

Chapter 4: Motion in Two and Three Dimensions

- ✓ **Position and Displacement**
- ✓ **Velocity**
- ✓ **Acceleration**
- ✓ **Finding Displacement and Velocity from Acceleration**
- ✓ **Projectile Motion**
- ✓ **Uniform Circular Motion**
- ✓ **Relative Motion**

Chapter 4: Motion in Two and Three Dimensions

Session 8:

- ✓ **Uniform Circular Motion**
- ✓ **Relative Motion**
- ✓ **Examples**

Uniform Circular Motion

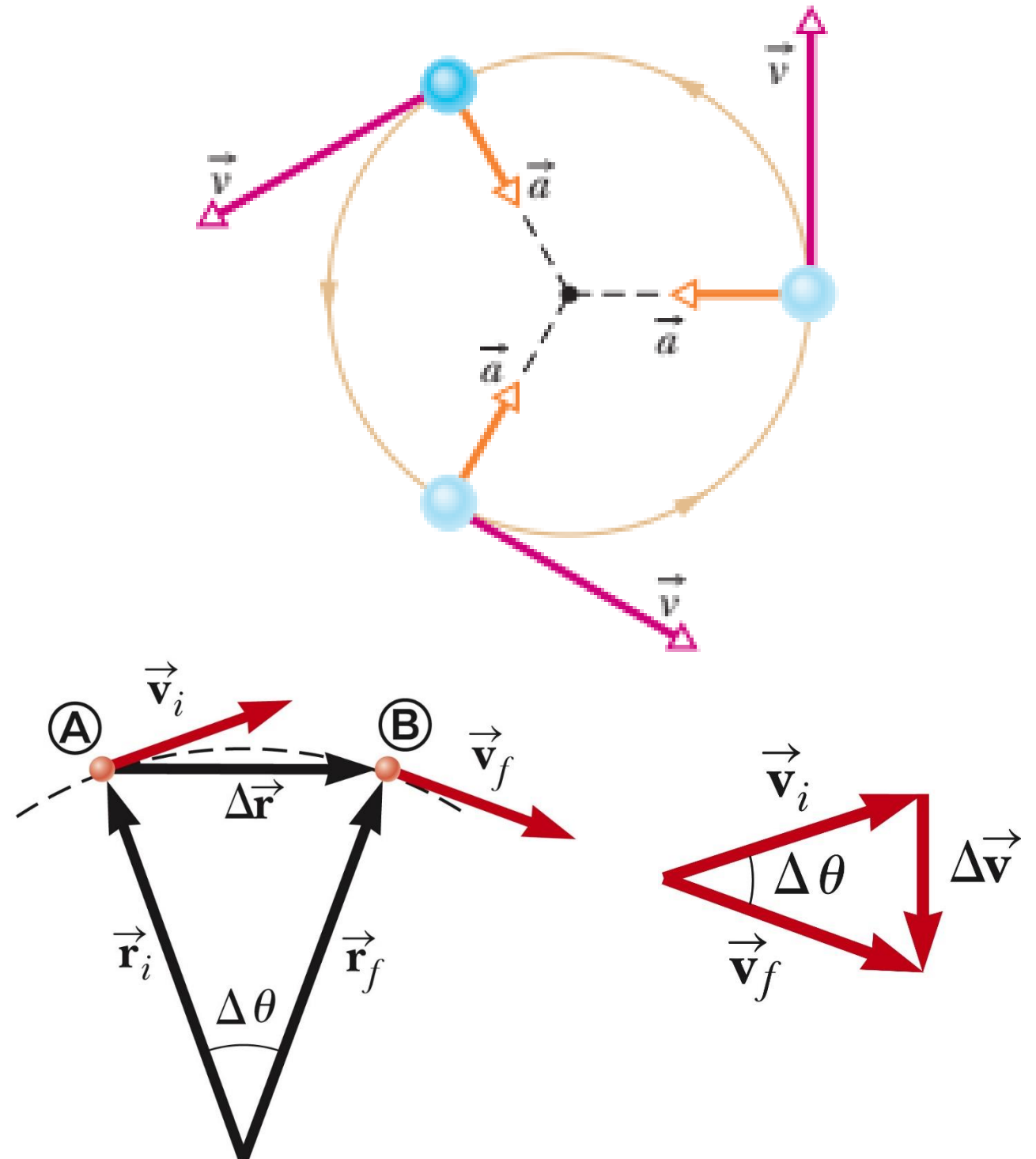
- ❖ A particle is in **uniform circular motion** if it travels around a circle or a circular arc at **constant (uniform) speed**.
- ❖ The particle is **accelerating** because the **velocity changes in direction**.

