



Farzad Tat Shahdost  
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Doctor of Engineering  
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About

300 Publications  
6,720 Reads ⓘ  
0 Citations

Introduction

Robot stability analysis in Banach space  
(<https://orcid.org/0000-0002-2283-2663>)  
<https://farzadtat.blog.ir/>

Skills and Expertise

MATLAB Simulation

Publications

Publications (300)

Land capability assessment by combining LESA and GIS in a calcareous watershed, Iran

Article

Mar 2022





Mohammad Akbari · Mohammad Tahmoures · Aliasghar Azma · Farzad Tat Shahdost

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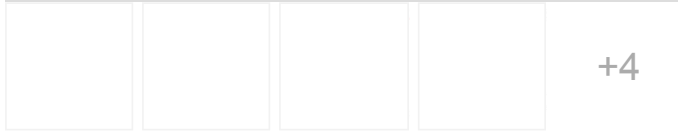
Arti

Feb 2022

 Pooya Pasha ·  Ali Hosin Alibak ·  Hossein Nabi ·  Farzad Tat Shahdost

This study aimed at investigating the variation of heat transfer and velocity changes of the fluid flow along the vertical line on a surface drawn from both sides. In the beginning, several parameters such as Prandtl number and viscoelastic effect were evaluated for heat transfer and fluid velocity by the variation iteration method. The results wer...





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### A universal methodology for reliable predicting the non-steroidal anti-inflammatory drug solubility in supercritical carbon dioxide

[Article](#) [Full-text available](#)

Jan 2022

 Tahereh Rezaei ·  Vesal Nazarpour ·  Nahal Shahini ·  Farzad Tat Shahdost





Understanding the drug solubility behavior is likely the first essential requirement for designing the supercritical technology for pharmaceutical processing. Therefore, this study utilizes different machine learning scenarios to simulate the solubility of twelve non-steroidal anti-inflammatory drugs (NSAIDs) in the supercritical carbon dioxide (SC...

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### A universal methodology for reliable predicting the non-steroidal anti-inflammatory drug solubility in supercritical carbon dioxide

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### Prevalence of depression and its effect on quality of life of medical staff in the prevalence of 19-COVID

[Research](#) [Full-text available](#)

Jan 2022

 masoume\_ahmadi\_14@yahoo.com ·  am.parizi@gmail.com ·  Farzad Tat Shahdost

با توجه به اینکه کارکنان مراقبت های بهداشتی و درمانی در خط اول مبارزه با بیماری های عفونی و بیماری کووید- 91 می باشند اولین کسانی هستند که در معرض آلودگی به این ویروس قرار می گیرند ترس و اضطراب ناشی از ابتلای احتمالی، بار

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بیماری های عفونی و بیماری کووید- 91 می باشند اولین کسانی هستند که در معرض آلودگی به این ویروس قرار می گیرند ترس و اضطراب ناشی از ابتلای احتمالی، بار روانی زیاد و مخربی ایجاد نموده که می تواند منجر به ناهنجاری های روحی و ...روانی، تضعیف سیستم ایمنی و کاهش توان بدن در مبارزه با بیما

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### A theoretical survey on the chlorine dioxide (ClO<sub>2</sub>) and its decomposed species detection by the AlN nanotube in presence of environmental gases

Article

Dec 2021

 Zahra Rahmani ·  Saeed Fosshat ·  Seyed Mehdi Seyed Alizadeh · [...] ·  Abdol Ghaffar Ebadi




The adsorption of N<sub>2</sub>, O<sub>2</sub>, H<sub>2</sub>O, hydrogen chloride (HCl), Cl<sub>2</sub>, hypochlorous acid (HClO), and ClO<sub>2</sub> gases was explored onto an AlN nanotube (AlNNT) through density functional theory computations. As N<sub>2</sub>, O<sub>2</sub>, H<sub>2</sub>O, HCl, Cl<sub>2</sub>, and HClO approach the AlNNT, their adsorption releases 7.1, 12.6, 22.3, 26.5, 30.2, and 41.2 kJ/mol of energy, respectively, indicat...

