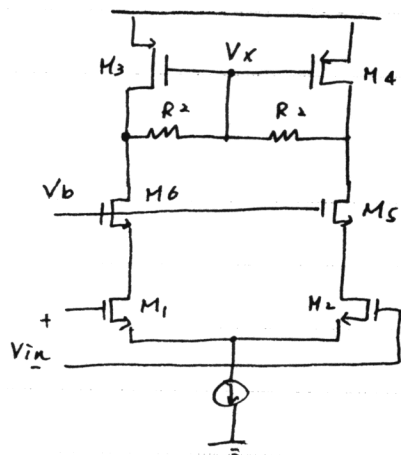
half circuit



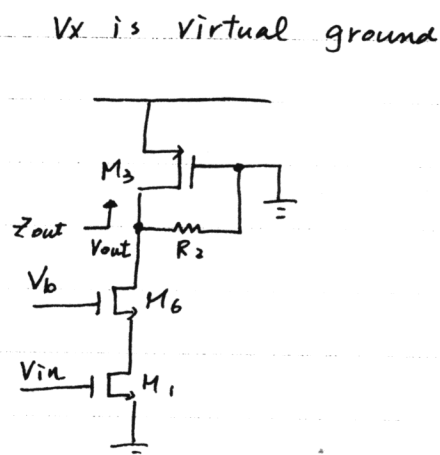
$$\frac{V_y}{V_{in}} = -g_{m1} \left(\frac{1}{g_{m6}} \parallel \frac{R_1}{2} \right), \quad \frac{V_{out}}{V_y} \cong +g_{m6} \cdot R_2$$

$$\frac{V_{out}}{V_{in}} = - \frac{g_{m1} g_{m6} R_1 R_2}{(2 + g_{m6} \cdot R_1)}$$

(b) (i) At low frequency, the equivalent circuit is



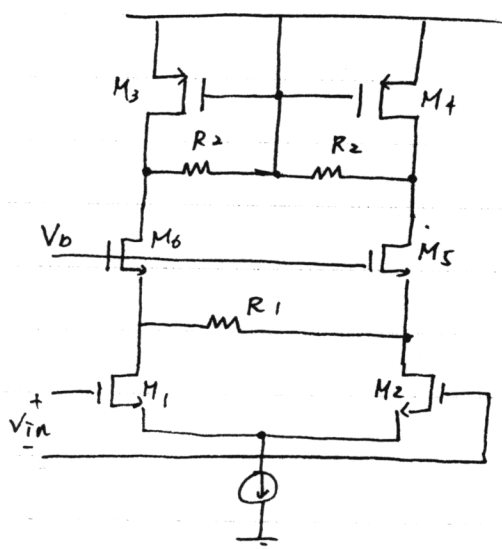
half circuit



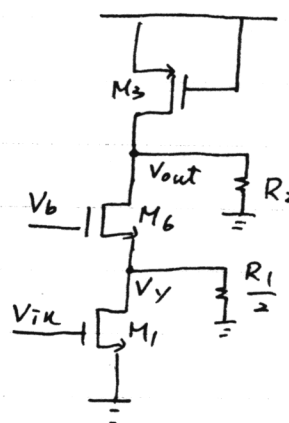
$$Z_{out} \cong r_{o3} \parallel R_2 \cong R_2$$

$$A_v = -g_{m1} \cdot (R_2 \parallel r_{o3}) \cong -g_{m1} R_2$$

(ii) At high frequency



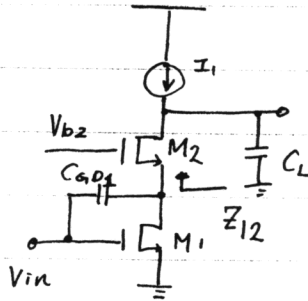
half circuit



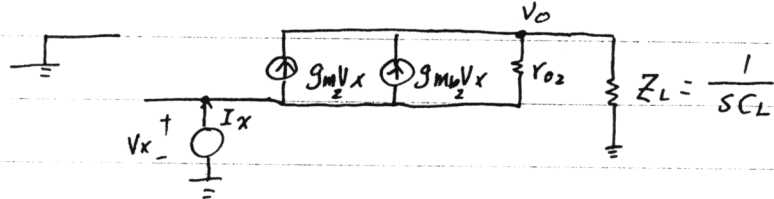
$$\frac{V_y}{V_{in}} = -g_{m1} \left(\frac{1}{g_{m6}} \parallel \frac{R_1}{2} \right), \quad \frac{V_{out}}{V_y} \cong +g_{m6} \cdot R_2$$

$$\frac{V_{out}}{V_{in}} = - \frac{g_{m1} g_{m6} R_1 R_2}{(2 + g_{m6} R_1)}$$

6.6



The impedance Z_{12} can be derived from the following small signal model



$$\text{KCL @ } V_0: \frac{V_0}{Z_L} + \frac{V_0 - V_x}{r_{o2}} = (g_{m2} + g_{mb2})V_x \Rightarrow \left(\frac{1}{Z_L} + \frac{1}{r_{o2}}\right)V_0 = \left(g_{m2} + g_{mb2} + \frac{1}{r_{o2}}\right)V_x$$

$$\Rightarrow V_0 = \left(\frac{g_{m2} + g_{mb2} + \frac{1}{r_{o2}}}{1 + \frac{Z_L}{r_{o2}}}\right)V_x$$

$$\Rightarrow I_x = \frac{V_0}{Z_L} = \left[\frac{g_{m2} + g_{mb2} + \frac{1}{r_{o2}}}{1 + \frac{Z_L}{r_{o2}}}\right]V_x \Rightarrow \frac{V_x}{I_x} = Z_{12} = \frac{1 + \frac{Z_L}{r_{o2}}}{g_{m2} + g_{mb2} + \frac{1}{r_{o2}}}$$

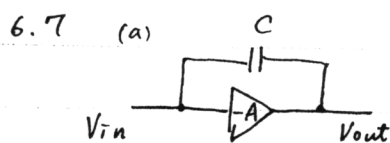
$$\Rightarrow Z_{12} = \frac{r_{o2} + Z_L}{1 + (g_{m2} + g_{mb2})r_{o2}}$$

The miller multiplication for $C_{GD1} = 1 + g_{m1}Z_{12}$

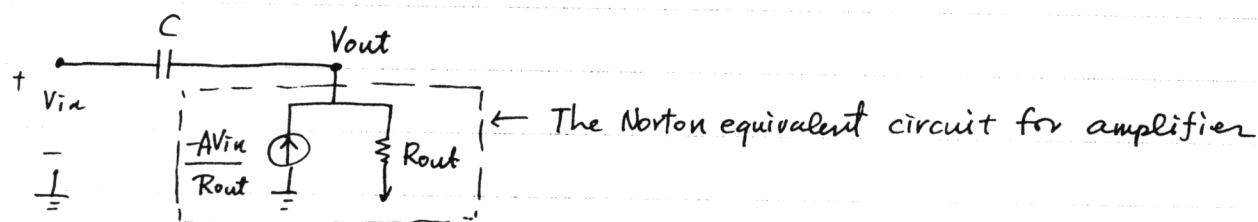
$$= 1 + \frac{g_{m1}(r_{o2} + Z_L)}{1 + (g_{m2} + g_{mb2})r_{o2}} \quad \text{--- (1)}$$

If C_L is relatively large $\Rightarrow \left|\frac{1}{sC_L}\right| \ll r_{o2}$

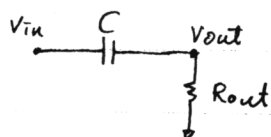
$$\text{eg 0 can be approximated as } \approx 1 + \frac{g_{m1}r_{o2}}{1 + (g_{m2} + g_{mb2})r_{o2}} \approx 1 + \frac{g_{m1}}{g_{m2} + g_{mb2}}$$



Assume the amplifier output resistance R_{out}
 The small signal model is as follows



As we can see, the above circuit forms a high pass network



Thus, when there is a step ΔV at the input, output will follow input, a step ΔV , first. Then, it will settle down to $-AV_{in}$ as the steady state

(b) KCL @ V_{out} :

$$-\frac{AV_{in}}{R_{out}} = \frac{V_{out}}{R_{out}} + sC(V_{out} - V_{in})$$

$$\Rightarrow \left(sC - \frac{A}{R_{out}}\right)V_{in} = \left(\frac{1}{R_{out}} + sC\right)V_{out} \Rightarrow \frac{V_{out}}{V_{in}} = \frac{sCR_{out} - A}{1 + sCR_{out}} \quad *$$

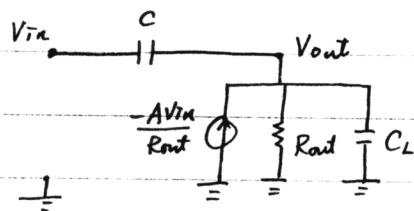
for the step response, $x(t) = u(t)$, $t \geq 0 \rightarrow X(s) = \frac{1}{s}$

$$Y(s) = \frac{1}{s} \cdot \frac{V_{out}}{V_{in}}(s) = \frac{sCR_{out} - A}{s(1 + sCR_{out})} = \frac{-A}{s} + \frac{(A+1) \cdot R_{out}C}{1 + sCR_{out}}$$

$$\Rightarrow y(t) = -Au(t) + (A+1)e^{-\frac{t}{R_{out}C}}, t \geq 0$$

For a ΔV input step, output = $-A \cdot \Delta V + (A+1) \cdot \Delta V \cdot e^{-\frac{t}{R_{out}C}}$ *

6.8 (a) Small-signal circuit model



When input has ΔV jump, V_{out} will follow
and the output jump $= \left(\frac{C}{C_L + C} \right) \Delta V$ *

(b) The transfer function $H(s)$

$$H(s) = \frac{V_{out}(s)}{V_{in}(s)} \quad \text{KCL @ } V_{out}$$

$$\Rightarrow -\frac{A V_{in}}{R_{out}} = \frac{V_{out}}{R_{out}} + sC(V_{out} - V_{in}) + sC_L V_{out}$$

$$\Rightarrow V_{in} \left(sC - \frac{A}{R_{out}} \right) = V_{out} \left(\frac{1}{R_{out}} + sC + sC_L \right)$$

$$\Rightarrow \frac{V_{out}}{V_{in}} = \frac{sC R_{out} - A}{1 + sR_{out}(C + C_L)} \quad *$$

step response

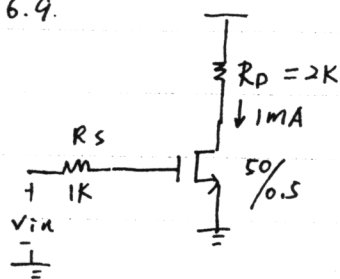
$$Y(s) = \frac{1}{s} \cdot \frac{sC R_{out} - A}{1 + sR_{out}(C + C_L)} = \frac{-A}{s} + \frac{[(A+1)C + AC_L] R_{out}}{1 + sR_{out}(C + C_L)} = \frac{-A}{s} + \frac{\frac{(A+1)C + AC_L}{C + C_L}}{s + \frac{1}{R_{out}(C + C_L)}}$$

$$y(t) = -A u(t) + \frac{(A+1)C + AC_L}{C + C_L} e^{-\frac{t}{R_{out}(C + C_L)}} u(t)$$