Centripetal Acceleration

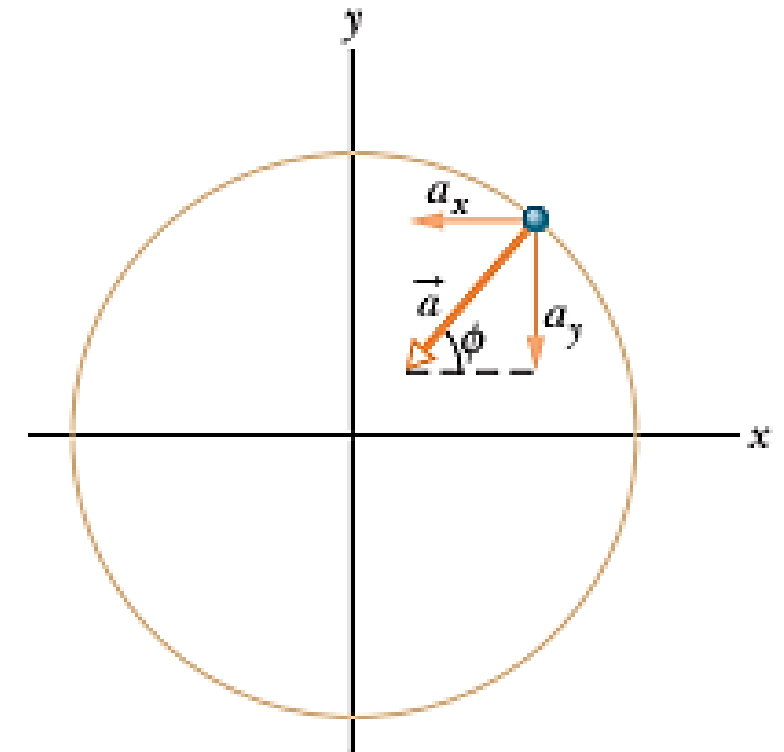
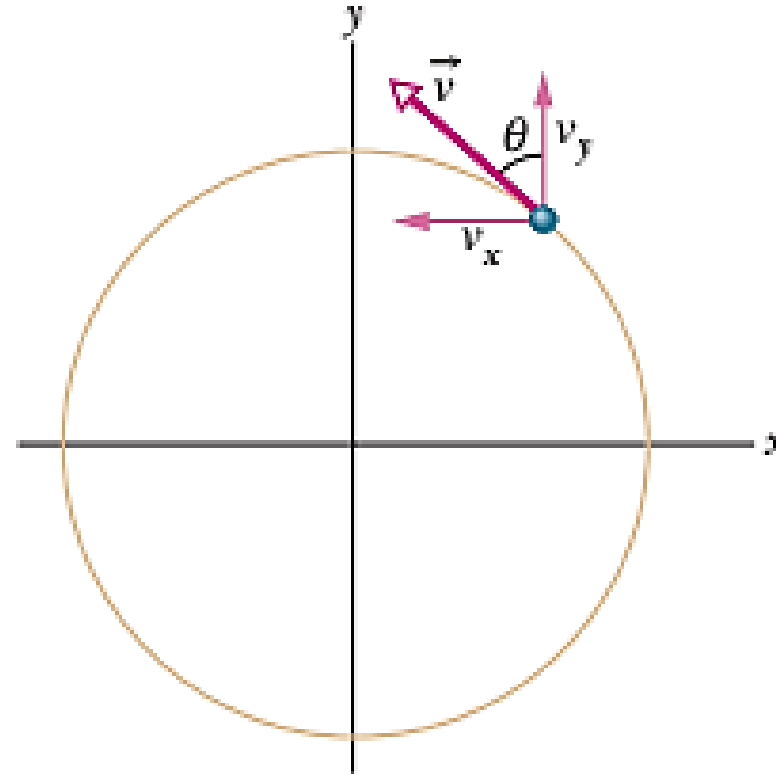
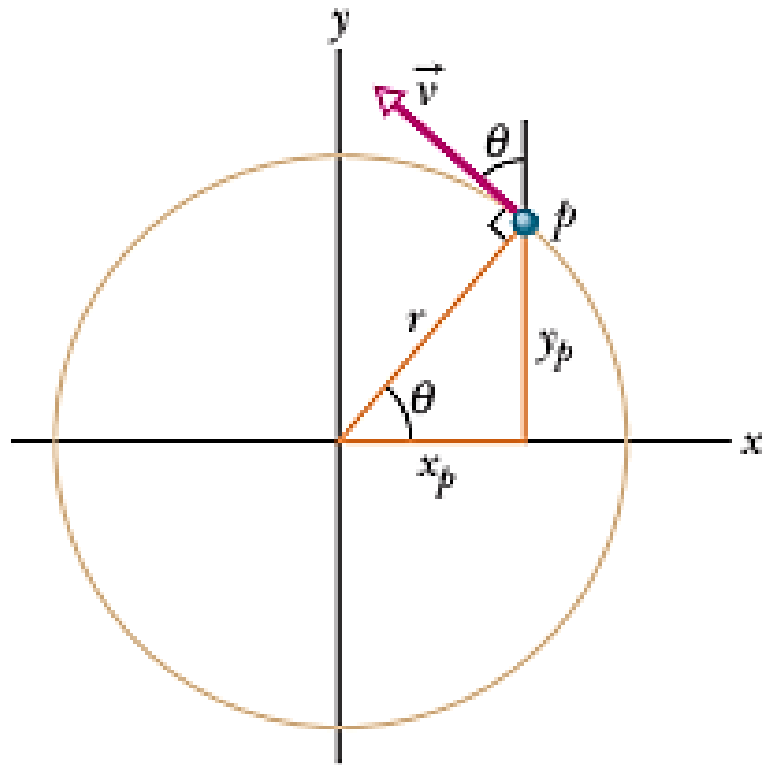
$$a_c = \frac{v^2}{r}$$

