

$$m v_0 = (m+M) v \rightarrow v = \frac{m v_0}{m+M}$$

$$-v_0^2 = -2\left(\mu g + \frac{\mu m^2 g}{M}\right) x \rightarrow x = \frac{M v_0^2}{2\mu g (m+M)}$$

$$2\left(\mu g + \frac{\mu m g}{M}\right) L = -v_{min}^2 \rightarrow v_{min} = \sqrt{\frac{2\mu g L (m+M)}{M}}$$

(1) نسبت دوم:

$$-v_0 = -\left(\mu g + \frac{\mu m g}{M}\right) t \rightarrow t = \frac{M v_0}{\mu g (m+M)}$$

نسبت اول:

$$L = -\frac{\mu g (m+M)}{2M} t^2 + v_0 t \rightarrow \left(\frac{\mu g (m+M)}{2M}\right) t^2 - v_0 t + L = 0 \rightarrow t = \frac{v_0 \pm \sqrt{v_0^2 - \frac{2\mu g L (m+M)}{M}}}{\frac{\mu g (m+M)}{M}}$$

$$t = \frac{M}{\mu g (m+M)} \left( v_0 - \sqrt{v_0^2 - \frac{2\mu g L (m+M)}{M}} \right)$$

(2)

$$x_2 = \dot{x}_1(t-T) T + x_1(t-T) \rightarrow x_2(t) = a\omega \sqrt{\frac{2h}{g}} \cos(\omega(t-T)) + a \sin(\omega(t-T))$$

$$T = \sqrt{\frac{2h}{g}}, \dot{x}_1(t) = a\omega \cos(\omega t)$$

$$x_2(t) = a\omega \sqrt{\frac{2h}{g}} \cos\left(\omega\left(t - \sqrt{\frac{2h}{g}}\right)\right) + a \sin\left(\omega\left(t - \sqrt{\frac{2h}{g}}\right)\right)$$

$$x_2(t) = a \sqrt{1 + \frac{2\omega^2 h}{g}} \sin\left(\omega\left(t - \sqrt{\frac{2h}{g}}\right) + \tan^{-1}\left(\omega \sqrt{\frac{2h}{g}}\right)\right)$$

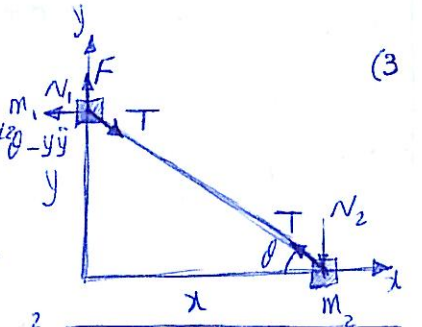
(3)

$$F - T \sin \theta = m_1 \ddot{y} \rightarrow \tan \theta = \frac{m_1 \ddot{y} - F}{m_2 \ddot{x}}$$

$$-T \cos \theta = m_2 \ddot{x}$$

$$\dot{x} \cos \theta = -\dot{y} \sin \theta \rightarrow x \dot{x} = -y \dot{y} \rightarrow \dot{x}^2 + x \ddot{x} = -y \dot{y} - y^2 \rightarrow L \cos \theta \ddot{x} + v_0^2 = -v_0^2 \cot^2 \theta - y \dot{y}$$

$$\rightarrow \ddot{x} = -\dot{y} \tan \theta - \frac{v_0^2}{L \cos \theta \sin^2 \theta} \rightarrow \frac{\sin \theta}{\cos \theta} \left( \dot{y} \frac{\sin \theta}{\cos \theta} + \frac{v_0^2}{L \cos \theta \sin^2 \theta} \right) = \frac{F - m_1 \ddot{y}}{m_2}$$



$$\ddot{y} \tan^2 \theta + \frac{v_0^2}{L \sin \theta \cos^2 \theta} = \frac{F}{m_2} - \frac{m_1}{m_2} \ddot{y} \rightarrow \ddot{y} \left( \frac{m_2 \tan^2 \theta + m_1}{m_2} \right) = \frac{F L \cos^2 \theta \sin \theta - m_1 v_0^2}{m_2 L \cos^2 \theta \sin \theta}$$

$$\ddot{y} = \frac{F L \cos^2 \theta \sin \theta - m_1 v_0^2}{\sin \theta (m_1 + m_2 \tan^2 \theta) L \cos^2 \theta}$$

$$\ddot{x} = \frac{-F \sin \theta}{(m_1 + m_2 \tan^2 \theta) \cos \theta} + \frac{m_2 v_0^2}{(m_1 + m_2 \tan^2 \theta) L \cos^3 \theta} - \frac{v_0^2}{L \cos \theta \sin^2 \theta}$$

$$\ddot{x} = \frac{m_2 v_0^2 \sin^2 \theta - F L \sin^3 \theta \cos^2 \theta - (m_1 + m_2 \tan^2 \theta) \cos^2 \theta v_0^2}{(m_1 + m_2 \tan^2 \theta) L \sin^2 \theta \cos^3 \theta}$$

$$\ddot{x} = \frac{F L \sin^5 \theta + m_1 v_0^2}{(m_1 + m_2 \tan^2 \theta) L \sin^2 \theta \cos \theta}$$

$$T = \frac{m_2 (F L \sin^3 \theta + m_1 v_0^2)}{(m_1 + m_2 \tan^2 \theta) L \sin^2 \theta \cos \theta}$$

$$\theta = \frac{\pi}{6}$$

$$T = \frac{2 m_2 (F L + 8 m_1 v_0^2)}{(3 m_1 + m_2) L}$$



ایستادن

$$\ddot{x} = -\frac{\sqrt{3}(FL + 8m_1v_0)}{(3m_1 + m_2)L}$$

$$\ddot{y} = \frac{3FL - 8m_2v_0^2}{(3m_1 + m_2)L}$$

این سوال بدون داشتن  $v_0$  هم قابل حل شود.