For a step ΔV @ the input

$$\text{output} = -A \Delta V + \left[\frac{(A+1)C + AC_L}{C + C_L} \right] \cdot \Delta V \cdot e^{-\frac{t}{R_{out}(C + C_L)}} \quad *$$

6.9.



$$\lambda = 0.1$$

$$C_{ox} = \frac{\epsilon_{SiO_2}}{t_{ox}} = \frac{3.9 \times 8.85 \times 10^{-14}}{9 \times 10^{-7}} = 3.835 \times 10^{-7}$$

$$\mu_n = 350$$

$$I_D = 10^{-3} = \frac{1}{2} \times 350 \times 3.835 \times 10^{-7} \times \left(\frac{50}{0.5 - 2 \times 0.08} \right) (V_{gs} - V_T)^2 (1 + 0.1 \times V_{ds})$$

$$= 67.113 \times 10^{-6} \times \frac{50}{0.34} \times 1.1 \times (V_{in} - 0.7)^2$$

$$\Rightarrow V_{in} = 1.0035$$

$$g_m = \frac{2I_D}{(V_{gs} - V_T)} = 6.59 \times 10^{-3}$$

$$C_{gs} = \frac{2}{3} C_{ox} W L + C_{ov} \cdot W$$

$$= \frac{2}{3} \times 3.835 \times 10^{-7} \times 50 \times (0.5 - 0.08 \times 2) \times 10^{-8} + 3.835 \times 10^{-7} \times 0.08 \times 10^{-4} \times 50 \times 10^{-4}$$

$$= 53.7 \times 10^{-15}$$

$$C_{gd} = C_{gd0} \cdot W = 0.4 \times 10^{-11} \times 50 \times 10^{-6} = 2 \times 10^{-16}$$

$$C_{db} = \frac{0.56 \times 10^{-3} \times 75 \times 10^{-12}}{(1 + \frac{1}{0.9})^{0.6}} + \frac{0.35 \times 10^{-11} \times 103 \times 10^{-6}}{(1 + \frac{1}{0.9})^{0.2}} = 2.714 \times 10^{-14}$$

According to eq (20)

$$\text{Zero} = \frac{g_m}{C_{gd}} = \frac{6.59 \times 10^{-3}}{2 \times 10^{-16}} = 3.3 \times 10^{13} \text{ rad/sec}$$

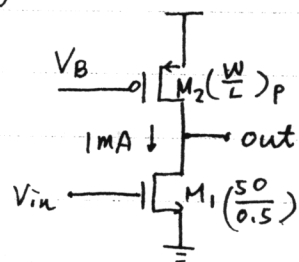
pde is the root of $R_S R_D (C_{gs} C_{gd} + C_{gs} C_{db} + C_{gd} C_{db}) s^2$
 $+ [R_S (1 + g_m R_D) C_{gd} + R_S C_{gs} + R_D (C_{gd} + C_{db})] s + 1$... from eq (6.20)

$$\Rightarrow 2.95 \times 10^{-21} s^2 + 1.112 \times 10^{-10} s + 1 = 0$$

$$\omega_{p1} = -14.82 \times 10^9 \text{ rad/sec}$$

$$\omega_{p2} = -22.88 \times 10^9 \text{ rad/sec}$$

6.10



(a) The maximum output level = 2.6 V

→ V_B can be as low as $2.6 - |V_{THP}| = 2.6 - 0.8 = 1.8V$

Let's choose output DC bias @ 1.5V, such that

 M_1, M_2 are both in saturation region

$$\text{Thus, } I_{D1} = 10^{-3} = \frac{1}{2} \times 350 \times 3.835 \times 10^{-7} \times \left(\frac{50}{0.5 - 2 \times 0.08} \right) (V_{in} - 0.7)^2 (1 + 0.1 \times 1.5)$$

$$\Rightarrow V_{in} = 0.997 \cong 1V$$

$$\text{Also, } I_{D2} = 10^{-3} = \frac{1}{2} \times 100 \times 3.835 \times 10^{-7} \times \left(\frac{W_P}{0.5 - 2 \times 0.09} \right) (3 - 1.8 - 0.8)^2 (1 + 0.2 \times 1.5)$$

$$W_P \cong 80.5 \mu m = 81 \mu m$$

Therefore, we can choose $\left(\frac{W}{L} \right)_P = \left(\frac{81 \mu m}{0.5 \mu m} \right)$ with gate bias 1.8Vso that M_1, M_2 are both in saturation region and $V_{out} \cong 1.5V$

$$V_{out, low} = V_{in} - |V_{THN}| = 0.3V$$

Thus, the maximum output peak-to-peak swing = $2.6 - 0.3 = 1.3V$ *

(b) This problem is similar to problem 6.9 except

$$R_D \rightarrow (r_{o1} \parallel r_{o2})$$

$$C_{DB} = C_{DB1} + C_{DB2} + C_{gd2}$$

$$\therefore g_{m1} = \frac{2I_D}{V_{GS} - V_{t1}} = 2 \times 10^{-3} / 0.297 = 6.73 \times 10^{-3}$$

$$r_{op} = \frac{1}{\left(\frac{\lambda_P I_D}{1 + \lambda_P V_{DS}} \right)} \cong 6.5K$$

$$r_{oN} = \frac{1}{\left(\frac{\lambda_N I_D}{1 + \lambda_N V_{DS}} \right)} = 11.5K$$

$$\therefore R_D = r_{op} \parallel r_{oN} = 4.1K$$

$$R_S = 1K$$

$$C_{gs1} = \frac{2}{3} C_{ox} W_1 L_1 + C_{ox} W_1 \Delta L = 58.8 \times 10^{-15} F$$

$$C_{gd1} = 2 \times 10^{-16}$$

$$C_{db1} = \frac{0.56 \times 10^{-3} \times 75 \times 10^{-12}}{\left(1 + \frac{1.5}{0.9}\right)^{0.6}} + \frac{0.35 \times 10^{-11} \times 103 \times 10^{-6}}{\left(1 + \frac{1.5}{0.9}\right)^{0.2}} = 23.38 \times 10^{-15} \text{ F}$$

$$C_{db2} = \frac{0.94 \times 10^{-3} \times 121.5 \times 10^{-12}}{\left(1 + \frac{1.5}{0.9}\right)^{0.5}} + \frac{0.32 \times 10^{-11} \times 165 \times 10^{-6}}{\left(1 + \frac{1.5}{0.9}\right)^{0.3}} = 70.33 \times 10^{-15} \text{ F}$$

$$C_{gd2} = 81 \times 0.3 \times 10^{-11} \times 10^{-6} = 0.243 \times 10^{-15} \text{ F}$$

$$\omega_3 = -\frac{g_{m1}}{C_{gd1}} = -\frac{6.59 \times 10^{-3}}{2 \times 10^{-16}} = -3.3 \times 10^{13} \text{ rad/sec}$$

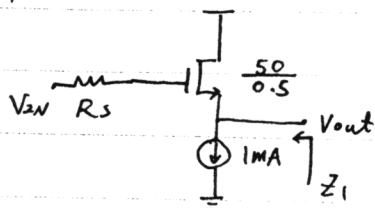
ω_{p1}, ω_{p2} is the root of the equation

$$R_s R_D (C_{gs1} C_{gd1} + C_{gs1} C_{db1} + C_{gd1} C_{db1}) + [R_s (1 + g_{m1} R_D) C_{gd1} + R_s C_{gs1} + R_D (C_{gd1} + C_{db1})] + 1$$

$$\Rightarrow \omega_{p1} = -2.2 \times 10^9 \text{ rad/sec}$$

$$\omega_{p2} = -17.36 \times 10^9 \text{ rad/sec}$$

6.11

Assume $\sigma = 0$

$$g_m = \frac{2I_D}{(V_{GS} - V_{th})}$$

$$= \frac{2 \times 10^{-3}}{0.3} = 6.67 \times 10^{-3}$$

From eq (6.49) $Z_i = \frac{R_S C_{gs} s + 1}{g_m + C_{gs} s}$

Since $\frac{1}{g_m} < R_S$

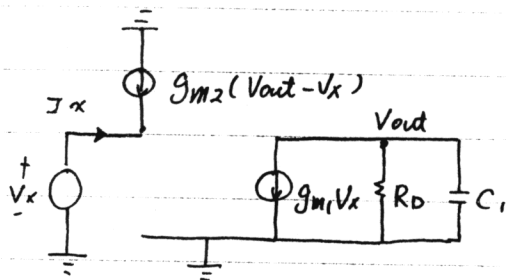
, thus Z_i is inductive and the equivalent inductance is

$$= \frac{C_{gs}}{g_m} \left(R_S - \frac{1}{g_m} \right)$$

$$C_{gs} = 58 \times 10^{-15} \text{ F}$$

$$\therefore L = 8.56 \times 10^{-8} \text{ H}$$

6.12 (a)



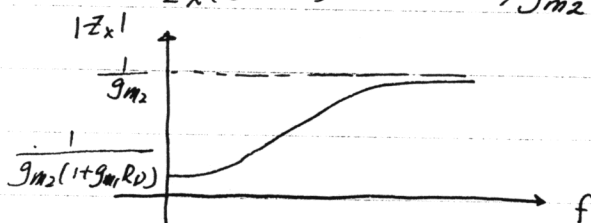
$$V_{out} = -g_{m1} V_x (R_D \parallel \frac{1}{sC_1})$$

$$I_x = -g_{m2}(V_{out} - V_x) = -g_{m2}V_{out} + g_{m2}V_x = [g_{m2}g_{m1}(R_D \parallel \frac{1}{sC_1}) + g_{m2}]V_x$$

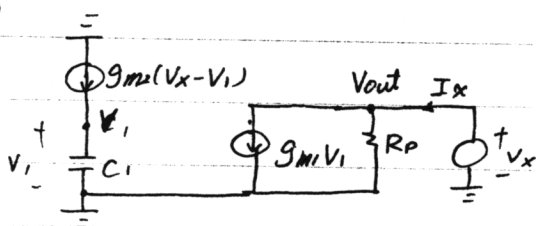
$$Z_x = \frac{V_x}{I_x} = \frac{1}{g_{m2}g_{m1} \frac{R_D \parallel \frac{1}{sC_1}}{R_D + \frac{1}{sC_1}} + g_{m2}} = \frac{1}{g_{m2} \left[\left(\frac{g_{m1}R_D}{1 + sR_DC_1} \right) + 1 \right]}$$

$$\text{Thus, } Z_x(s \rightarrow 0) = \frac{1}{g_{m2}(1 + g_{m1}R_D)}$$

$$Z_x(s \rightarrow \infty) = \frac{1}{g_{m2}}$$



(b)



