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Add new research

Overview Research Experience Stats Scores Following Saved List

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Business card

Your business card is a short summary of your profile which can be displayed to others across the platform.

Business card preview showing name, title, institution, and skills.

About me Edit

Introduction
Robot stability analysis in Banach space
Languages
English
Disciplines
Engineering Education
Skills and expertise
MATLAB Simulation

Stats overview View all

Stats overview cards: 4,031 Research Interest, 0 Citations, 17,380 Recommendations, 4,070 ...

Reads

Current affiliation Edit

Islamic Azad University, Garmсар Branch
Location
Varāmīn, Iran
Department
Department of Electrical and Electronic Engineering
Position
PhD Student
Time period
Feb 2017 - Present

Add missing details about your affiliation

Pooya Pasha's Lab
Lab head
Pooya Pasha
Lab members (5)

Network

Following (2075)
Jimrong Liu
Somak Karan
Abdefattah Elgendy
Followers (937)
Abdefattah Elgendy
Farshad Nadri
Hossein Nabi

Follow researchers with the same skills as you

Sumit Trimukhe
Bhagyashree Karur
Dianne Dhanassar

View more researchers

Top co-authors View all

O.R. Seryasat
Pooya Yousefi
Sareh Sanei

Sina Ahmadi
Ali Hosin Ailbak

Following
Following

Complete your co-author network

rasol Safaei namin
Not on ResearchGate, or hasn't claimed this research yet.

Research

Research overview View all

Research overview cards: 290 Research items, 246 Projects, 70 Questions, 54 Answers

Featured research Edit

Indicators Of Urban Design In Contemporary Trends In The Last Two Decades
Investigating the Role of Lighting in the Security of Citizens
Numerical Investigation fluid velocity and heat transfer on the stretching sheet

24 Reads - 153 Recommendations
Under what conditions is the controller design reduced and how is it done?
September 2021
Farzad Tat Shahdost
36 Reads - 153 Recommendations

Projects

Beiträge zur Disziplin- und Wissenschaftsgeschichte // Educational Science: Contributions to the History of Science and Education
How to prove the complete stability of a state (a linear control system or a linear non-control system)
How do we rewrite the equations of differential and differential (discrete-time) of the system written in Euclidean space and Hilbert space in Banach space?