حالت اول:

$$Mg \sin \alpha + N_1 \sin \theta - T(\cos \theta + \sin \theta) = MA$$

$$T \cos \gamma - m_2 g \cos \alpha = m_2 \ddot{y}_2$$

$$T \sin \gamma + m_2 g \sin \alpha - m_2 A = m_2 \ddot{x}_2$$

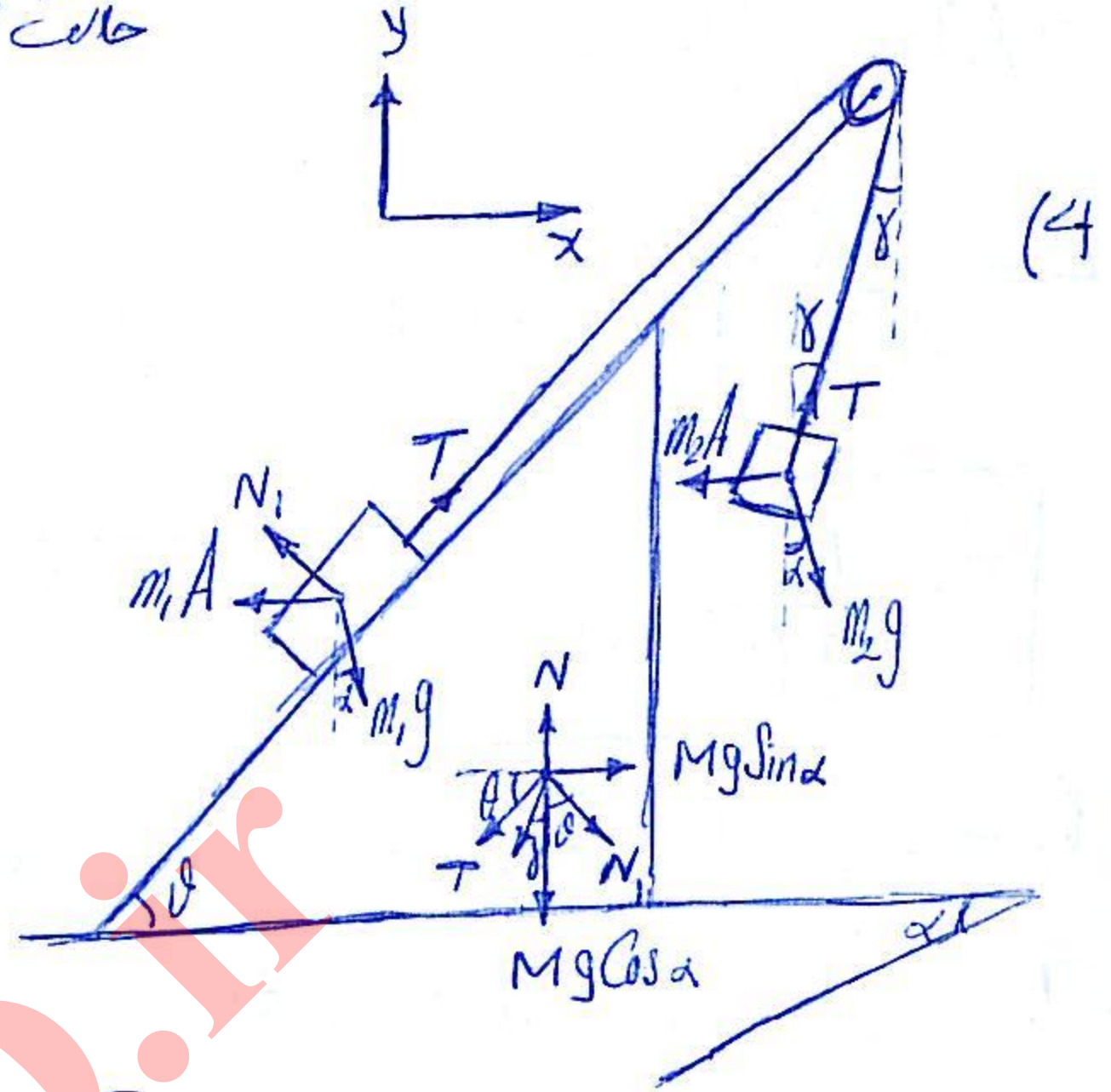
$$T \sin \theta + N_1 \cos \theta - m_1 g \cos \alpha = m_1 \ddot{y}_1$$

$$T \cos \theta - N_1 \sin \theta - m_1 A - m_1 g \sin \alpha = m_1 \ddot{x}_1$$

$$\ddot{y}_1 = \ddot{x}_1 \tan \theta$$

$$\ddot{y}_1^2 + \ddot{x}_1^2 = \ddot{y}_2^2 + \ddot{x}_2^2$$

$$\ddot{x}_2 = \ddot{y}_2 \tan \gamma$$



حالت دوم:

$$Mg \sin \alpha - N_2 - T \cos \theta + N_1 \sin \theta = MA$$

$$T - m_2 g \cos \alpha = m_2 \ddot{y}_2$$

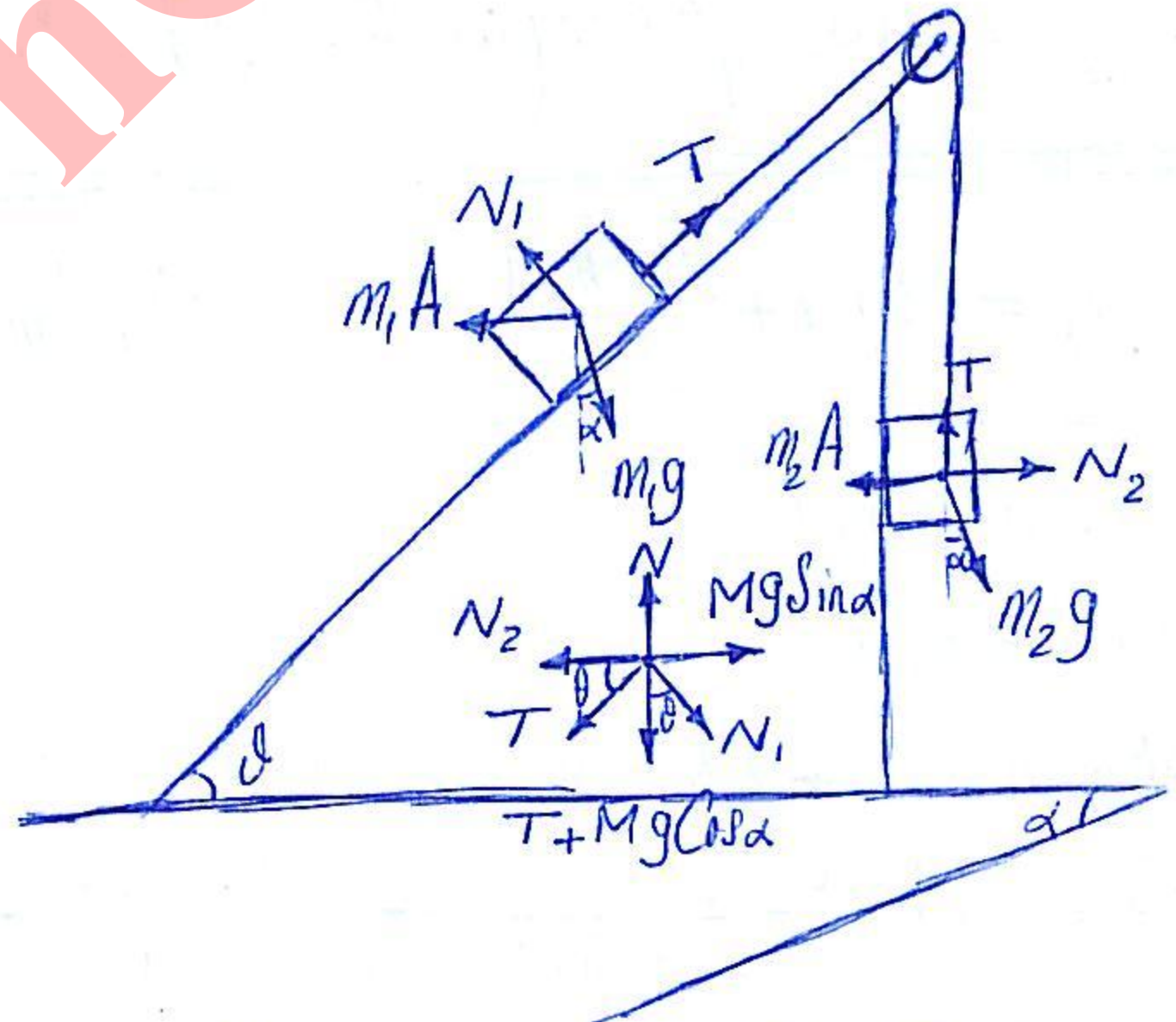
$$N_2 + m_2 g \sin \alpha = m_2 A$$

$$T \sin \theta + N_1 \cos \theta - m_1 g \cos \alpha = m_1 \ddot{y}_1$$

$$T \cos \theta - N_1 \sin \theta - m_1 A + m_1 g \sin \alpha = m_1 \ddot{x}_1$$

$$\ddot{y}_1 = \ddot{x}_1 \tan \theta$$

$$\ddot{y}_2^2 = \ddot{x}_1^2 + \ddot{y}_1^2$$



ایستادن دوم - استادن 87 - دوره 21

$$Q_{in} = 4\pi\rho_0 \int_0^a \left(1 - \frac{r^2}{a^2}\right) r^2 dr = 4\pi\rho_0 \left(\frac{a^3}{3} - \frac{a^3}{5}\right) \rightarrow Q_{in} = \frac{8\pi\rho_0 a^3}{15}$$

(الف)

$$E_{out} = \frac{Q_{in}}{\epsilon_0 \times 4\pi r^2} \rightarrow E_{out} = \left(\frac{2\rho_0 a^3}{15\epsilon_0}\right) \left(\frac{1}{r^2}\right)$$

(ب)

(ج)

(د)

$$dV_0 = \rho_0 (1 - r^2) \times 4\pi r^2 dr \times \frac{1}{r^2} \rightarrow V_0 = \frac{\rho_0 a^2}{2} \left(\frac{1}{2} - \frac{1}{4}\right) \rightarrow V_0 = \frac{\rho_0 a^2}{16}$$



$$x = (c+1) \sqrt{\frac{z_0^2(1+c^2+2c)}{4(1-c)^2} + \frac{z_0^2(1+c^2-2c)}{(1+c)^2}} - z_0 \cdot l + \left[ \frac{l(c+1)}{2} + z_0(1-c) \right]$$

$$x = (c+1) \sqrt{\left( \frac{l(1+c)}{2(1-c)} - \frac{z_0(1-c)}{(1+c)^2} \right)^2} + \left[ \frac{l}{2}(c+1) + z_0(1-c) \right] = \frac{l(c+1)}{2} \left( 1 + \frac{c+1}{1-c} \right) = \frac{l(1+c)}{-c+1} \rightarrow \boxed{x = \frac{l(e^{\frac{2V_0}{2kq}} + 1)}{-e^{\frac{2V_0}{2kq}} + 1}}$$

$$\rightarrow x = \frac{l(1+e^{\frac{2V_0}{2kq}})}{(e^{\frac{2V_0}{2kq}} - 1)} = l \frac{e^{\frac{2V_0}{2kq}} + 1}{e^{\frac{2V_0}{2kq}} - 1} \rightarrow \boxed{x = l \coth\left(\frac{2V_0}{2kq}\right)}$$

$$dF = \frac{kq_1q_2}{l_1l_2d} \left( \frac{\frac{l_1}{2} - x_2}{\sqrt{d^2 + (\frac{l_1}{2} - x_2)^2}} dx_2 + \frac{\frac{l_1}{2} + x_2}{\sqrt{d^2 + (\frac{l_1}{2} + x_2)^2}} dx_2 \right) \rightarrow F = \frac{kq_1q_2}{2l_1l_2d} \left( - \int \frac{d(d^2 + (\frac{l_1}{2} - x_2)^2)}{\sqrt{d^2 + (\frac{l_1}{2} - x_2)^2}} + \int \frac{d((\frac{l_1}{2} + x_2)^2 + d^2)}{\sqrt{d^2 + (\frac{l_1}{2} + x_2)^2}} \right)$$