Period

$$T = \frac{2\pi r}{v}$$



Uniform Circular Motion



$$\left\{ \begin{array}{l} \vec{r} = x_p \hat{i} + y_p \hat{j} \\ x_p = r \cos \theta \\ y_p = r \sin \theta \end{array} \right.$$

$$\left\{ \begin{array}{l} \vec{v} = v_x \hat{i} + v_y \hat{j} = (-v \sin \theta) \hat{i} + (v \cos \theta) \hat{j} \\ \vec{v} = \left(-\frac{v y_p}{r}\right) \hat{i} + \left(\frac{v x_p}{r}\right) \hat{j} \end{array} \right.$$

$$\vec{a} = \frac{d\vec{v}}{dt} = \left(-\frac{v}{r} \frac{dy_p}{dt}\right) \hat{i} + \left(\frac{v}{r} \frac{dx_p}{dt}\right) \hat{j} \quad \Rightarrow \quad \vec{a} = \left(-\frac{v v_y}{r}\right) \hat{i} + \left(\frac{v v_x}{r}\right) \hat{j} = \left(-\frac{v^2}{r} \cos \theta\right) \hat{i} + \left(-\frac{v^2}{r} \sin \theta\right) \hat{j}$$

$$|\vec{a}| = \sqrt{a_x^2 + a_y^2} = \frac{v^2}{r}$$

$$\tan \phi = \frac{a_y}{a_x} = \frac{-\frac{v^2}{r} \sin \theta}{-\frac{v^2}{r} \cos \theta} = \tan \theta$$

Ex 9:

What is the magnitude of the centripetal acceleration of an object on Earth's equator due to the rotation of Earth?