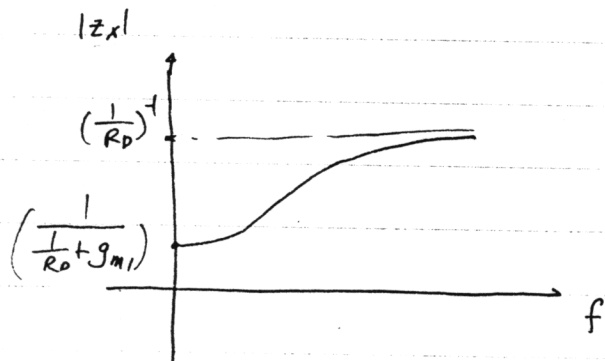
$$\text{KCL @ } V_1: g_{m2}(V_x - V_1) = sC_1 V_1$$

$$\Rightarrow V_1 = \left(\frac{g_{m2}}{sC_1 + g_{m2}} \right) V_x$$

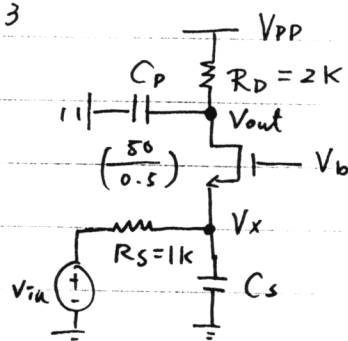
$$\text{KCL @ } V_{out}: I_x = \frac{V_x}{R_D} + g_{m1}V_1$$

$$= \frac{V_x}{R_D} + \frac{g_{m1}g_{m2}}{sC_1 + g_{m2}} V_x$$

$$\Rightarrow Z_x = \frac{1}{\frac{1}{R_D} + \frac{g_{m1}g_{m2}}{sC_1 + g_{m2}}}$$



6.13



from eq (6.53)

$$\frac{V_{out}}{V_{in}}(s) = \frac{(g_m + g_{mb})R_D}{1 + (g_m + g_{mb})R_S} \frac{1}{\left(1 + \frac{C_S}{g_m + g_{mb} + R_S^{-1}} \cdot s\right)(1 + R_D C_D s)}$$

Assume V_b is chosen appropriately such that $V_x \approx 0$ (no body effect)

$$g_m \sim 6.59 \times 10^{-3}$$

$$g_{mb} = \left[\frac{\sigma}{2\sqrt{2}\phi_f} \right] g_m = 1.563 \times 10^{-3}$$

$$\left. \begin{aligned} C_S &= C_{SB} + C_{gs} = 42.4 \times 10^{-15} + 58.8 \times 10^{-15} \\ C_D &= C_{DB} = 27.14 \times 10^{-15} \text{ F} \end{aligned} \right\} \text{from problem 9}$$

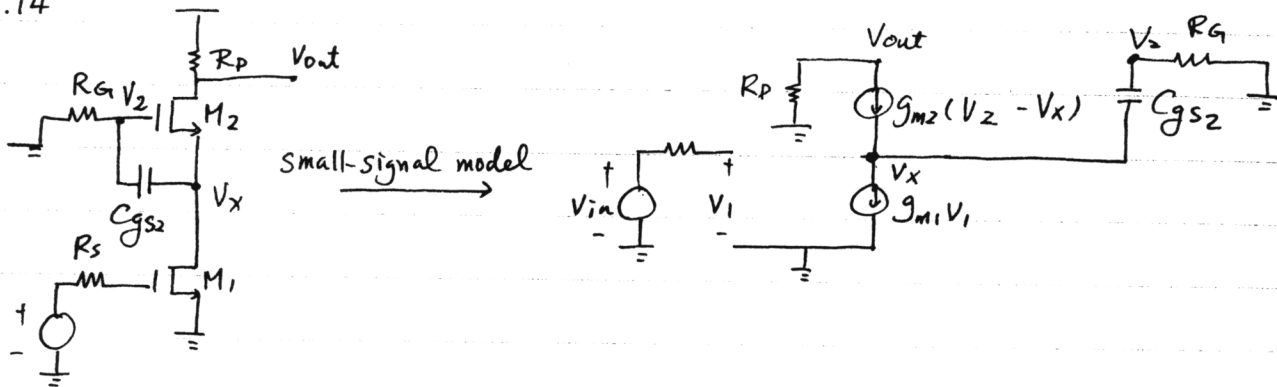
$$A_v(\text{low frequency}) = \frac{(g_m + g_{mb})R_D}{1 + (g_m + g_{mb})R_S} = 1.44$$

$$\omega_{p1} = - \frac{g_m + g_{mb} + R_S^{-1}}{C_S} = - \frac{6.59 \times 10^{-3} + 1.563 \times 10^{-3} + 10^{-3}}{42.4 \times 10^{-15} + 58.8 \times 10^{-15}} = -9.044 \times 10^{10} \text{ rad/s}$$

$$\omega_{p2} = - \frac{1}{R_D C_D} = - \frac{1}{2 \times 10^3 \times 27.14 \times 10^{-15}} = -1.84 \times 10^{10} \text{ rad/s}$$

Compared with the pole locations in problem 9, the poles for common-gate configuration are much larger because there is no Miller-effect for C_{gd} in this case

6.14



$$\text{KCL @ } V_2 : \frac{V_2}{R_g} = s C_{gs2} (V_x - V_2)$$

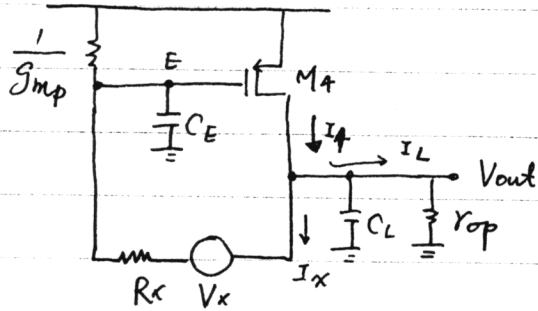
$$\Rightarrow \frac{V_2}{V_x} = \frac{s C_{gs2}}{\frac{1}{R_g} + s C_{gs2}} = \frac{s R_g C_{gs2}}{1 + s R_g C_{gs2}} \quad \text{--- ①}$$

$$\text{KCL @ } V_{out} : V_{out} = -g_{m2} (V_2 - V_x) R_D = \left[\frac{g_{m2} R_D}{1 + s R_g C_{gs2}} \right] V_x \quad \text{--- ②}$$

$$\begin{aligned} \text{KCL @ } V_x : \quad g_{m1} V_1 &= g_{m1} V_{in} = (g_{m2} + s C_{gs2}) (V_2 - V_x) \\ &= \frac{-(g_{m2} + s C_{gs2})}{1 + s R_g C_{gs2}} V_x \quad \text{--- ③} \end{aligned}$$

$$\text{from ②, ③, } \frac{V_{out}}{V_{in}} = \frac{-g_{m1} g_{m2} R_D}{g_{m2} + s C_{gs2}} \quad \#$$

6.15



For zero frequency, $I_L = 0$ & $I_4 = I_x$

$$I_4 = -g_{mp} V_E$$

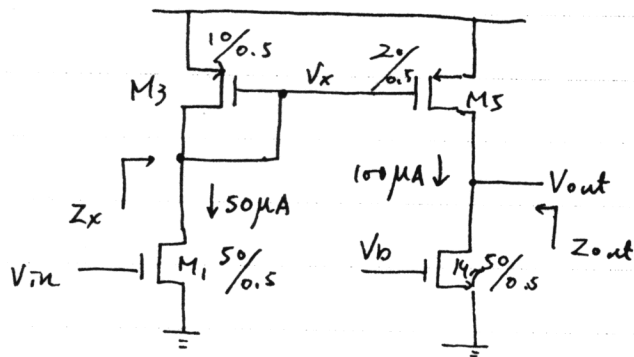
$$I_x = V_E (g_{mp} + sC_E)$$

$$\therefore I_4 = I_x \Rightarrow -g_{mp} = g_{mp} + sC_E$$

$$s_z = \frac{-2g_{mp}}{C_E}$$

✱

6.15 Half circuit can be drawn as follows



Since $R_s = 0$, According to (6.20) & (6.76)

$$\frac{V_{out}}{V_{in}}(s) = - \frac{(C_{gd1} \cdot s - g_{m1}) \cdot \frac{1}{g_{m3}}}{\frac{1}{g_{m3}} (C_{gd1} + C_X) s + 1} \cdot g_{m5} \cdot (r_{o5} \parallel r_{o7}) \cdot \frac{1}{1 + (r_{o5} \parallel r_{o7}) \cdot C_L \cdot s}$$

where $C_L = C_{db7} + C_{gd7} + C_{db5}$

$$C_X = C_{gs3} + C_{db1} + C_{gs5} + C_{db3} + C_{gd5} (1 + g_{m5} (r_{o5} \parallel r_{o7}))$$

$$Z_{out} = (r_{o5} \parallel r_{o7})$$

$$Z_X = \frac{1}{g_{m3}}$$

First of all, let's calculate V_X operating point

$$I_{d3} = 50 \times 10^{-6} = \frac{1}{2} \times 100 \times 3.835 \times 10^{-7} \times \frac{10}{0.5 - 0.09 \times 2} (3 - V_X - 0.8)^2 (1 + 0.2(3 - V_X))$$

$$V_X \approx 1.94V$$

For V_{in} operating point

$$I_{d1} = 50 \times 10^{-6} = \frac{1}{2} \times 250 \times 3.835 \times 10^{-7} \times \frac{50}{0.5 - 0.08 \times 2} (V_{gs1} - 0.7)^2 (1 + 0.1 \cdot 1.94)$$

$$V_{gs1} \approx 0.765V$$

$$\Rightarrow g_{m1} = \frac{2 I_{d1}}{(V_{gs1} - V_t)} \approx 1.54 \times 10^{-3}$$

$$g_{m3} = \frac{2 I_{d1}}{(3 - 1.94 - 0.8)} \approx 3.73 \times 10^{-4} \Rightarrow g_{m5} = 2 \cdot g_{m3} = 7.46 \times 10^{-4}$$

$$g_{ds5} = 2 \times 50 \times 10^{-6} \cdot \lambda / (1 + \lambda \cdot 1.06) = 10^{-4} \cdot 0.2 / 1.212 \approx 1.649 \times 10^{-5}$$

$$g_{ds7} = 10^{-4} \times 0.1 / (1 + 0.196) \approx 8.36 \times 10^{-6}$$

$$r_{os} // r_{o7} = 40290$$

$$C_L = C_{DB5} + C_{DB7} + C_{gd7} = \left[\frac{0.94 \times 10^{-3} \times 30 \times 10^{-12}}{\left(1 + \frac{1.06}{0.9}\right)^{0.5}} + \frac{0.32 \times 10^{-11} \times 43 \times 10^{-6}}{\left(1 + \frac{1.06}{0.9}\right)^{0.3}} \right] \\ + \left[\frac{0.56 \times 10^{-3} \times 75 \times 10^{-12}}{\left(1 + \frac{1.94}{0.9}\right)^{0.6}} + \frac{0.35 \times 10^{-11} \times 103 \times 10^{-6}}{\left(1 + \frac{1.94}{0.9}\right)^{0.2}} \right] + 50 \times 0.4 \times 10^{-17} \\ = 19.22 \times 10^{-15} + 21.36 \times 10^{-15} + 2 \times 10^{-16} = 40.78 \times 10^{-15}$$

$$C_{gs3} = \frac{2}{3} \times 3.835 \times 10^{-7} \times 10 \times 0.32 + 3.835 \times 10^{-7} \times 10 \times 0.09 = 11.633 \times 10^{-15}$$

$$C_{AB1} \approx C_{AB7} \approx 21.36 \times 10^{-15}$$

$$C_{gs5} = 2 \cdot C_{gs3} = 23.266 \times 10^{-15}$$

$$C_{AB3} = \frac{1}{2} \cdot C_{DB5} = 9.61 \times 10^{-15}$$

$$C_{gd5} = 6.3 \times 10^{-11} \times 20 \times 10^{-6} = 6 \times 10^{-17}$$

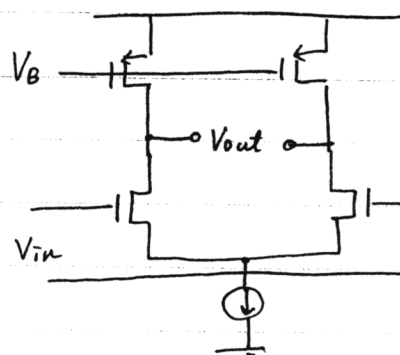
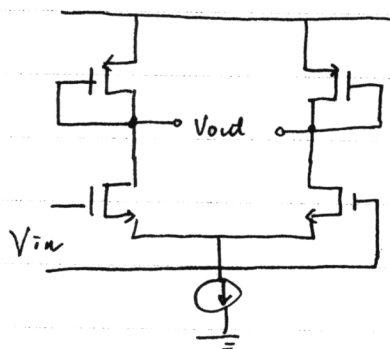
$$C_x = [11.633 + 21.36 + 23.27 + 9.61 + 0.06 (1 + g_{m5} \cdot (r_{os} // r_{o7}))] \times 10^{-15} = 67.732 \times 10^{-15}$$

$$\therefore \omega_z = \frac{g_{m1}}{C_{gd1}} = 7.7 \times 10^{12} \text{ rad/sec}$$