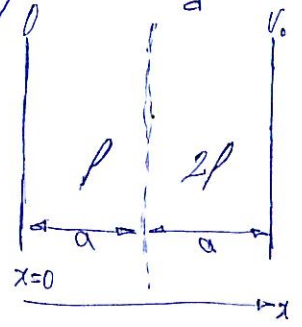
$$\rightarrow F = \frac{kq_1q_2}{l_1l_2d} \left( \int_{\frac{l_1}{2}}^{-\frac{l_1}{2}} \frac{1}{\sqrt{d^2 + (\frac{l_1}{2} - x_2)^2}} dx_2 + \int_{-\frac{l_1}{2}}^{\frac{l_1}{2}} \frac{1}{\sqrt{d^2 + (\frac{l_1}{2} + x_2)^2}} dx_2 \right) \rightarrow \boxed{F = \frac{2kq_1q_2}{l_1l_2d} \left( \sqrt{d^2 + (\frac{l_1+l_2}{2})^2} - \sqrt{d^2 + (\frac{l_1-l_2}{2})^2} \right)}$$

$$F = \frac{2kq_1q_2}{l_1l_2d} \left( \sqrt{l_2^2 + 2l_1l_2} - \sqrt{l_2^2 - 2l_1l_2} \right) = \frac{kq_1q_2}{l_1d} \left( 1 + \frac{l_1}{l_2} - 1 + \frac{l_1}{l_2} \right) \rightarrow \boxed{F = \frac{2kq_1q_2}{l_2d}}$$

$$F = \frac{2kq_1q_2}{l_1l_2} \left( \sqrt{1 + \left(\frac{l_1+l_2}{2d}\right)^2} - \sqrt{1 + \left(\frac{l_1-l_2}{2d}\right)^2} \right) \rightarrow F = \frac{2kq_1q_2}{l_1l_2} \left( \frac{2(2l_1l_2 + 2l_1l_2)}{2 \times 4d^2} \right) \rightarrow F = \frac{kq_1q_2}{d^2}$$

$$V.E_s \begin{cases} \frac{\rho}{\epsilon_0} & 0 < x < a \\ \frac{2\rho}{\epsilon_0} & a < x < 2a \\ 0 & x < 0 \text{ or } x > 2a \end{cases}$$

$$\rightarrow E = \begin{cases} \frac{\rho}{\epsilon_0}x + A & 0 < x < a \\ \frac{2\rho}{\epsilon_0}x + B & a < x < 2a \\ C & x < 0 \\ D & x > 2a \end{cases}$$



شرایط مرزی: 1)  $V_{(0)} = 0 \rightarrow 2) V_{(2a)} = V_0$  3)  $V_{(a)} = V_{(a)}$  4)  $V_{(a)} = V_{(a)}$  5)  $V_{(a)} = V_{(a)}$

$$V = \begin{cases} \frac{\rho x^2}{2\epsilon_0} + Ax + A' & 0 < x < a \\ \frac{\rho x^2}{\epsilon_0} + Bx + B' & a < x < 2a \\ Cx + C' & x < 0 \\ Bx + B' & x > 2a \end{cases}$$

مسئله ۱

$$v_{(x)} = -a \cos \theta + u, v_{(y)} = -a \sin \theta \rightarrow \begin{cases} v_y = -u \sin \theta \\ v_x = u(1 - \cos \theta) \end{cases}$$

$$\begin{cases} v_{(r)} = -u(1 - \cos \theta) \\ v_{\theta} = -u \sin \theta \end{cases}$$

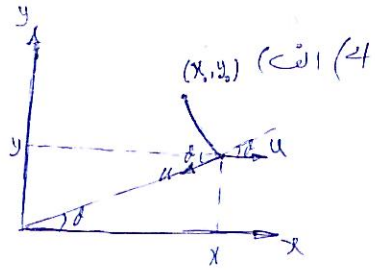
$$\frac{dr}{r d\theta} = \frac{1 - \cos \theta}{\sin \theta} \rightarrow \int \frac{dr}{r} = \int \frac{d \cos \theta}{1 - \cos \theta} - \int \frac{d \sin \theta}{\sin \theta} \rightarrow \ln\left(\frac{r}{r_0}\right) = \left| \tan \frac{\theta}{2} \right| - \ln(\sin \theta)$$

$$\rightarrow \ln\left(\frac{r}{r_0}\right) = -\frac{1}{2} \ln\left(\frac{(1 - \cos \theta)(1 + \cos \theta)}{(1 + \cos \theta)(1 - \cos \theta)}\right) - \ln\left(\frac{\sin \theta}{\sin \theta_0}\right) \rightarrow r = r_0 \frac{\sin \theta_0}{\sin \theta} \sqrt{\frac{(1 - \cos \theta)(1 + \cos \theta_0)}{(1 - \cos \theta_0)(1 + \cos \theta)}}$$

$$\frac{r}{r_0} = \frac{\sin \theta_0}{\sin \theta} \times \frac{(1 + \cos \theta_0)}{\sin \theta_0} \times \frac{\sin \theta}{1 + \cos \theta} \rightarrow r_{(x)} = r_0 \frac{(1 + \cos \theta_0)}{1 + \cos \theta}$$

$$\dot{r}_{(x)} = r_0 (1 + \cos \theta_0) \times \frac{\sin \theta}{(1 + \cos \theta)^2} \times \frac{d\theta}{dt} = -u(1 - \cos \theta) \rightarrow dt = -\frac{r_0 (1 + \cos \theta_0)}{u} \frac{\sin \theta}{(1 + \cos \theta)^2 (1 - \cos \theta)} d\theta = -\frac{r_0 (1 + \cos \theta_0)}{u} \frac{d\theta}{(1 + \cos \theta) \sin \theta}$$

$$\approx -\frac{r_0 (1 + \cos \theta_0)}{u} \frac{1 + \frac{\theta^2}{4}}{2\theta} \rightarrow t \approx -\frac{r_0 (1 + \cos \theta_0)}{2u} \times \left( \ln\left(\frac{\theta}{\alpha}\right) + \frac{\theta^2}{8} \right), \quad \theta \rightarrow 0, \alpha \ll 1 \rightarrow t = \infty$$



1)  $F_{(x)} = N \sin \alpha = mg \sin \alpha \cos \alpha = ma_{(x)} \rightarrow v_{(x)} = (g \sin \alpha \cos \alpha) t$ ,  $t_1 = \sqrt{\frac{2ab}{g \sin \alpha \cos \alpha}}$ ,  $v_{(x) \text{ max}} = \sqrt{2ga} \cos \alpha$  (سوال 5)

2)  $0 \leq t \leq \sqrt{\frac{2a}{g}} : v_{(x)} = 0$ ,  $\sqrt{\frac{2a}{g}} \leq t \leq \frac{b+2a}{\sqrt{2ag}} : v_{(x)} = \sqrt{2ag}$