$$R = 6370 \text{ km} = 6.37 \times 10^6 \text{ m}$$

$$T = 24 \text{ h} = 86400 \text{ s} = 8.64 \times 10^4 \text{ s}$$

$$T = \frac{2\pi R}{v}$$



$$v = \frac{2\pi R}{T} = \frac{2\pi (6.37 \times 10^6)}{(8.64 \times 10^4)} \simeq 463 \text{ (m / s)}$$

$$a_c = \frac{v^2}{R}$$

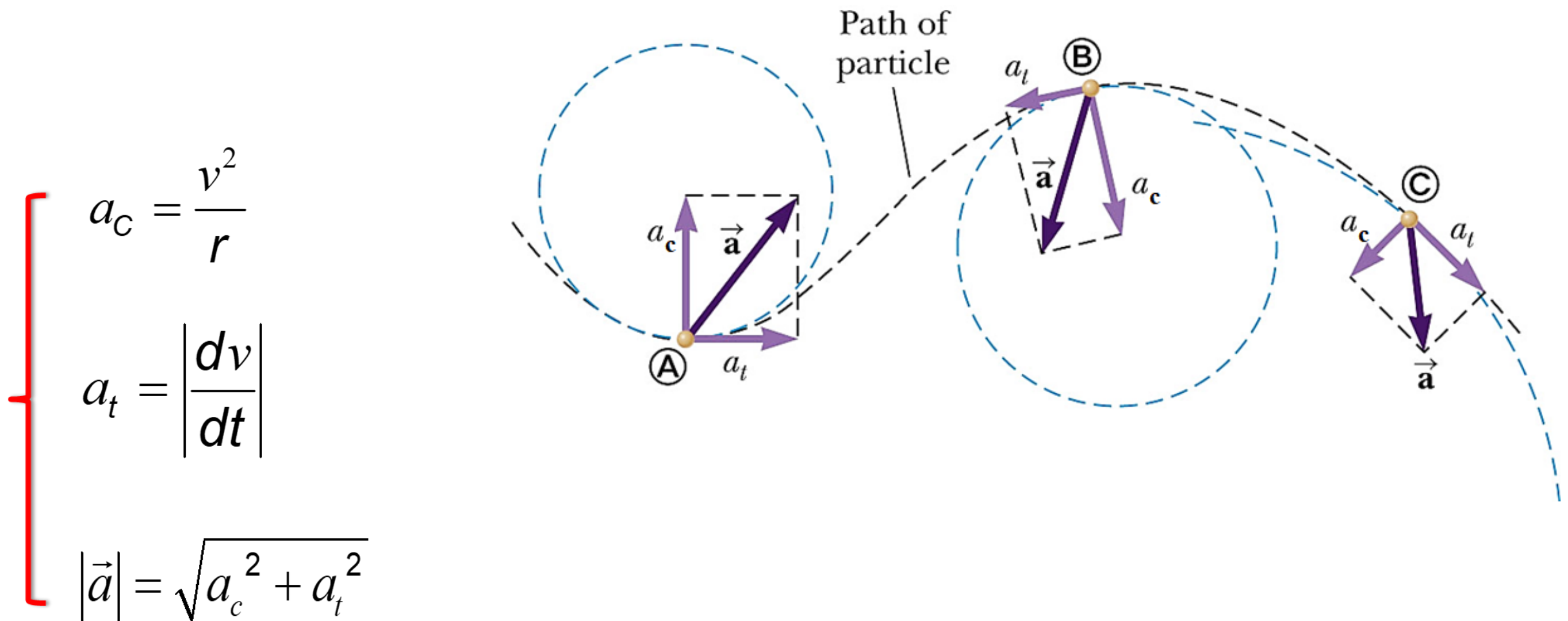


$$a_c = \frac{(463)^2}{6.37 \times 10^6} \simeq 34 \times 10^{-3} \text{ (m / s}^2\text{)}$$

Circular Motion, General

Tangential Acceleration:

- The **centripetal acceleration** comes from a **change in the direction** of the velocity vector.
- The **tangential acceleration** causes the **change in the speed** of the particle.