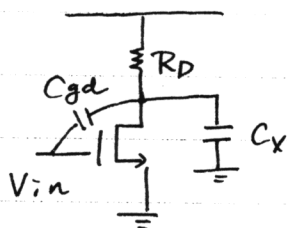
$$\omega_{p1} = - \frac{1}{C_L \cdot (r_{os} // r_{o7})} = - \frac{1}{40290 \times 40.78 \times 10^{-15}} = 6.08 \times 10^8 \text{ rad/sec}$$

$$\omega_{p2} = - \frac{g_{m3}}{(C_{gd1} + C_x)} = \frac{-3.73 \times 10^{-4}}{2 \times 10^{-16} + 67.732 \times 10^{-15}} = 5.5 \times 10^9 \text{ rad/sec}$$

6.17 (a)



Both of these two differential pair can be simplified as common-source amplifier with different load resistance and capacitance



Since $R_s = 0$, equation (6.20) can be simplified as

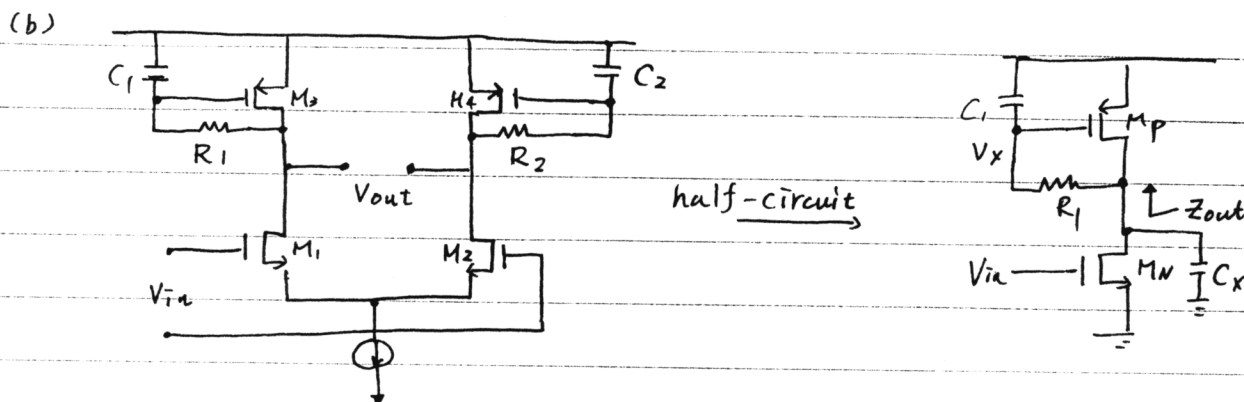
$$\frac{V_{out}}{V_{in}}(s) = \frac{(C_{gd}s - g_m)R_D}{s[R_D(C_{gd} + C_x)] + 1}$$

where $\begin{cases} R_D = \frac{1}{g_{mp}} \text{ for diode connected load} \\ C_x = C_{dbN} + C_{dbP} + C_{gsP} \end{cases}$

$\begin{cases} R_p \cong (r_{oN} \parallel r_{oP}) \text{ for current mirror load} \\ C_x = C_{dbN} + C_{dbP} + C_{gdP} \end{cases}$

Although there is right-half-plane zero, however this zero is much larger than the dominant pole.

Therefore, the maximum phase shift it can achieve is $\sim 90^\circ$ before the gain is down to unity.



(i) At low frequency, C_1 is open circuit,

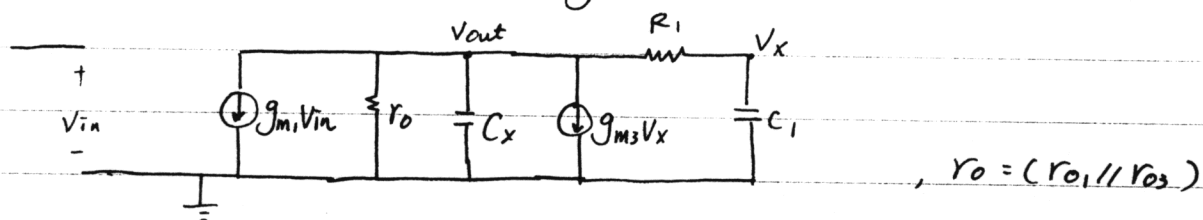
M_P is like a diode-connected device $\rightarrow Z_{out} \sim \frac{1}{g_{mp}}$

(ii) At high frequency, C_1 is short circuit.

M_P is like a current source device $\rightarrow Z_{out} \sim (r_{on} // r_{op})$

Since $(r_{on} // r_{op}) \gg \frac{1}{g_{mp}}$, Z_{out} exhibits an inductive behavior

For transfer function, small-signal model



$$\text{KCL @ } V_x : \frac{V_{out} - V_x}{R_1} = sC_1 V_x \Rightarrow V_{out} = (1 + sR_1 C_1) V_x$$

$$\Rightarrow V_x = \frac{V_{out}}{1 + sR_1 C_1}$$

$$\text{KCL @ } V_{out} : -g_{m1} V_{in} = V_{out} \left(\frac{1}{r_o} + sC_x \right) + \frac{1}{R_1} (V_{out} - V_x) + g_{m3} V_x$$

$$= V_{out} \left(\frac{1}{r_o} + sC_x + \frac{1}{R_1} \right) + \left(g_{m3} - \frac{1}{R_1} \right) \cdot \frac{V_{out}}{1 + sR_1 C_1}$$

$$-g_m V_{in} = V_{out} \left(\frac{\frac{1}{r_o} + \frac{1}{R_1} + sC_x + \left(\frac{R_1}{r_o} + 1\right)sC_1 + s^2 R_1 C_1 C_x + g_{m3} \frac{1}{R_1}}{1 + sR_1 C_1} \right)$$

$$\frac{V_{out}}{V_{in}} = \frac{-g_m (1 + sR_1 C_1)}{s^2 R_1 C_1 C_x + s(C_1 + \frac{R_1 C_1}{r_o} + C_x) + (g_{m3} + \frac{1}{r_o})}$$

From the above transfer function,

$$\omega_z = -\frac{1}{R_1 C_1}$$

$$\text{the sum of two poles} = -\frac{1}{R_1 C_1 C_x} (C_1 + \frac{R_1 C_1}{r_o} + C_x) = -\frac{1}{R_1 C_1} (1 + \frac{C_1}{C_x} (1 + \frac{R_1}{r_o}))$$

usually $C_1 > C_x$, C_1 at least $= C_{gs3}$

Thus, the sum of two poles $> -\frac{2}{R_1 C_1}$, which means that at least one of the poles are larger than zero $\Rightarrow$ It's quite impossible to produce 135° phase shift

Thus, this circuit still can't produce 135° phase shift.

However, it's more likely for it to generate 90° phase shift

@ unity-gain frequency.

CHAPTER 7: NOISE

$$(7.1) \quad |A_v| = g_m R_D$$

$$\overline{V_{n,out}^2} = \left(4KT \frac{2}{3} g_m + \frac{4KT}{R_D} \right) R_D^2$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{A_v^2} = 4KT \left(\frac{2}{3} \frac{1}{g_m} + \frac{1}{g_m^2 R_D} \right)$$

$$\overline{V_{n,in_{TOT}}} = \sqrt{\overline{V_{n,in}^2} \cdot BW}$$

$$g_m = \sqrt{2I_D \mu_n C_{ox} \left(\frac{W}{L} \right)} = \sqrt{2(1mA)(134.28 \frac{\mu A}{V^2}) \left(\frac{50\mu m}{0.34\mu m} \right)} \approx 6.28 \frac{mA}{V}$$

$$4KT = 1.656 \times 10^{-20} \text{ V-c}, \quad R_D = 2k\Omega, \quad BW = 100 \text{ MHz}$$

$$\therefore \overline{V_{n,in_{TOT}}} = \sqrt{(1.966 \times 10^{-18} \frac{V^2}{Hz})(100 \text{ MHz})} \approx 14 \mu V \text{ rms} //$$

(7.2) using eqn. (7.57)

$$\overline{V_{n,in}^2} = 4KT \left(\frac{2}{3} \frac{1}{g_{m1}} + \frac{2}{3} \frac{g_{m2}}{g_{m1}^2} \right)$$

$$\overline{V_{n,in}} = \sqrt{4KT \frac{2}{3}} \sqrt{\frac{1}{g_{m1}} + \frac{g_{m2}}{g_{m1}^2}}$$

$$\frac{g_{m2}}{g_{m1}^2} = \left(\frac{1}{5} \right)^2 \frac{1}{g_{m1}} \Rightarrow g_{m2} = \left(\frac{1}{5} \right)^2 g_{m1}$$

$$g_m = \frac{2I_D}{V_{GS} - V_T} \Rightarrow V_{GS} - V_T = \frac{2I_D}{g_m}$$

$$\therefore \text{Output Swing} = V_{DD} - (V_{GS1} - V_{T1}) - |(V_{GS2} - V_{T2})|$$

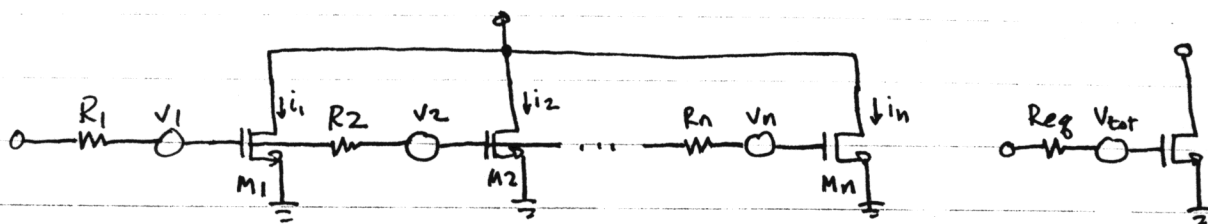
$$= V_{DD} - 2I_D \left(\frac{1}{g_{m1}} + \frac{1}{g_{m2}} \right)$$

$$= V_{DD} - 2I_D \left(\frac{1}{g_{m1}} \right) (1 + 5^2)$$

$$g_{m1} = \sqrt{2I_D \mu_n C_{ox} \left(\frac{W}{L} \right)} = \sqrt{2(61mA)(134.28 \frac{\mu A}{V^2}) \left(\frac{50\mu m}{0.34\mu m} \right)} \approx 1.986 \frac{mA}{V}$$

$$\therefore \text{Output Swing} = 3V - 2(61mA) \left(\frac{1}{1.986 \frac{mA}{V}} \right) (26) \approx 0.38V //$$