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### Developing a global approach for determining the molar heat capacity of deep eutectic solvents

Article

Dec 2021

 Ali Bagherzadeh ·  Nahal Shahini ·  Danial Saber · [...] ·  Farzad Tat Shahdost

Deep eutectic solvents (DES) are a new class of green solvents. Reliable characterization of DESs is a prerequisite for their successful applications. The molar heat capacity (C<sub>p</sub>) is likely an essential thermal property often measured through expensive and time-consuming experimentations. Hence, it is necessary to derive an accurate model for C<sub>p</sub> ca...





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### Spirit in Literature and Psychology

Research

Full-text available

Nov 2021

 Rassa Safaei Namin ·  rasol Safaei namin ·  Faezeh Saeidi ·  Farzad Tat Shahdost

Spirit in Literature and Psychology

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کودک دوستدار شهر های شاخص بررسی و مطالعه نمین صفائی رسا

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Nov 2021

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Conference Paper

Full-text available

Oct 2021

Farzad Tat Shahdost

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

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**Numerical investigation fluid velocity and heat transfer on the stretching sheet by VIM method and optimization fluid temperature and velocity parameter by Prandtl number and viscoelastic parameter**

Preprint

Full-text available

Sep 2021

 Pooya Pasha ·  Ali Hosin Alibak ·  Hossein Nabi ·  Farzad Tat Shahdost

This study aimed at investigating the variation of heat transfer and velocity changes of the fluid flow along the vertical line on a surface drawn from both sides. In the beginning, the several parameters such as Prandtl number and viscoelastic effect evaluated for heat transfer and fluid velocity by variation iteration method. The results were com...

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**How is it easier to implement a control system (with a controller)?**

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**Multiple errors in fractional order systems with sliding model Observer How can full order slide control control be detected and identified?**

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**How to identify multiple sensors and actuators of fault tolerant systems? (Objective: To determine single or multiple faults)**

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How to identify multiple sensors and actuators of fault tolerant systems? (Objective: To determine single or multiple faults)

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permissible to accumulate all kinds of environmental or non-environmental noise? Can they be considered as a unit?

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**What is the effect of measuring noise and components of unknown uncertainties on system performance as well as its stability?**

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**If noise is added to the input and output signals of the system, what effect does it have on the controller design for the system?**

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**When does a sudden robot joint failure occur?**

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**How do uncertainties stimulate instability in the system?**

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**In a fault system based on multiple viewers, is it better to design an input rule with interrelated components or several control rules?**

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In a fault system based on multiple viewers, is it better to design an input rule with interrelated components or several control rules?

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**Is the difference between the estimated angular position and the measured angular position called the sensor-actuator error or the error based on the uncertainty of unmodulated dynamics?**

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**Are the error and control variable signals separable (separate isolation and analysis)? (Sensor-actuator signal or sensor-actuator error)**

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**What is the function of sensor error detection sensors in the absence of general uncertainty?**

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How can the nonlinear matrix function of the dynamic model of the control system be expressed in linear form in the parameters?

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**What is the change in the system if we remove at least one of the components of fuzzy maker, non-fuzzy maker, rule base and inference engine in a fuzzy system?**

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What is the change in the system if we remove at least one of the components of fuzzy maker, non-fuzzy maker, rule base and inference engine in a fuzzy system?

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How do we design a robust controller based on linear and nonlinear programming to deal with all kinds of uncertainty?

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**If the zeros and poles of the nonlinear descriptive function are definite positive or semi-definite negative, what changes occur in the system behavior as well as the type and definition of system stability?**

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If the zeros and poles of the nonlinear descriptive function are definite positive or semi-definite negative, what changes occur in the system behavior as well as the type and definition of system stability?