Ex 10:

A car leaves a stop sign and exhibits a constant acceleration of **0.300 m/s²** parallel to the roadway. The car passes over a rise in the roadway such that the top of the rise is shaped like an arc of a circle of radius **500 m**. At the moment the car is at the top of the rise, its velocity vector is horizontal and has a magnitude of **6.00 m/s**. What are the **magnitude and direction of the total acceleration** vector for the car at this instant?

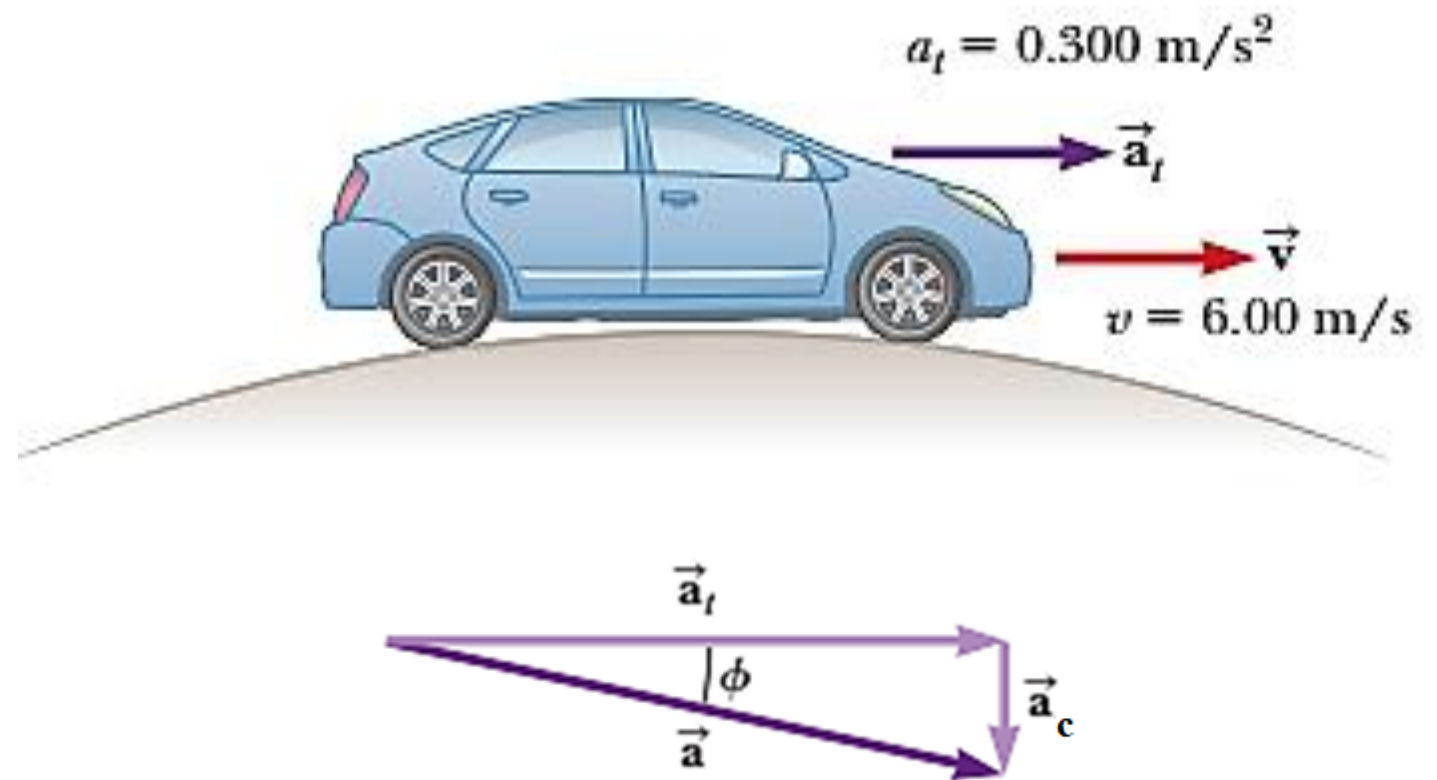
$$a_c = \frac{v^2}{r}$$

➔ $a_c = \frac{(6)^2}{500} = 0.072 \text{ (m / s}^2\text{)}$

$$|\vec{a}| = \sqrt{a_c^2 + a_t^2}$$

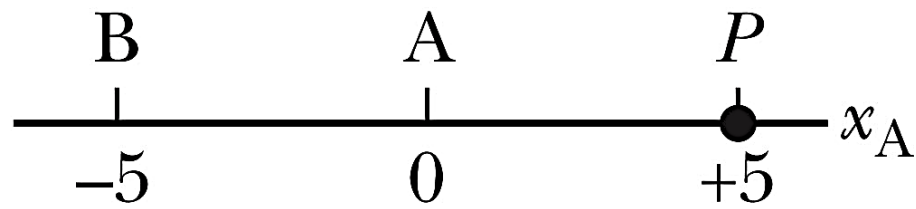
➔ $|\vec{a}| = \sqrt{(0.072)^2 + (0.3)^2} = 0.309 \text{ (m / s}^2\text{)}$

$$\phi = \tan^{-1} \frac{a_c}{a_t} = \tan^{-1} \frac{0.072}{0.3} = 13.5^\circ$$

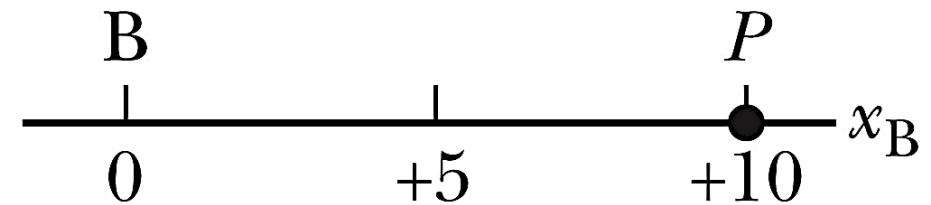
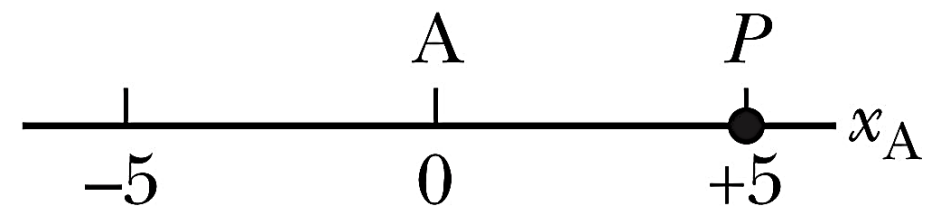