3)  $0 \leq t < 2\sqrt{\frac{a}{g}} : v_{(x)} = 0$ ,  $2\sqrt{\frac{a}{g}} \leq t \leq \sqrt{\frac{2a}{g}} \left( \sqrt{2} + \frac{1-\sqrt{2}}{\sin \alpha} \right) : v_{(x)} = (2\sqrt{ag} - g \sin \alpha t) \cos \alpha$

$$-g \sin \alpha \cos \alpha t' = \sqrt{2ag} \cos \alpha - 2\sqrt{ag} \cos \alpha \rightarrow t' = \frac{\sqrt{2ag} (1 - \sqrt{2})}{g \sin \alpha} = \sqrt{\frac{2a}{g}} \frac{1 - \sqrt{2}}{\sin \alpha} \rightarrow t_3 = \sqrt{\frac{2a}{g}} \left( \sqrt{2} + \frac{1 - \sqrt{2}}{\sin \alpha} \right)$$

$$T_2 = \frac{b+2a}{\sqrt{2ag}}$$

3)  $v_{(x)} = (2\sqrt{ag} (1 + \sin \alpha) - g \sin \alpha t) \cos \alpha$

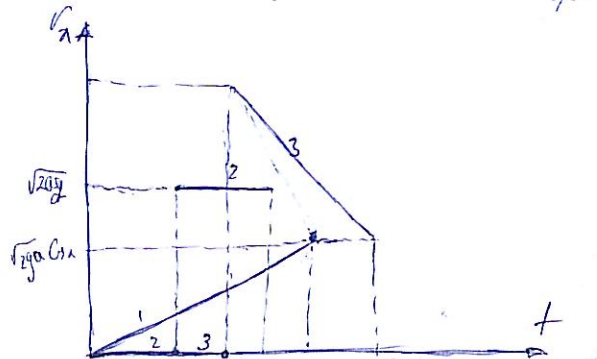
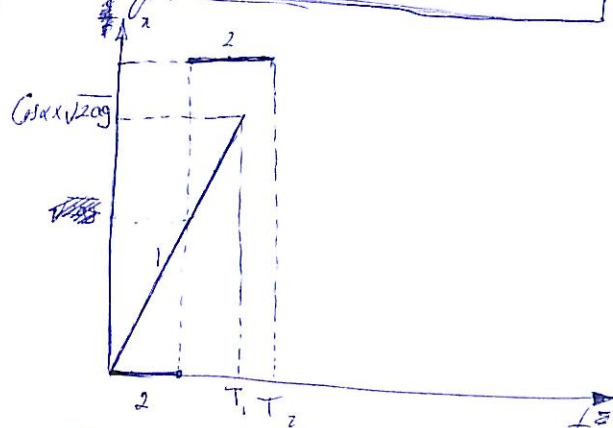
$$\sin \alpha = \frac{a}{\sqrt{a^2 + b^2}}, \cos \alpha = \frac{b}{\sqrt{a^2 + b^2}}$$

1)  $v_{(x)} = \frac{gab}{a^2 + b^2} t$

$$v_{(x)} = \left( 2\sqrt{ag} \left( 1 + \frac{a}{\sqrt{a^2 + b^2}} \right) - \frac{ag}{\sqrt{a^2 + b^2}} t \right) \times \frac{b}{\sqrt{a^2 + b^2}} \rightarrow v_{(x)} = \frac{\sqrt{2ag} b}{a^2 + b^2} \left( 2(\sqrt{a^2 + b^2} + a) - \sqrt{ag} t \right)$$

$$T_3 = \sqrt{\frac{2a}{g}} \left( \sqrt{2} + \frac{(1 - \sqrt{2}) \sqrt{a^2 + b^2}}{a} \right)$$

$$T_1 = \sqrt{\frac{2(a^2 + b^2)}{2ag}}$$





بسته نغان

تاسان 87 - آرگون دوم - حردی ای

$$\frac{1}{r^2} \frac{\partial (r^2 E_{in})}{\partial r} = \frac{\rho_0}{\epsilon_0} (1 - \frac{r^2}{a^2}) \rightarrow r^2 E_{in} = \frac{\rho_0 r^3}{\epsilon_0} (\frac{1}{3} - \frac{r^2}{5a^2}) \rightarrow E_{in} = \frac{\rho_0 r}{\epsilon_0} (\frac{1}{3} - \frac{r^2}{5a^2}) \quad (1)$$

$$V_{in} - V_0 = - \int_0^r \frac{\rho_0}{\epsilon_0} (\frac{r}{3} - \frac{r^3}{5a^2}) dr \rightarrow V_{in} = \frac{\rho_0 a^2}{4\epsilon_0} - \frac{\rho_0 r^2}{\epsilon_0} (\frac{1}{6} - \frac{r^2}{20a^2}) \rightarrow V_{in} = \frac{\rho_0}{\epsilon_0} (\frac{a^2}{4} - \frac{r^2}{6} + \frac{r^4}{20a^2}) \quad (2)$$

$$V_{out} - V_a = - \int_a^r E_{out} dr \rightarrow V_{out} = \frac{\rho_0 a^2}{\epsilon_0} (\frac{1}{4} - \frac{1}{6} + \frac{1}{20}) + \frac{2\rho_0 a^3}{15\epsilon_0} (\frac{1}{r} - \frac{1}{a}) \rightarrow V_{out} = (\frac{2\rho_0 a^3}{15\epsilon_0}) \frac{1}{r} \quad (3)$$

$\frac{\partial E_{in}}{\partial r} = 0 \rightarrow \frac{1}{3} = \frac{3r^2}{5a^2} \rightarrow r = \frac{a\sqrt{5}}{3}$