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### How to design a complete sliding model Observer?

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### How are the power-matrix state equations of the control system solvable?

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### How can designed observers minimize the effect of external disturbances on the controlled system?

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### What is the difference between an indeterminate parameter and an uncertainty in a dynamic model?

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### A single multi-input-multi-state second order sliding mode observer How is it designed?

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**If an observer (browser) is designed for a control system, is it considered a separate input, or is the browser input integrated with the system input control rule and a general input for the controlled system?**

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**If any indeterminate parameter (of any degree and with any intensity) exists in the control system, can it be claimed that the system has a structured uncertainty?**

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**How can error thresholds be minimized or false alarms detected? In what cases are these cases undetectable or mis detection?**

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How can error thresholds be minimized or false alarms detected? In what cases are these cases undetectable or mis detection?

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**If we have a structured uncertainty control system, what changes or changes will be achieved in achieving and satisfying finite time stability?**

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If we have a structured uncertainty control system, what changes or changes will be achieved in achieving and satisfying finite time stability?

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**If the errors of a control system in theory converge to zero, what guarantee is there that the same will happen in its implementation?**

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**In a system under study, how do the considered error sensors distinguish the input error from the output error and detect it separately and then converge to zero by the same unit or another unit?**

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In a system under study, how do the considered error sensors distinguish the input error from the output error and detect it separately and then converge to zero by the same unit or another unit?

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**How can not eliminating or minimizing the input error expand the error circle of the state and output variables?**

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**integrated unit, create a problem in the analysis and design of the system?**

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Does not distinguishing between faults caused by the power supply or wiring and considering all of them as an integrated unit, create a problem in the analysis and design of the system?

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What is the difference between a system that is not stable and a system that is unstable? (What are the oscillating, transient and mean states of each)

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**How can the necessary and sufficient stable conditions and the promotion of stability be expressed and separated?**

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**How can the nonlinear (perturbation)turbulence of a strictly nonlinear control system be compensated?**

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**How can the detection, identification of (faults)errors and uncertainties, as well as their isolation from the model, be accomplished through an adaptive fuzzy sliding model observer(viewer)?**

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How and under what conditions can the necessary and sufficient conditions of linear control systems be defined and implemented for nonlinear systems of any degree and difficulty?

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**Can intra-system and extra-system errors be classified into two categories: finite and infinite or definite, definite and indefinite?**

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**Can all concepts of linear control systems be generalized to nonlinear systems?**

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Can all concepts of linear control systems be generalized to nonlinear systems?

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**In a control system, how can unwanted signals, uncertainties and errors be separated?**

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**Can errors due to inaccurate modeling or other types of errors fall into the category of uncertainties or vice versa?**

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Can errors due to inaccurate modeling or other types of errors fall into the category of uncertainties or vice versa?

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If the uncontrolled (or uncontrollable) system is assumed to be nonlinear, how can it be proved that the stable system is asymptotic (or exponential) in Lyapunov's concept(sense)?

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**Conditional Stability -A Comparison for exactly null-controlability-observability How does it make sense?**

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Conditional Stability -A Comparison for exactly null-controlability-observability How does it make sense?

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**How to control a linear uncontrolled system in the Hilbert and Euclidean space?**

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How to control a linear uncontrolled system in the Hilbert and Euclidean space?

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**What does uncontrollable and exactly null- controllable mean?**

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What does uncontrollable and exactly null- controllable mean?

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**What is the connection between the two areas exact null-controllable systems and exponentially stabilizable?**

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What is the connection between the two areas exact null-controllable systems and exponentially stabilizable?

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**What is the difference between the concept of stability and stability for systems with finite temporal-spatial dimensions and the type of infinite dimensions?**

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What is the difference between the concept of stability and stability for systems with finite temporal-spatial dimensions and the type of infinite dimensions?