(7.3)



The drain noise current of M_1 resulting from the gate resistance is

$$i_1 = g_{m1} V_1 \quad \text{where } V_1 \text{ is the noise voltage of } R_1.$$

Similarly, $i_2 = g_{m2} (V_1 + V_2)$

Thus, for transistor M_j , $i_j = g_{mj} (V_1 + V_2 + \dots + V_j)$

The total drain noise current is,

$$\begin{aligned} i_{tot} &= i_1 + i_2 + \dots + i_n \\ &= g_{m1} V_1 + g_{m2} (V_1 + V_2) + \dots + g_{mn} (V_1 + V_2 + \dots + V_n) \end{aligned}$$

If $g_{m1} = g_{m2} = \dots = g_{mn} = \frac{g_m}{n}$ then

$$i_{tot} = \frac{g_m}{n} [nV_1 + (n-1)V_2 + \dots + V_n]$$

Assuming $V_1, \dots, V_n$ are uncorrelated,

$$\overline{i_{tot}^2} = \frac{g_m^2}{n^2} [n^2 \overline{V_1^2} + (n-1)^2 \overline{V_2^2} + \dots + \overline{V_n^2}]$$

If $R_1 = R_2 = \dots = R_n = \frac{R_g}{n}$ then $\overline{V_1^2} = \overline{V_2^2} = \dots = \overline{V_n^2} = 4kTB \frac{R_g}{n}$

$$\overline{i_{tot}^2} = \frac{g_m^2}{n^2} \frac{4kTB R_g}{n} [n^2 + (n-1)^2 + \dots + 1]$$

$$= g_m^2 (4kTB) R_g \frac{n(n+1)(2n+1)}{6n^3}$$

As $n \rightarrow \infty$

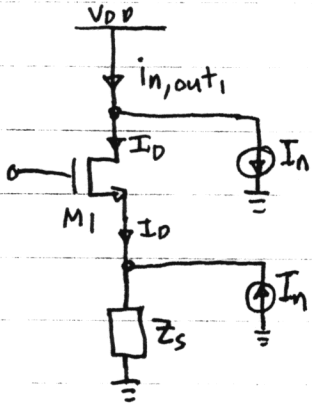
$$\overline{i_{tot}^2} = g_m^2 (4kTB \frac{R_g}{3})$$

which can be referred to the input as

$$\overline{V_{tot}^2} = \frac{\overline{i_{tot}^2}}{g_m^2} = 4kTB \left(\frac{R_g}{3} \right)$$

$$\Rightarrow \text{lumped resistance} = \frac{R_g}{3} //$$

(7.4)



$$I_{n,out,1} = I_D + I_n, \text{ KCL @ drain}$$

$$I_D = \frac{-z_s}{(\frac{1}{g_m} \parallel r_o) + z_s} I_n, \text{ current divider @ source}$$

$$\therefore I_{n,out,1} = \left(\frac{-z_s}{(\frac{1}{g_m} \parallel r_o) + z_s} + 1 \right) I_n$$

$$\therefore I_{n,out,1} = \frac{I_n}{z_s(g_m + \frac{1}{r_o}) + 1} //$$

(7.5)

$$|A_v| = (g_{m1} + g_{m2})(r_{o1} \parallel r_{o2})$$

$$\overline{V_{n,out}^2} = 4kT \frac{2}{3} (g_{m1} + g_{m2})(r_{o1} \parallel r_{o2})^2$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4kT \frac{2}{3} \left(\frac{1}{g_{m1} + g_{m2}} \right)$$

$$\text{eqn(7.57)} \quad \overline{V_{n,in}^2} = 4kT \frac{2}{3} \left(\frac{1}{g_{m1}} + \frac{g_{m2}}{g_{m1}^2} \right)$$

increasing g_{m2} increases $\overline{V_{n,in}^2}$ in eqn. (7.57)

but reduces $\overline{V_{n,in}^2}$ for amplifier in figure 7.49.

(7.6)(a)

$$|A_v| = \frac{g_m R_D}{1 + g_m R_S}$$

$$\overline{V_{n,out}^2} = 4kT R_D + 4kT \frac{2}{3} \frac{1}{g_m} \left(\frac{g_m R_D}{1 + g_m R_S} \right)^2 + 4kT \frac{1}{R_S} \left(\frac{R_S}{\frac{1}{g_m} + R_S} \right)^2 R_D^2$$

$$= 4kT R_D + 4kT \frac{2}{3} \frac{1}{g_m} \left(\frac{g_m R_D}{1 + g_m R_S} \right)^2 + 4kT R_S \left(\frac{g_m R_D}{1 + g_m R_S} \right)^2$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4kT \frac{2}{3} \frac{1}{g_m} + 4kT R_S + 4kT R_D \left(\frac{1 + g_m R_S}{g_m R_D} \right)^2 //$$

(7.6)(b)

$$|A_v| = g_m \left(\frac{1}{g_m} \parallel R_S \right)$$

$$\overline{V_{n,out}^2} = (4kT \frac{2}{3} g_m + 4kT \frac{1}{R_S}) \left(\frac{1}{g_m} \parallel R_S \right)^2$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4kT \frac{2}{3} \frac{1}{g_m} + 4kT \frac{1}{g_m^2 R_S} //$$

$$(7.6)(c) \quad |A_v| = \frac{g_m}{1 + (g_m + \frac{1}{R_F})R_S} \cdot R_{out}$$

$$R_{out} = R_S + (1 + g_m R_S) R_F$$

$$\overline{V_{n,out}^2} = \left(\frac{4KT \frac{2}{3} g_m}{(1 + (g_m + \frac{1}{R_F})R_S)^2} + \frac{4KT \frac{1}{R_F}}{(1 + (g_m + \frac{1}{R_F})R_S)^2} + \frac{4KT \frac{1}{R_S} \cdot R_S^2}{(R_S + \frac{1}{g_m} \parallel R_F)^2} \right) R_{out}^2$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4KT \left(\frac{2}{3} \frac{1}{g_m} + \frac{1}{g_m^2 R_F} + R_S \left(1 + \frac{1}{g_m R_F} \right)^2 \right) //$$

$$(7.6)(d) \quad |A_v| = \frac{g_{m1}}{1 + g_{m1} R_S} \cdot R_{out}$$

$$R_{out} = \frac{1}{g_{m2}}$$

$$\overline{V_{n,out}^2} = 4KT \frac{2}{3} g_{m2} R_{out}^2 + 4KT \frac{2}{3} \frac{1}{g_{m1}} |A_v|^2 + 4KT \frac{1}{R_S} \left(\frac{R_S}{\frac{1}{g_{m1}} + R_S} \right)^2 R_{out}^2$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4KT \left[\frac{2}{3} \frac{1}{g_{m1}} + R_S + \frac{2}{3} g_{m2} \left(\frac{1 + g_{m1} R_S}{g_{m1}} \right)^2 \right] //$$

$$(7.6)(e) \quad |A_v| = g_{m1} R_D$$

$$\overline{V_{n,out}^2} = (4KT \frac{2}{3} g_{m1} + 4KT \frac{1}{R_D}) R_D^2$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4KT \left(\frac{2}{3} \frac{1}{g_{m1}} + \frac{1}{g_{m1}^2 R_D} \right) //$$

$M2 + R_F$ do not
contribute noise
because $r_{o1} = \infty$

$$(7.6)(f) \quad |A_v| = g_{m1} \left(\frac{g_{m2} R_S}{1 + g_{m2} R_S} \right) R_D$$

$$\overline{V_{n,out}^2} = \left[4KT \frac{1}{R_D} + 4KT \frac{2}{3} \frac{1}{g_{m2}} \left(\frac{g_{m2}}{1 + g_{m2} R_S} \right)^2 + 4KT \frac{2}{3} \frac{1}{g_{m1}} \left(\frac{g_{m1} R_S}{\frac{1}{g_{m2}} + R_S} \right)^2 + 4KT \frac{1}{R_S} \left(\frac{R_S}{\frac{1}{g_{m2}} + R_S} \right)^2 \right] \cdot R_D^2$$

$$\text{note: } \frac{R_S}{\frac{1}{g_{m2}} + R_S} = \frac{g_{m2} R_S}{1 + g_{m2} R_S}$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4KT \left[\frac{2}{3} \frac{1}{g_{m1}} + \frac{2}{3} \frac{1}{g_{m2} (g_{m1} R_S)^2} + \frac{1}{g_{m1}^2 R_S} + \frac{1}{g_{m1}^2 R_D} \left(\frac{1 + g_{m2} R_S}{g_{m2} R_S} \right)^2 \right] //$$

$$(7.7)(a) \quad |A_v| = \frac{g_{m1} R_{out}}{1 + (g_{m1} + \frac{1}{R_F}) R_S}$$

$$R_{out} = R_S + (1 + g_{m1} R_S) R_F$$

$$\overline{V_{n,out}^2} = \left[\frac{4kT \frac{2}{3} g_{m1}}{(1 + (g_{m1} + \frac{1}{R_F}) R_S)^2} + \frac{4kT \frac{1}{R_F}}{(1 + (g_{m1} + \frac{1}{R_F}) R_S)^2} + \frac{4kT \frac{1}{R_S} \cdot R_S^2}{(R_S + \frac{1}{g_{m1}} // R_F)^2} + 4kT \frac{2}{3} g_{m2} \right] R_{out}^2$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4kT \left[\frac{2}{3} \frac{1}{g_{m1}} + \frac{1}{g_{m1}^2 R_F} + R_S \left(1 + \frac{1}{g_{m1} R_F} \right)^2 + \frac{2}{3} g_{m2} \left(\frac{1 + (g_{m1} + \frac{1}{R_F}) R_S}{g_{m1}} \right)^2 \right] //$$

$$(7.7)(b) \quad |A_v| = \left(g_{m2} + \frac{g_{m1}}{1 + (g_{m1} + \frac{1}{R_F}) R_S} \right) \cdot R_{out}$$

$$R_{out} = R_S + (1 + g_{m1} R_S) R_F$$

$$\overline{V_{n,out}^2} = \left[\frac{4kT \frac{2}{3} g_{m1}}{(1 + (g_{m1} + \frac{1}{R_F}) R_S)^2} + \frac{4kT \frac{1}{R_F}}{(1 + (g_{m1} + \frac{1}{R_F}) R_S)^2} + \frac{4kT \frac{1}{R_S} \cdot R_S^2}{(R_S + \frac{1}{g_{m1}} // R_F)^2} + 4kT \frac{2}{3} g_{m2} \right] R_{out}^2$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4kT \left(\frac{1}{g_{m1} + g_{m2} (1 + (g_{m1} + \frac{1}{R_F}) R_S)} \right)^2 \left[\frac{2}{3} g_{m1} + \frac{1}{R_F} + R_S (g_{m1} + \frac{1}{R_F})^2 + \frac{2}{3} g_{m2} (1 + (g_{m1} + \frac{1}{R_F}) R_S)^2 \right] //$$

$$(7.7)(c) \quad |A_v| = \left(\frac{g_{m1}}{1 + g_{m1} R_S} \right) (1 + g_{m2} R_S) (R_D)$$

$$\overline{V_{n,out}^2} = 4kT R_D + 4kT \frac{2}{3} g_{m2} R_D^2 + 4kT \frac{2}{3} \frac{1}{g_{m1}} |A_v|^2 + 4kT \frac{1}{R_S} \left[\frac{R_S}{\frac{1}{g_{m1}} + R_S} - \frac{\frac{1}{g_{m1}} R_S}{\frac{1}{g_{m1}} + R_S} g_{m2} \right]^2 R_D^2$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4kT \left[\frac{2}{3} \frac{1}{g_{m1}} + \left(\frac{1}{R_D} + \frac{2}{3} g_{m2} \right) \left(\frac{1 + g_{m1} R_S}{g_{m1} (1 + g_{m2} R_S)} \right)^2 + R_S (g_{m1} - g_{m2})^2 \left(\frac{1}{g_{m1} (1 + g_{m2} R_S)} \right)^2 \right] //$$

$$(7.7)(d) \quad |A_v| = g_{m1} R_D$$

$$\overline{V_{n,out}^2} = \left[4kT \frac{1}{R_D} + 4kT \frac{2}{3} g_{m3} + 4kT \frac{2}{3} g_{m1} \right] R_D^2$$

M2 does not contribute any noise because r_{o1} and $r_{o3} = \infty$.