(و) در خارج از میدان بر حسب r نازل است. پس  $E_{in}$  در داخل کروی رخ می دهد

$$E_{(a)} = \frac{2\rho_0 a}{15\epsilon_0} \rightarrow E_{(a)} = \frac{2 \times 5 \times 10^{23} \times 3.4 \times 10^{-5}}{15 \times 8.85 \times 10^{-12}} \rightarrow E_{(a)} = \frac{2 \times 34 \times 10^{31}}{3 \times 885} \rightarrow E_{(a)} = \frac{2 \times 884 \times 10^{31}}{3 \times 26 \times 885} \rightarrow E_{(a)} \approx \frac{2 \times 10^{31}}{39} \quad (4)$$

$$E_{(a)} \approx 0.25 \times 10^{30} \rightarrow E_{(a)} \approx 2.5 \times 10^{29}$$

$$V_{(a)} = \frac{2\rho_0 a^2}{15\epsilon_0} \rightarrow V_{(a)} \approx \frac{34 \times 10^{-6} \times 10^{31}}{39} \rightarrow V_{(a)} = \frac{272 \times 7 \times 10^{25}}{8 \times 273} \rightarrow V_{(a)} \approx \frac{7}{8} \times 10^{25} \rightarrow V_{(a)} \approx \frac{7 \times 5^3}{10^3} \times 10^{25} \rightarrow V_{(a)} \approx 8.7 \times 10^{24}$$

$$Q_{in} = \frac{8\pi \rho_0 a^3}{15} \rightarrow Q_{in} = \frac{2\rho_0 a^2}{15\epsilon_0} 4\pi a \epsilon_0 \rightarrow Q_{in} = 8.7 \times 10^{24} \times 4 \times 3.1 \times 3.4 \times 10^{-5} \times 8.85 \times 10^{-12}$$

$$Q_{in} = 87 \times 4 \times 31 \times 34 \times 885 \times 10^2 \rightarrow Q_{in} = 90 \times 2 \times 30 \times 30 \times 180 \times 10^3 \rightarrow Q_{in} \approx 2.9 \times 10^{10}$$

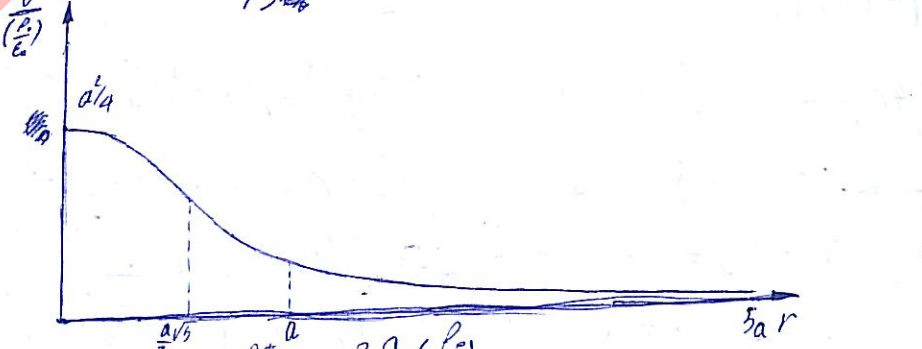
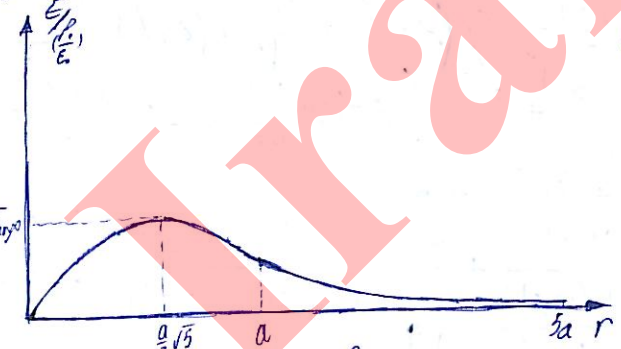
$$V_0 = \frac{\rho_0 a^2}{4\epsilon_0} \rightarrow V_0 = (\frac{2\rho_0 a^2}{15\epsilon_0}) \times \frac{15}{8} \rightarrow V_0 = \frac{15}{8} V_{(a)} \rightarrow V_0 \approx 1.9 V_{(a)} \rightarrow V_0 \approx 1.6 \times 10^{25}$$

$$E = \begin{cases} \frac{\rho_0}{\epsilon_0} \left( \frac{r}{3} - \frac{r^3}{5a^2} \right) & r < a, \left( \frac{\epsilon_0}{\rho_0} \right) \frac{\partial E}{\partial r} = \frac{1}{3} - \frac{3r^2}{5a^2} \\ \frac{2\rho_0 a^3}{15r^2} & r > a, \left( \frac{\epsilon_0}{\rho_0} \right) \frac{\partial E}{\partial r} = -\frac{3r}{5a^2} \end{cases}$$

$$V = \begin{cases} \frac{\rho_0}{\epsilon_0} \left( \frac{a^2}{4} - \frac{r^2}{6} + \frac{r^4}{20a^2} \right) & r < a, \left( \frac{\epsilon_0}{\rho_0} \right) \frac{\partial V}{\partial r} = \frac{r^3}{5a^2} - \frac{r}{3} \\ \left( \frac{2\rho_0 a^3}{15\epsilon_0} \right) \frac{1}{r} & r > a, \left( \frac{\epsilon_0}{\rho_0} \right) \frac{\partial V}{\partial r} = -\frac{1}{r} + \frac{3r^2}{5a^2} \end{cases} \quad (C)$$

$$\left( \frac{\epsilon_0}{\rho_0} \right) E_{(a)} = \frac{2a}{375}$$

$$\left( \frac{\epsilon_0}{\rho_0} \right) V_{(a)} = \frac{2a^2}{75\epsilon_0}$$



$$r = a^- : \frac{\partial E}{\partial r} = \frac{1}{3} - \frac{3r^2}{5a^2} = \frac{1}{3} - \frac{3}{5} = -\frac{4}{15} \left( \frac{\rho_0}{\epsilon_0} \right)$$

$$r = a^+ : \frac{\partial E}{\partial r} = -\frac{3r}{5a^2} = -\frac{3}{5} \left( \frac{\rho_0}{\epsilon_0} \right)$$

$$r = 0 : \frac{\partial E}{\partial r} = \frac{1}{3}, E = 0$$

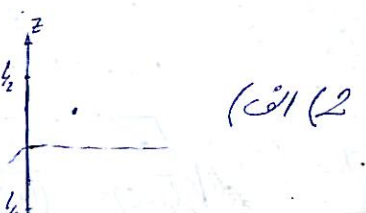
$$r = a^- : \frac{\partial V}{\partial r} = -\frac{2a}{15} \left( \frac{\rho_0}{\epsilon_0} \right)$$

$$r = a^+ : \frac{\partial V}{\partial r} = -\frac{2a}{15} \left( \frac{\rho_0}{\epsilon_0} \right)$$

$$r = 0 : \frac{\partial V}{\partial r} = 0, V = \frac{a^2}{4} \left( \frac{\rho_0}{\epsilon_0} \right)$$

$$\frac{dE_z}{dz} = -k\lambda dx \frac{(\lambda - z)}{(\rho^2 + (\lambda - z)^2)^{3/2}}, \rho^2 + (\lambda - z)^2 = a^2$$

$$dE_p = \frac{k\lambda dx \cdot \rho}{(\rho^2 + (\lambda - z)^2)^{3/2}}, \lambda - z = u$$