Relative Motion

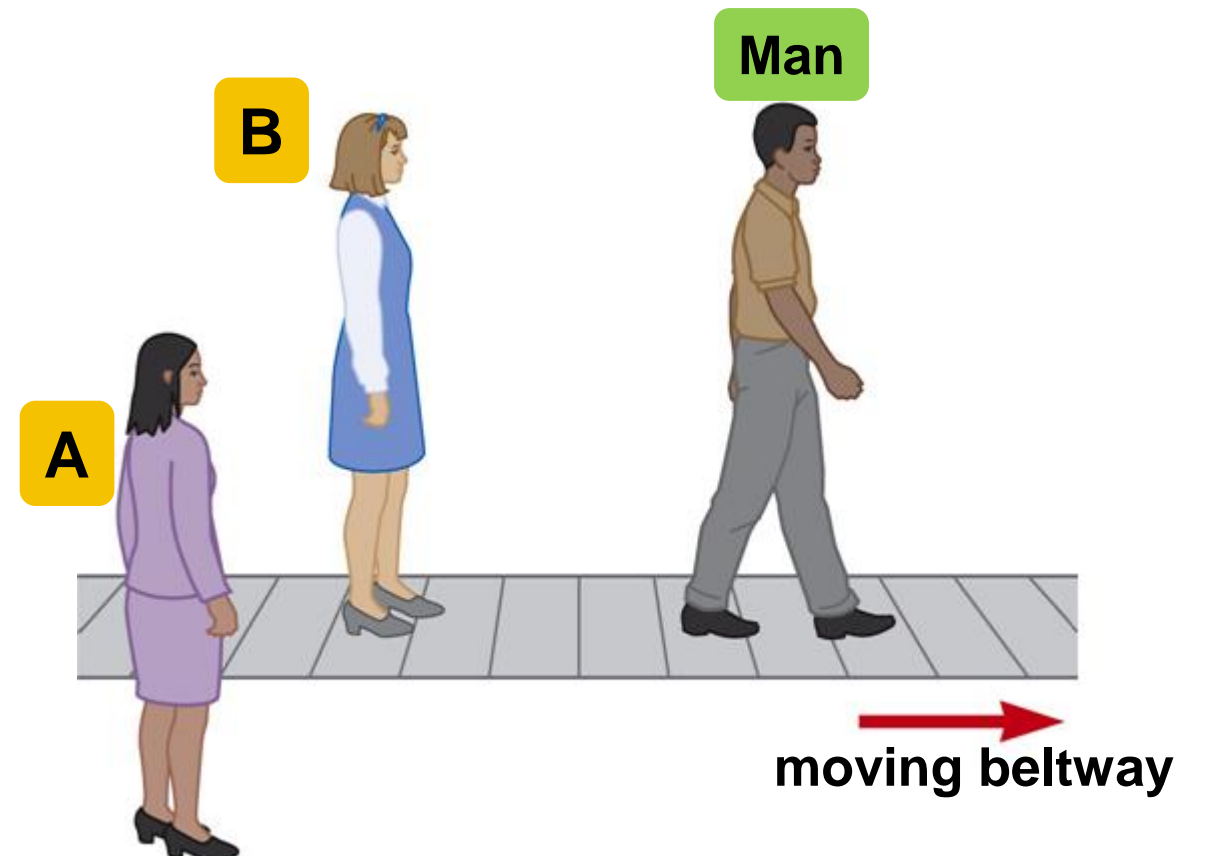
Different measurements due to the different frames of reference:



$$\left\{ \begin{array}{l} x_{pA} = +5m \\ x_{pB} = +10m \end{array} \right.$$



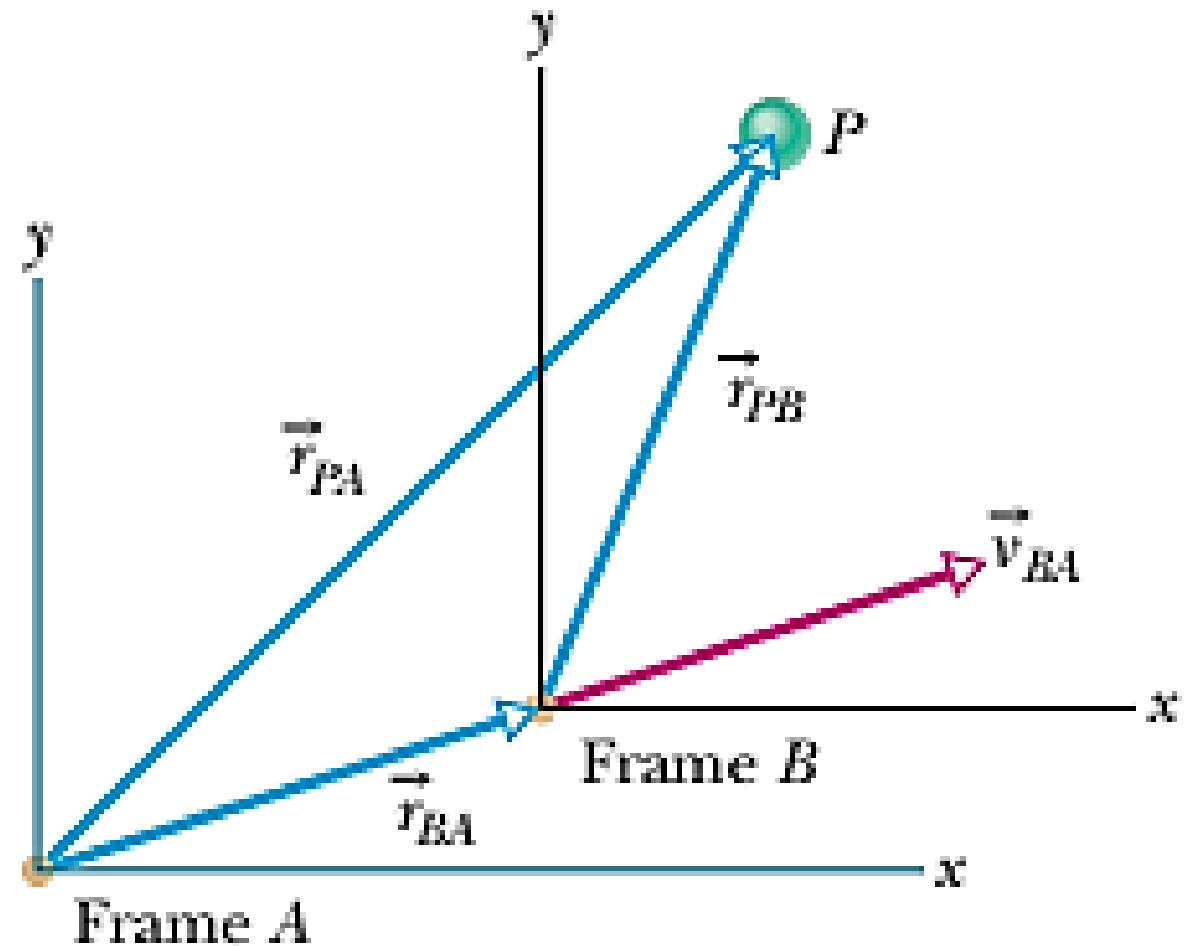
$$v_{MA} > v_{MB}$$



Relative Motion

$$\vec{\mathbf{r}}_{PA} = \vec{\mathbf{r}}_{PB} + \vec{\mathbf{r}}_{BA}$$

$$\frac{d}{dt}(\vec{\mathbf{r}}_{PA}) = \frac{d}{dt}(\vec{\mathbf{r}}_{PB}) + \frac{d}{dt}(\vec{\mathbf{r}}_{BA})$$



$$\vec{\mathbf{v}}_{PA} = \vec{\mathbf{v}}_{PB} + \vec{\mathbf{v}}_{BA}$$

Galilean transformation equations.

$$\frac{d}{dt}(\vec{\mathbf{v}}_{PA}) = \frac{d}{dt}(\vec{\mathbf{v}}_{PB}) + \frac{d}{dt}(\vec{\mathbf{v}}_{BA})$$



$$\vec{\mathbf{a}}_{PA} = \vec{\mathbf{a}}_{PB} + \vec{\mathbf{a}}_{BA}$$

$$\text{if } \vec{\mathbf{v}}_{BA} = \text{constant} \Rightarrow \vec{\mathbf{a}}_{BA} = 0$$



$$\vec{\mathbf{a}}_{PA} = \vec{\mathbf{a}}_{PB}$$

Ex 11: A boat crossing a wide river moves with a speed of **10.0 km/h** relative to the water. The water in the river has a uniform speed of **5.00 km/h** due east relative to the Earth. If the boat heads due north, determine the velocity of the boat relative to an observer standing on either bank.

$$\vec{v}_{bE} = \vec{v}_{br} + \vec{v}_{rE}$$

$$|\vec{v}_{bE}| = \sqrt{|\vec{v}_{br}|^2 + |\vec{v}_{rE}|^2}$$

$$|\vec{v}_{bE}| = \sqrt{(10)^2 + (5)^2} \simeq 11.2 \text{ (km / h)}$$

$$\theta = \tan^{-1} \frac{v_{rE}}{v_{br}} = \tan^{-1} \frac{5}{10} \simeq 26.6^\circ$$

$$\left[\begin{array}{l} |\vec{v}_{bE}| = \sqrt{|\vec{v}_{br}|^2 - |\vec{v}_{rE}|^2} \simeq 8.66 \text{ (km / h)} \\ \varphi = \tan^{-1} \frac{v_{rE}}{v_{bE}} = \tan^{-1} \frac{5}{8.66} = 30^\circ \end{array} \right.$$