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4kT \left[\frac{2}{3} \frac{1}{g_{m1}} + \frac{2}{3} \frac{g_{m3}}{g_{m1}^2} + \frac{1}{g_{m1}^2 R_D} \right] //$$

$$(7.8)(a) \quad |A_v| = g_{m1} R_D$$

$$\overline{V_{n,out}^2} = \left[4kT \frac{1}{R_D} + 4kT \frac{2}{3} g_{m1} + 4kT R_G g_{m1}^2 \right] R_D^2$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4kT \left(\frac{2}{3} \frac{1}{g_{m1}} + R_G + \frac{1}{g_{m1}^2 R_D} \right) //$$

$$(7.8)(b) \quad |A_v| = \left(g_{m1} + \frac{1}{R_1} \right) (R_1 // R_D)$$

$$\overline{V_{n,out}^2} = \left[4kT \frac{2}{3} g_{m1} + 4kT \frac{1}{R_1} + 4kT \frac{1}{R_D} \right] (R_1 // R_D)^2$$

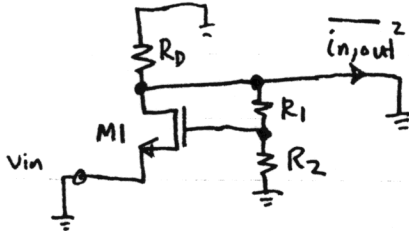
$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4kT \left(\frac{1}{g_{m1} + \frac{1}{R_1}} \right)^2 \left[\frac{2}{3} g_{m1} + \frac{1}{R_1} + \frac{1}{R_D} \right] //$$

$$(7.8)(c) \quad A_v = \left(-g_{m1} + \frac{1}{R_F} \right) (R_F // R_D)$$

$$\overline{V_{n,out}^2} = 4kT \left(\frac{1}{R_F} + \frac{1}{R_D} + \frac{2}{3} g_{m1} \right) (R_F // R_D)^2$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4kT \left(\frac{1}{-g_{m1} + \frac{1}{R_F}} \right)^2 \left[\frac{2}{3} g_{m1} + \frac{1}{R_F} + \frac{1}{R_D} \right] //$$

$$(7.8)(d) \quad \text{Find short circuit output noise current } \overline{i_{n,out}^2}$$

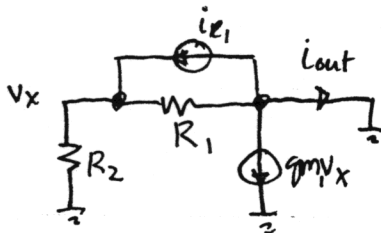


$$\overline{i_{n,out}^2} = 4kT \frac{1}{R_D} + 4kT \frac{2}{3} g_{m1} + \overline{i_{noise,R1}^2} + \overline{i_{noise,R2}^2}$$

$$\overline{i_{noise,R1}^2} = 4kT \frac{1}{R_1} |A_{I,R1}|^2$$

$$\overline{i_{noise,R2}^2} = 4kT \frac{1}{R_2} |A_{I,R2}|^2$$

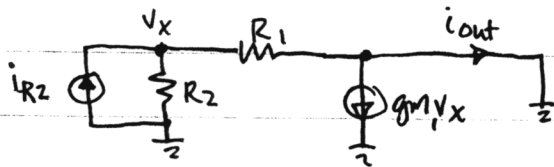
• small signal model used to find $A_{I,R1}$



$$A_{I,R1} = \frac{i_{out}}{i_{R1}} = -(1 + (R_1 // R_2)(g_{m1} - \frac{1}{R_1}))$$

(7.8) (d) cont.

- small signal model used to find $A_{I,R2}$



$$A_{I,R2} = \frac{i_{out}}{i_{R2}} = \left[\frac{R_2}{R_1 + R_2} - g_{m1}(R_1 \parallel R_2) \right]$$

$$\begin{aligned} \therefore \overline{i_{n,out}^2} &= 4kT \frac{1}{R_D} + 4kT \frac{2}{3} g_{m1} + 4kT \frac{1}{R_1} \left(1 + (R_1 \parallel R_2) \left(g_{m1} - \frac{1}{R_1} \right) \right)^2 + 4kT \frac{1}{R_2} \left[\frac{R_2}{R_1 + R_2} - g_{m1}(R_1 \parallel R_2) \right]^2 \\ \overline{v_{n,in}^2} &= \frac{\overline{i_{n,out}^2}}{g_{m1}^2} = 4kT \left[\frac{2}{3} \frac{1}{g_{m1}} + \frac{1}{g_{m1}^2 R_D} + \frac{1}{g_{m1}^2 R_1} \left(1 + (R_1 \parallel R_2) \left(g_{m1} - \frac{1}{R_1} \right) \right)^2 + \frac{1}{g_{m1}^2 R_2} \left(\frac{R_2}{R_1 + R_2} - g_{m1}(R_1 \parallel R_2) \right)^2 \right] // \end{aligned}$$

$$(7.9)(a) \quad |A_v| = g_{m1} R_D$$

$$\overline{v_{n,out}^2} = 4kT \left(\frac{1}{R_D} + \frac{2}{3} g_{m1} \right) R_D^2$$

$$\overline{v_{n,in}^2} = \frac{\overline{v_{n,out}^2}}{|A_v|^2} = 4kT \left(\frac{2}{3} \frac{1}{g_{m1}} + \frac{1}{g_{m1}^2 R_D} \right) //$$

$$(7.9)(b) \quad |A_v| = g_{m1} (R_D \parallel \frac{1}{g_{m2}})$$

$$\overline{v_{n,out}^2} = 4kT \left(\frac{1}{R_D} + \frac{2}{3} g_{m1} + \frac{2}{3} g_{m2} \right) (R_D \parallel \frac{1}{g_{m2}})^2$$

$$\overline{v_{n,in}^2} = \frac{\overline{v_{n,out}^2}}{|A_v|^2} = 4kT \left(\frac{2}{3} \frac{1}{g_{m1}} + \frac{1}{g_{m1}^2 R_D} + \frac{2}{3} \frac{g_{m2}}{g_{m1}^2} \right) //$$

$$(7.9)(c) \quad |A_v| = g_{m1} R_D$$

$$\overline{v_{n,out}^2} = 4kT \left(\frac{2}{3} g_{m1} + \frac{1}{R_D} \right) R_D^2$$

$$\overline{v_{n,in}^2} = \frac{\overline{v_{n,out}^2}}{|A_v|^2} = 4kT \left(\frac{2}{3} \frac{1}{g_{m1}} + \frac{1}{g_{m1}^2 R_D} \right) //$$

$$(7.9)(d) \quad |A_v| = \frac{g_{m1}}{g_{m1} + g_{m2}}$$

$$\overline{v_{n,out}^2} = \left(4kT \frac{2}{3} g_{m1} + 4kT \frac{2}{3} g_{m2} \right) \left(\frac{1}{g_{m1} + g_{m2}} \right)^2$$

$$\overline{v_{n,in}^2} = \frac{\overline{v_{n,out}^2}}{|A_v|^2} = 4kT \left(\frac{2}{3} \frac{1}{g_{m1}} + \frac{2}{3} \frac{g_{m2}}{g_{m1}^2} \right) //$$

$$(7.9)(e) \quad |A_v| = 1, \quad \overline{v_{n,in}^2} = \overline{v_{n,out}^2} = 4kT \frac{2}{3} \frac{1}{g_{m1}} //$$

(7.10) • With the input shunted to ground,

$$\overline{V_{n,out}^2} = \frac{1}{C_{ox} f} \left[\frac{g_{m1}^2 k_n}{(WL)_1} + \frac{g_{m3}^2 k_p}{(WL)_3} + \frac{g_{m3}^2 k_p}{(WL)_4} \right] (r_{o1} \parallel r_{o3})^2$$

$$|A_v| = (g_{m1} + g_{mb1})(r_{o1} \parallel r_{o3})$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = \frac{1}{C_{ox} f} \left[\frac{g_{m1}^2 k_n}{(WL)_1} + \frac{g_{m3}^2 k_p}{(WL)_3} + \frac{g_{m3}^2 k_p}{(WL)_4} \right] \frac{1}{(g_{m1} + g_{mb1})^2} //$$

• With the input open,

$$\overline{V_{n,out}^2} = \frac{1}{C_{ox} f} \left[g_{m2}^2 k_n \left(\frac{1}{(WL)_0} + \frac{1}{(WL)_2} \right) + g_{m3}^2 k_p \left(\frac{1}{(WL)_3} + \frac{1}{(WL)_4} \right) \right] R_{out}^2$$

$$R_{out} \approx r_{o3} \parallel (g_{m1} r_{o1} r_{o2})$$

$$\overline{I_{n,in}^2} = \frac{1}{C_{ox} f} \left[g_{m2}^2 k_n \left(\frac{1}{(WL)_0} + \frac{1}{(WL)_2} \right) + g_{m3}^2 k_p \left(\frac{1}{(WL)_3} + \frac{1}{(WL)_4} \right) \right] //$$

$$(7.11) \quad \overline{V_{n,out}^2} = \frac{k}{C_{ox}(WL)_1} \cdot \frac{1}{f} (g_{m1} R_{out})^2 + \frac{k}{C_{ox}(WL)_2} \cdot \frac{1}{f} (g_{m2} R_{out})^2$$

$$R_{out} = \left(\frac{1}{g_{m1}} \parallel \frac{1}{g_{mb1}} \parallel r_{o1} \parallel r_{o2} \right)$$

$$|A_v| = g_{m1} R_{out}$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = \frac{k}{C_{ox} f} \left[\frac{1}{(WL)_1} + \frac{g_{m2}^2}{(WL)_2 g_{m1}^2} \right] //$$

$$(7.12)(a) \quad \overline{V_{n,out}^2} = 4KT \frac{2}{3} (g_{m1} + g_{m2} + g_{m3} + g_{m4} + g_{m5} + g_{m6}) R_{out}^2$$

$$|A_v| = g_{m1} R_{out}$$

$$g_{m1} = g_{m2}, \quad g_{m3,4} = 0.5 g_{m5,6}$$

$$\overline{V_{n,in}^2} = 4KT \frac{2}{3} \left[\frac{2}{g_{m1}} + \frac{2 g_{m5}}{g_{m1}^2} \right] //$$

$$(7.12)(b) \quad |A_v| = g_{m1} (r_{o2} \parallel r_{o4})$$

$$\overline{V_{n,out}^2} = 4KT \frac{2}{3} [g_{m1} + g_{m2} + g_{m3} + g_{m4}]$$

$$g_{m1} = g_{m2}, \quad g_{m3} = g_{m4}$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4KT \left(\frac{2}{3} \right) \left[\frac{2}{g_{m1}} + \frac{2 g_{m3}}{g_{m1}^2} \right] //$$

$$(7.13)(a) \quad |A_v| = \frac{g_{m1} R_D}{1 + g_{m1} R_S}$$

$$\overline{V_{n,out}^2} = 4KT R_D + 4KT \frac{2}{3} \frac{1}{g_{m1}} |A_v|^2 + 4KT \frac{1}{R_S} \left(\frac{R_S}{R_S + \frac{1}{g_{m1}}} \right)^2 R_D^2$$

$$\overline{V_{n,in}^2} = 4KT \left[\frac{2}{3} \frac{1}{g_m} + R_S + \frac{1}{R_D} \left(\frac{1 + g_{m1} R_S}{g_{m1}} \right)^2 \right]$$

$$(7.13)(b) \quad I R_S = V_{GS} - V_T \Rightarrow R_S = \frac{V_{GS} - V_T}{I}$$