دائرة

$$dv = \frac{k\lambda dx}{\sqrt{(x-z)^2 + \rho^2}} = k\lambda \frac{d(x-z)}{\sqrt{(x-z)^2 + \rho^2}} \rightarrow v = \frac{-kq/n \left( (-\frac{l}{2} - z) + \sqrt{\rho^2 + (z + \frac{l}{2})^2} \right)}{l \left( (\frac{l}{2} - z) + \sqrt{\rho^2 + (\frac{l}{2} - z)^2} \right)}$$

$$\int dE_z = \frac{-k\lambda da}{2 \int a^{3/2}} \rightarrow E_z = \frac{kq}{l} \left( \frac{1}{\sqrt{\rho^2 + (\frac{l}{2} - z)^2}} - \frac{1}{\sqrt{\rho^2 + (\frac{l}{2} + z)^2}} \right)$$

$$dE_\rho = k\lambda \rho \frac{du}{[\rho^2 + u^2]^{3/2}} \rightarrow E_\rho = \frac{kq}{l\rho^2} \left[ \frac{u}{\sqrt{\rho^2 + u^2}} \right]_{-\frac{l}{2}-z}^{\frac{l}{2}-z} \rightarrow E_\rho = \frac{kq}{l\rho^2} \left( \frac{\frac{l}{2}-z}{\sqrt{\rho^2 + (\frac{l}{2}-z)^2}} + \frac{z+\frac{l}{2}}{\sqrt{\rho^2 + (z+\frac{l}{2})^2}} \right)$$

$$\vec{E} = \frac{kq}{l} \left[ \frac{1}{\rho^2} \left( \frac{\frac{l}{2}-z}{\sqrt{\rho^2 + (\frac{l}{2}-z)^2}} + \frac{\frac{l}{2}+z}{\sqrt{\rho^2 + (z+\frac{l}{2})^2}} \right) \hat{\rho} + \left( \frac{1}{\sqrt{\rho^2 + (\frac{l}{2}-z)^2}} - \frac{1}{\sqrt{\rho^2 + (\frac{l}{2}+z)^2}} \right) \hat{z} \right]$$

$$E_\rho = 0 \rightarrow \vec{E} = \frac{kq}{l} \left( \frac{1}{\sqrt{(\frac{l}{2}-z)^2}} - \frac{1}{\sqrt{(z+\frac{l}{2})^2}} \right) \hat{z} \rightarrow \vec{E} = \begin{cases} \frac{kq}{l} \frac{2z}{\frac{l^2}{4} - z^2} & |z| < \frac{l}{2} \\ \frac{kq}{l} \frac{l}{z^2 - \frac{l^2}{4}} & |z| > \frac{l}{2} \end{cases}$$

$$\vec{E} = \begin{cases} \frac{2kqz}{l(\frac{l^2}{4} - z^2)} & |z| < \frac{l}{2} \\ \frac{kq}{z^2 - \frac{l^2}{4}} & |z| > \frac{l}{2} \end{cases}$$

$$e^{-\frac{1}{c}} = \frac{(z+\frac{l}{2}) + \sqrt{\rho^2 + (z+\frac{l}{2})^2}}{(\frac{l}{2}-z) + \sqrt{\rho^2 + (\frac{l}{2}-z)^2}} = c \rightarrow (z+\frac{l}{2}) + c(\frac{l}{2}-z) = c\sqrt{\rho^2 + (\frac{l}{2}-z)^2} - \sqrt{\rho^2 + (z+\frac{l}{2})^2}$$

$$(z+\frac{l}{2})^2 + c^2(\frac{l}{2}-z)^2 + 2c(\frac{l^2}{4}-z^2) = c^2\rho^2 + c^2(\frac{l}{2}-z)^2 + \rho^2 + (z+\frac{l}{2})^2 - 2c\sqrt{(\rho^2 + (\frac{l}{2}-z)^2)(\rho^2 + (z+\frac{l}{2})^2)}$$

$$4c^2\rho^2 + 4c^2(\frac{l^2}{4}-z^2) + 4c^2\rho^2(2z+\frac{l}{2}) = \rho^2 + c^2\rho^2 + 4c^2(\frac{l^2}{4}-z^2) + 2c^2\rho^2 - 24c\rho^2(\frac{l}{2}-z) - 4c^3\rho^2(\frac{l}{2}-z)$$

$$\rho^2(1-c^2)^2 + 4c^2z^2(1-c)^2 = c^2l^2(1+c)^2 \rightarrow \frac{\rho^2(1-c)^2(1+c)^2}{4c(1-c)^2(1+c)^2} + \frac{4c^2z^2(1-c)^2}{4c(1-c)^2(1+c)^2} = \frac{c^2l^2(1+c)^2}{4c(1-c)^2(1+c)^2}$$

$$\rightarrow \left( \frac{\rho}{2\sqrt{c}} \right)^2 + \left( \frac{z}{1+c} \right)^2 = \left( \frac{l}{2(1-c)} \right)^2 \rightarrow \left( \frac{\rho}{2e^{-\frac{1}{c}}\sqrt{c}} \right)^2 + \left( \frac{z}{1+e^{-\frac{1}{c}}} \right)^2 = \left( \frac{l}{2(1-e^{-\frac{1}{c}})} \right)^2$$

$$= \sqrt{\rho^2 + (z+\frac{l}{2})^2} + \sqrt{\rho^2 + (\frac{l}{2}-z)^2} = (c+1)\sqrt{\rho^2 + (\frac{l}{2}-z)^2} + \left[ c(\frac{l}{2}-z) + (z+\frac{l}{2}) \right]$$

$$\rho^2 = \frac{c^2l^2(1+c)^2 - 4c^2z^2(1-c)^2}{(1+c)^2(1-c)^2} \rightarrow \rho^2 = \frac{cl^2}{(1-c)^2} - \frac{4cz^2}{(1+c)^2}$$

$$= (c+1)\sqrt{\frac{cl^2}{(1-c)^2} - \frac{4cz^2}{(1+c)^2} + \frac{l^2}{4} + z^2 - z \cdot l} + \left[ c(\frac{l}{2}-z) + (z+\frac{l}{2}) \right]$$



$$m v_0 \leq (m_1 + m) v_{10} \rightarrow \left[ v_{10} \leq \frac{m}{m_1 + m} v_0 \right], \left[ v_{20} \leq 0 \right]$$