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**What is the status of the design of advanced controllers for advanced robots?**

Question

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What is the status of the design of advanced controllers for advanced robots?

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If noise is added to the input and output signals of the system, what effect does it have on the controller design for the system?

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**If noise is added to the input and output signals of the system, what effect does it have on the controller design for the system?**

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اگر نویز به سیگنال های ورودی و خروجی سیستم اضافه شود چه تاثیری در طراحی کنترل کننده برای سیستم دارد؟

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**What is the maximum allowable torque for robot corresponding sensors and actuators?**

Question

Sep 2021

What is the maximum allowable torque for robot corresponding sensors and actuators?

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**What is the relationship between exponential stability and the overall exponential stability of a controlled system?**

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What is the relationship between exponential stability and the overall exponential stability of a controlled system?



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**How exponential stability of a controlled system is related to asymptotic stability?**

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How exponential stability of a controlled system is related to asymptotic stability?

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**What is amplitude, dimension, dual, inverse operator as well as auxiliary controller of fuzzy systems?**

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**What is amplitude, dimension, dual, inverse operator as well as auxiliary controller of fuzzy systems?**

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1 Answer

**How do fuzzy mappings take place in metrologically spaced spaces with infinite dimensions?**

Question

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How do fuzzy mappings take place in metrologically spaced spaces with infinite dimensions?

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**How is the multi-input-multi-mode(state) controller designed for follower two-degree-free robots?**

Question

Aug 2021

How is the multi-input-multi-mode(state) controller designed for follower two-degree-free robots?

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**Waste generators are typically (usually) based on the viewer. How does noise and uncertainty ensure the performance of the viewers?**

Question

Aug 2021

Waste generators are typically (usually) based on the viewer. How does noise and uncertainty ensure the performance of the viewers?

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**What is the modeling of actuator and sensor frequency errors (due to the presence of ...)**



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What about modeling errors as an unexpected change in system dynamics or as an unexpected presence of unknown signals?

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How can the actuators of the fault unit be activated while the FD is activated a second time on the sensors?

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**How to design a second-order sliding model viewer with the aim of error detection and isolation?**

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How to design a second-order sliding model viewer with the aim of error detection and isolation?

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Optimal direct adaptive nonlinear controller for three degree freedom robot How is it designed with a gravitational term?

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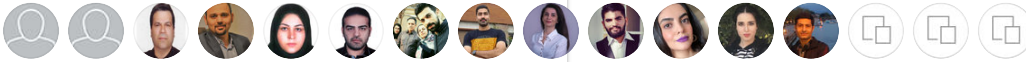
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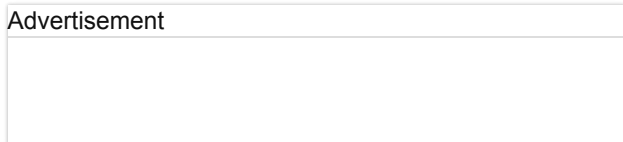
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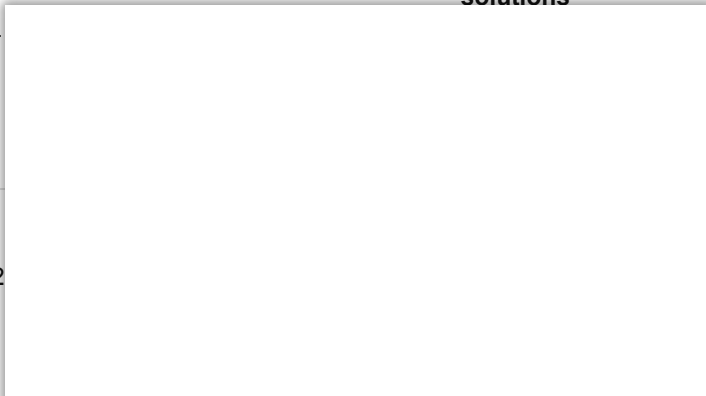
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