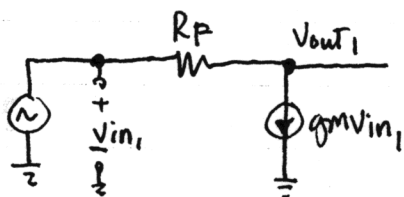
$$g_{m1} = \frac{2I}{V_{GS} - V_T} = \frac{2}{R_S}$$

$$\therefore 4KT \left[\frac{2}{3} g_m \right] = 4KT \frac{R_S}{3} \quad \leftarrow \text{Thermal noise of } M1$$

$$4KT R_S \quad \leftarrow \text{Thermal noise of } R_S$$

$\therefore R_S$ contributes 3x more noise power ($\overline{V_{n,in}^2}$) than $M1$
when $I R_S = V_{GS} - V_T$.

(7.14) Consider the following ckt with noise only due to resistor R_F :

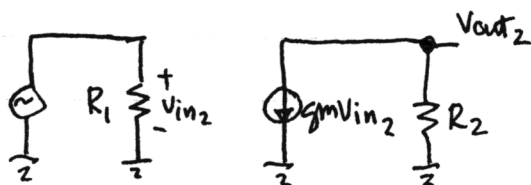


$$A_{v1} = \frac{V_{out1}}{V_{in1}} = -g_m R_F + 1$$

$$\overline{V_{n,out1}^2} = 4KT R_F$$

$$\overline{V_{n,in1}^2} = \frac{\overline{V_{n,out1}^2}}{|A_{v1}|^2} = 4KT R_F \left(\frac{1}{-g_m R_F + 1} \right)^2$$

using the Miller effect, we have the following ckt:



$$A_{v2} = \frac{V_{out2}}{V_{in2}} = -g_m R_2 = \frac{-g_m R_F A_{v1}}{A_{v1} - 1} = (-g_m R_F + 1) = A_{v1}$$

$$\overline{V_{n,out2}^2} = 4KT R_2$$

$$\overline{V_{n,in2}^2} = \frac{\overline{V_{n,out2}^2}}{|A_{v2}|^2} = 4KT \frac{1}{g_m^2 R_2} = 4KT \frac{1}{g_{m1}} \left(\frac{-1}{-g_m R_F + 1} \right)$$

$$R_1 = \frac{R_F}{1 - A_{v1}} \quad R_2 = \frac{R_F}{1 - \frac{1}{A_{v1}}}$$

notice: $\overline{V_{n,in1}^2} \neq \overline{V_{n,in2}^2} \Rightarrow$ cannot use Miller's Theorem //

(7.15) Using equation (7.26)

$$\begin{aligned} V_{n,out}^2 &= 4kT \left(\frac{2}{3} g_m \right) r_o^2 \\ &= (1.656 \times 10^{-20} \text{ V}\cdot\text{C}) \left(\frac{2}{3} \right) \left(4.44 \frac{\text{mA}}{\text{V}} \right) (20 \text{ k}\Omega)^2 \\ &= 19.6 \times 10^{-15} \frac{\text{V}^2}{\text{Hz}} \end{aligned}$$

$$\overline{V_{n,out}}_{TOT} = \sqrt{(19.6 \times 10^{-15} \frac{\text{V}^2}{\text{Hz}})(50 \text{ MHz})} \approx 990 \mu\text{V rms} //$$

$$(7.16) |A_v|^2 = \frac{[g_m(R_D || r_o)]^2}{1 + (2\pi(R_D || r_o)C_L f)^2}$$

$$\begin{aligned} \overline{V_{n,out}^2} &= 4kT \frac{(R_D || r_o)^2}{R_D} \frac{1}{1 + (2\pi(R_D || r_o)C_L f)^2} + 4kT \frac{2}{3} g_m (R_D || r_o)^2 \frac{1}{1 + (2\pi(R_D || r_o)C_L f)^2} \\ &\quad + \frac{k}{C_{ox} W L} g_m^2 (R_D || r_o)^2 \frac{1}{1 + (2\pi(R_D || r_o)C_L f)^2} \end{aligned}$$

$$\begin{aligned} \overline{V_{n,out}}_{TOT}^2 &= 4kT (R_D || r_o) \left[\frac{(R_D || r_o)}{R_D} + \frac{2}{3} g_m (R_D || r_o) \right] \int_{f_L}^{f_H} \frac{df}{1 + (2\pi(R_D || r_o)C_L f)^2} \\ &\quad + \frac{k g_m^2 (R_D || r_o)^2}{C_{ox} W L} \int_{f_L}^{f_H} \frac{df}{f (1 + (2\pi(R_D || r_o)C_L f)^2)} \end{aligned}$$

$$\begin{aligned} \overline{V_{n,out}}_{TOT}^2 &= \frac{2kT}{\pi C_L} \left[\frac{(R_D || r_o)}{R_D} + \frac{2}{3} g_m (R_D || r_o) \right] \left[\tan^{-1}(2\pi(R_D || r_o)C_L f_H) - \tan^{-1}(2\pi(R_D || r_o)C_L f_L) \right] \\ &\quad + \frac{k g_m^2 (R_D || r_o)^2}{C_{ox} W L} \int_{f_L}^{f_H} \frac{df}{f [1 + (2\pi(R_D || r_o)C_L f)^2]} // \end{aligned}$$

(7.17) Using equation number (7.57)

$$\overline{V_{n,in}^2} = 4kT \left(\frac{2}{3} \right) \left(\frac{1}{g_{m1}} + \frac{g_{m2}}{g_{m1}^2} \right)$$

$$g_{m1} = \sqrt{2(0.5 \text{ mA})(134.29 \frac{\text{mA}}{\text{V}^2} \times \frac{50}{.34})} = 4.44 \frac{\text{mA}}{\text{V}}$$

$$g_{m2} = \sqrt{2(0.5 \text{ mA})(38.37 \frac{\text{mA}}{\text{V}^2} \times \frac{50}{.34})} = 2.36 \frac{\text{mA}}{\text{V}}$$

$$\begin{aligned} \therefore \overline{V_{n,in}^2} &= (1.656 \times 10^{-20} \text{ V}\cdot\text{C}) \left(\frac{2}{3} \right) (225.23 \Omega + 119.71 \Omega) \\ &\approx 3.81 \times 10^{-18} \frac{\text{V}^2}{\text{Hz}} \end{aligned}$$

$$\overline{V_{n,in}} \approx 1.95 \frac{\text{nV}}{\sqrt{\text{Hz}}} //$$

$$(7.18)(a) |A_v| = g_{m1} R_{out}$$

$$R_{out} = r_{o1} \parallel (R_S + (1 + g_{m2} R_S) r_{o2})$$

$$\overline{V_{n,out}}^2 = \left[4kT \frac{1}{R_S} \left(\frac{R_S}{R_S + \frac{1}{g_{m2}}} \right)^2 + 4kT \frac{2}{3} \frac{1}{g_{m2}} \left(\frac{g_{m2}}{1 + g_{m2} R_S} \right)^2 + 4kT \frac{2}{3} g_{m1} \right] R_{out}^2$$

$$\overline{V_{n,in}}^2 = \frac{\overline{V_{n,out}}^2}{|A_v|^2} = 4kT \left[\frac{2}{3} \frac{1}{g_{m1}} + R_S \left(\frac{g_{m2}}{1 + g_{m2} R_S} \right)^2 \frac{1}{g_{m1}^2} + \frac{2}{3} \frac{g_{m2}}{g_{m1}^2} \left(\frac{1}{1 + g_{m2} R_S} \right)^2 \right]$$

(b) R_S large

(7.19) Neglecting body effect and using eqns 7.60 and 7.61

$$\overline{V_{n,in}}^2 = 4kT \left(\frac{2}{3} \frac{1}{g_{m2}} + \frac{1}{g_{m2}^2 R_D} \right)$$

$$\overline{I_{n,in}}^2 = \frac{4kT}{R_D}$$

$$g_m = \sqrt{2(1mA)(134.29 \frac{\mu A}{V^2})(\frac{50}{.34})} = 6.28 \frac{mA}{V}$$

$$\therefore \overline{V_{n,in}}^2 = (1.656 \times 10^{-20} V \cdot C) \left(\frac{2}{3} 159.24 \Omega + 25.36 \Omega \right) \cong 2.18 \times 10^{-18} \frac{V^2}{Hz} //$$

$$\overline{I_{n,in}}^2 = \frac{(1.656 \times 10^{-20} V \cdot C)}{1k\Omega} = 16.56 \times 10^{-24} \frac{A^2}{Hz} //$$

$$(7.20)(a) \overline{I_{n,in}}^2 = 4kT \frac{1}{R_D} + 4kT \frac{2}{3} g_{m2}$$

$$\overline{I_{n,in}} = \sqrt{4kT \left(\frac{1}{R_D} + \frac{2}{3} g_{m2} \right)}$$

$$\therefore \frac{2}{3} g_{m2} = \left(\frac{1}{5} \right)^2 \left(\frac{1}{R_D} \right)$$

$$\Rightarrow g_{m2} = \left(\frac{1}{25} \right) \left(\frac{1}{1000} \right) \left(\frac{3}{2} \right) = 60 \frac{\mu A}{V}$$

$$\left(\frac{W}{L} \right)_2 = \frac{g_{m2}^2}{2I_D \mu_n C_{ox}} = \frac{(60 \frac{\mu A}{V})^2}{2(0.05mA)(134.29 \frac{\mu A}{V^2})} \cong 0.268 //$$

$$(b) g_{m2} = \frac{2I_D}{(V_{GS} - V_T)_2} \Rightarrow (V_{GS} - V_T)_2 = \frac{2I_D}{g_m} = \frac{2(0.05mA)}{60 \frac{\mu A}{V}} \cong 1.67 V$$

$$(V_{GS} - V_T)_1 = \sqrt{\frac{2I_D}{\mu_n C_{ox} \left(\frac{W}{L} \right)_1}} = \sqrt{\frac{2(0.05mA)}{134.29 \frac{\mu A}{V^2} \left(\frac{50}{.34} \right)}} \cong 71.2 mV$$

neglecting body effect

$$V_b = (V_{GS} - V_T)_2 + V_{GS1} = 1.67 + 0.0712 + 0.7 = 2.4412 V //$$

$$\text{Output Swing} = V_{CC} - (V_{GS} - V_T)_1 - (V_{GS} - V_T)_2 = 3 - 1.67 - 0.0712 = 1.2588 V //$$

Note: output swing is not symmetric.

(7.21) Neglecting body effect and using the result of eqn. 7.60

$$\overline{V_{n,in}} = \sqrt{4kT \left(\frac{2}{3} \frac{1}{g_{m1}} + \frac{1}{g_{m1}^2 R_D} \right)} = 3 \frac{nV}{\sqrt{Hz}}$$

$$\frac{2}{3} \frac{1}{g_{m1}} + \frac{1}{g_{m1}^2 R_D} = 543.4 \Omega$$

note:

$$\frac{1}{g_{m1}} = \frac{(V_{GS} - V_T)}{2I_D} \approx \frac{\Delta V}{2I_D}$$

$$\text{also define } R_N = 543.4 \Omega$$

$$\Rightarrow \Delta V^2 + \frac{4}{3} I_D R_D \Delta V - 4 I_D^2 R_D R_N = 0 \quad ; \quad I_D = 0.5 \text{ mA}$$

One possible answer assuming $(\frac{W}{L})_1 = (\frac{W}{L})_2$ and a 3V supply

$$\Delta V_1 = \Delta V_2 = 562 \text{ mV} \quad ; \quad R_D = 1875 \Omega$$

$$\Rightarrow \text{Output swing} = 2 \cdot I_D R_D = 1.875 \text{ V}_{//}$$

$$g_{m1} = g_{m2} = \frac{2I_D}{\Delta V} = 1.78 \frac{\text{mA}}{\text{V}}$$

$$\left(\frac{W}{L} \right) = \frac{g_m^2}{2I_D \mu_n C_{ox}} = \frac{(1.78 \text{ mA/V})^2}{2(0.5 \text{ mA})(134.29 \frac{\mu\text{A}}{\text{V}^2})} \approx 23.6 //$$

$$V_b = \Delta V_2 + V_{GS2} \approx 0.562 \text{ V} + 0.562 \text{ V} + 0.7 \text{ V} = 1.824 \text{ V} //$$

(7.22) Neglecting body effect and using eqns 7.64 + 7.65

$$\overline{V_{n,in}}^2 = 4kT \frac{2}{3} \left(\frac{1}{g_{m1}} + \frac{g_{m3}}{g_{m1}^2} \right)$$

$$\overline{I_{n,in}}^2 = 4kT \frac{2}{3} (g_{m2} + g_{m3})$$

$$g_{m1} = g_{m2} = \sqrt{2(0.5 \text{ mA})(134.29 \frac{\mu\text{A}}{\text{V}^2})(\frac{50}{.34})} \approx 4.44 \frac{\text{mA}}{\text{V}}$$

$$g_{m3} = \sqrt{2(0.5 \text{ mA})(38.37 \frac{\mu\text{A}}{\text{V}^2})(\frac{50}{.34})} \approx 2.38 \frac{\text{mA}}{\text{V}}$$

$$\therefore \overline{V_{n,in}}^2 = (1.656 \times 10^{-20} \text{ V} \cdot \text{C}) \left(\frac{2}{3} \right) (225.23 \Omega + 120.73 \Omega) \approx 3.82 \times 10^{-18} \frac{\text{V}^2}{\text{Hz}} //$$

$$\overline{I_{n,in}}^2 = (1.656 \times 10^{-20} \text{ V} \cdot \text{C}) \left(\frac{2}{3} \right) \left(4.44 \frac{\text{mA}}{\text{V}} + 2.38 \frac{\text{mA}}{\text{V}} \right) \approx 75.3 \times 10^{-24} \frac{\text{A}^2}{\text{Hz}} //$$

(7.23) Neglect body effect and use eqn. 7.65

$$\overline{I_{n,in}^2} = 4kT \frac{2}{3} (g_{m2} + g_{m3})$$

$$g_{m1} = \sqrt{2(0.5mA)(134.29 \frac{\mu A}{V^2})(\frac{50}{34})} = 4.44 \frac{mA}{V}$$

$$(V_{GS} - V_t)_1 = \frac{2I_D}{g_{m1}} = \frac{2(0.5mA)}{4.44 mA/V} \approx 225.23 mV$$

$$\text{define } \Delta V_x = |(V_{GS} - V_t)|_x$$

$$\therefore \text{Output Swing} = V_{CC} - (\Delta V_1 + \Delta V_2 + \Delta V_3) = 2V \quad ; \quad V_{CC} = 3V$$

$$\Rightarrow \Delta V_2 + \Delta V_3 = 774.77 mV$$

$$\text{note: } g_m = \frac{2I_D}{\Delta V}$$

$$\therefore \overline{I_{n,in}^2} = 4kT \left(\frac{2}{3} \right) 2I_D \left(\frac{\Delta V_2 + \Delta V_3}{\Delta V_2 \Delta V_3} \right)$$

$$\text{to minimize } \overline{I_{n,in}^2} \text{ let } \Delta V_2 = \Delta V_3 \Rightarrow g_{m2} = g_{m3} = \frac{2(0.5mA)}{0.387V} = 2.58 \frac{mA}{V}$$

$$\left(\frac{W}{L_{eff}} \right)_2 = \frac{(g_{m2})^2}{2I_{D,n} \mu_n C_{ox}} = \frac{(2.58 \frac{mA}{V})^2}{2(0.5mA)(134.29 \frac{\mu A}{V^2})} \approx 49.7 //$$

$$\left(\frac{W}{L_{eff}} \right)_3 = \frac{(g_{m3})^2}{2I_{D,p} C_{ox}} = \frac{(2.58 \frac{mA}{V})^2}{2(0.5mA)(38.37 \frac{\mu A}{V^2})} \approx 174 //$$

(7.24) (a) Neglecting body effect and r_{o1}, r_{o2}

$$R_{out} = \frac{1}{g_{m1}} = \frac{1}{\sqrt{2I_D \mu_n C_{ox} \left(\frac{W}{L}\right)_1}} = 100 \Omega$$

$$\left(\frac{W}{L}\right)_1 = \frac{1}{2I_D \mu_n C_{ox} R_{out}^2} = \frac{1}{2(61 \mu A)(134.29 \frac{\mu A}{V^2})(100 \Omega)^2} \approx 3723 //$$

(b) Using the result from eqn 7.73

$$V_{n,in} = \sqrt{4KT \left(\frac{2}{3}\right) \left(\frac{1}{g_{m1}} + \frac{g_{m2}}{g_{m1}^2}\right)}$$

$$\frac{g_{m2}}{g_{m1}^2} = \left(\frac{1}{5}\right)^2 \frac{1}{g_{m1}} \Rightarrow g_{m2} = \left(\frac{1}{5}\right)^2 g_{m1} = \frac{1}{2500 \Omega}$$

$$(V_{GS} - V_T)_2 = \frac{2I_D}{g_{m2}} = 0.5 V, \quad \left(\frac{W}{L}\right)_2 = \frac{(g_{m2})^2}{2I_D \mu_n C_{ox}} = \frac{(400 \mu A/V)^2}{2(61 \mu A)(134.29 \frac{\mu A}{V^2})} \approx 596 //$$

$$(V_{GS} - V_T)_1 = \sqrt{\frac{2I_D}{\mu_n C_{ox} \left(\frac{W}{L}\right)_1}} = \sqrt{\frac{2(61 \mu A)}{(134.29 \frac{\mu A}{V^2})(3723)}} \approx 20 mV$$

neglecting body effect

$$V_{GS1} \approx 0.7 + 0.02 = 0.72$$

$$\therefore \text{Output swing} \approx V_{CC} - V_{GS1} - (V_{GS} - V_T)_2 = 3 - 0.72 - 0.5 = 1.78 V //$$

$$(7.25) \quad |A_v|^2 = g_{m1}^2 \left(\frac{g_{m2}}{\omega C_x} \right)^2 \left(\frac{1}{1 + \left(\frac{g_{m2}}{\omega C_x} \right)^2} \right) R_D^2 \quad \omega = 2\pi f$$

$$\overline{V_{n,out}^2} = \left[4kT \frac{1}{R_D} + 4kT \frac{2}{3} \frac{1}{g_{m2}} \frac{g_{m2}^2}{1 + \left(\frac{g_{m2}}{\omega C_x} \right)^2} + 4kT \frac{2}{3} g_{m1} \left(\frac{g_{m2}}{\omega C_x} \right)^2 \left(\frac{1}{1 + \left(\frac{g_{m2}}{\omega C_x} \right)^2} \right) \right] R_D^2$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_v|^2} = 4kT \left[\frac{2}{3} \frac{1}{g_{m1}} + \frac{2}{3} \frac{1}{g_{m2}} \left(\frac{\omega C_x}{g_{m1}} \right)^2 + \frac{1}{R_D} \left(\frac{g_{m2}^2 + (\omega C_x)^2}{g_{m1}^2 g_{m2}^2} \right) \right] //$$

(7.26) (a) $M_1 = M_2$, M_3 does not contribute differential noise

$$|A_v| = \frac{g_{m1} R_L}{1 + g_{m1} R_S}$$

$$\overline{V_{n,out_a}^2} = \left[2(4kT) \frac{1}{R_D} + 2(4kT) \frac{2}{3} \frac{1}{g_{m1}} \left(\frac{g_{m1}}{1 + g_{m1} R_S} \right)^2 + 2(4kT) \frac{1}{R_S} \left(\frac{R_S}{\frac{1}{g_{m1}} + R_S} \right)^2 \right] R_D^2$$

$$\overline{V_{n,in_a}^2} = \frac{\overline{V_{n,out_a}^2}}{|A_v|^2} = 2(4kT) \left[\frac{2}{3} \frac{1}{g_{m1}} + R_S + \frac{1}{R_D} \left(\frac{1 + g_{m1} R_S}{g_{m1}} \right)^2 \right] //$$

(b) $M_1 = M_2$, $M_3 = M_4$

$$\overline{V_{n,out_b}^2} = \overline{V_{n,out_a}^2} + 2(4kT) \left(\frac{2}{3} \right) g_{m3} \left(\frac{R_S}{\frac{1}{g_{m1}} + R_S} \right)^2 R_D^2$$

$$\overline{V_{n,in_b}^2} = \frac{\overline{V_{n,out_b}^2}}{|A_v|^2} = 2(4kT) \left[\frac{2}{3} \frac{1}{g_{m1}} + R_S + \frac{1}{R_D} \left(\frac{1 + g_{m1} R_S}{g_{m1}} \right)^2 + \frac{2}{3} g_{m3} R_S^2 \right] //$$

$$\therefore \overline{V_{n,in_b}^2} = \overline{V_{n,in_a}^2} + 2(4kT) \left(\frac{2}{3} g_{m3} R_S^2 \right)$$

$M_3 + M_4$
contribute differential
noise in (b)