ب) حالت کلی:

$$\left\{ \begin{aligned} m v_0 &\leq (m_1 + m + m_2) v \\ m v_0^2 &\leq (m_1 + m + m_2) v^2 + k d^2 \end{aligned} \right. \rightarrow \left( m - \frac{m^2}{m_1 + m + m_2} \right) v_0^2 \leq k d^2 \rightarrow v_{max} \leq d \sqrt{\frac{k(m_1 + m_2 + m)}{m_1(m_1 + m_2)}}$$

ج)  $\left\{ \begin{aligned} -k \Delta x &\leq m_2 \ddot{x}_2 \\ k \Delta x &\leq m_1 \ddot{x}_1 \end{aligned} \right. \rightarrow m_1 \ddot{x}_1 + m_2 \ddot{x}_2 \leq 0 \rightarrow m_1 \dot{x}_1 + m_2 \dot{x}_2 \leq m v_0 \rightarrow m_1 x_1 + m_2 x_2 \leq m v_0 t \rightarrow \left[ m_1' \leq m_1 + m \right]$

د)  $\Delta x \leq (x_2 + d) - x_1 \rightarrow \Delta x \leq x_2 - x_1$

$$\rightarrow k x_2 - k x_1 = (m_1 + m) \ddot{x}_1 \rightarrow \frac{k m v_0}{m_2} t = k x_1 \left( 1 + \frac{m_1 + m}{m_2} \right) + (m_1 + m) \dot{x}_1$$

$$\ddot{x}_1 + \frac{k(m_2 + m_1 + m)}{m_2(m_1 + m)} x_1 \leq \frac{k m v_0}{m_2(m_1 + m)} t \rightarrow x_1 = A \sin(\omega t + \phi) + \gamma t, t=0: x_1=0 \rightarrow \phi=0$$

$$x_1 = A \sin(\omega t) + \gamma t, t=0: \dot{x}_1 = \frac{m v_0}{m_1 + m} \rightarrow \dot{x}_1 = A \omega \cos(\omega t) + \gamma \rightarrow \frac{m v_0}{m_1 + m} \leq A \omega + \gamma$$

$$\left[ \frac{1}{\sqrt{k(m_2 + m_1 + m)}} + \frac{m v_0}{m_2 + m_1 + m} \leq \frac{m v_0}{m_1 + m} \right] \rightarrow A \leq \sqrt{\frac{m_2}{k(m_1 + m)(m_1 + m_2 + m)}} \frac{m m_2 v_0}{m_1 + m_2 + m}$$

$$x_1 = \frac{m v_0}{m_1 + m_2 + m} \left( \frac{m_2}{\sqrt{k(m_1 + m)(m_1 + m_2 + m)}} \sin\left(\sqrt{\frac{k(m_1 + m_2 + m)}{m_2(m_1 + m)}} t\right) + t \right)$$

$$x_2 = \frac{-m(m_1 + m_2) v_0}{m_1 + m_2 + m} \sqrt{\frac{m_2}{k(m_1 + m)(m_1 + m_2 + m)}} \sin\left(\sqrt{\frac{k(m_1 + m_2 + m)}{m_2(m_1 + m)}} t\right) - \frac{m(m_1 + m) v_0}{m_2(m_1 + m_2 + m)} t + \frac{m v_0}{m_2} t$$

$$x_2 = \frac{m v_0}{m_1 + m_2 + m} \left( t - \sqrt{\frac{m_2(m_1 + m)}{k(m_1 + m_2 + m)}} \sin\left(\sqrt{\frac{k(m_1 + m_2 + m)}{m_2(m_1 + m)}} t\right) \right)$$

ز:  $\dot{x}_1 = \dot{x}_2 \rightarrow \dot{x}_1 = \frac{m v_0}{m_1 + m_2 + m}, \dot{x}_1 = \frac{m v_0}{m_1 + m_2 + m} \left( \frac{m_2}{m_1 + m} \cos\left(\sqrt{\frac{k(m_1 + m_2 + m)}{m_2(m_1 + m)}} t\right) + 1 \right)$

$$\cos\left(\sqrt{\frac{k(m_1 + m_2 + m)}{m_2(m_1 + m)}} t\right) \leq 0 \rightarrow t = \frac{\pi}{2} \sqrt{\frac{m_2(m_1 + m)}{k(m_1 + m_2 + m)}}$$

$m_2 \geq m_1 + m$   $t_1: \dot{x}_1 = 0 \rightarrow t_1 \leq \sqrt{\frac{m_2(m_1 + m)}{k(m_1 + m_2 + m)}} \cos^{-1}\left(\frac{m_1 + m}{m_2}\right), \dot{x}_1 = 0 \rightarrow \dot{x}_2 = \frac{m}{m_2} v_0 \rightarrow v_{2(t_1)}$

2-  $x_1 = -d \rightarrow \frac{m v_0}{m_1 + m_2 + m} \sqrt{\frac{m_2}{k(m_1 + m)(m_1 + m_2 + m)}} (m_2 + m_1 + m) \sin\left(\sqrt{\frac{k(m_1 + m_2 + m)}{m_2(m_1 + m)}} \frac{t}{2}\right) = d \rightarrow t = t_2$



استمرارية

$$\sin\left(\sqrt{\frac{k(m_1+m_2+m)}{m_2(m_1+m)}} t\right) = \frac{d}{m v_0} \sqrt{\frac{k(m_1+m)(m_1+m_2+m)}{m_2}} \rightarrow t_2 = \sqrt{\frac{m_2(m_1+m)}{k(m_1+m_2+m)}} \sin^{-1}\left(\frac{d}{m v_0} \sqrt{\frac{k(m_1+m)(m_1+m_2+m)}{m_2}}\right)$$

$$m v_0 \leq (m_1+m+m_2) v_0' \rightarrow v_0' \leq \frac{m}{m_1+m_2+m} v_0$$

$$x_1 = a \sin((t-t_2)\omega + \varphi') + \delta(t-t_2) + b, \quad t=t_2: x_1 = b \rightarrow \varphi' = 0$$

$$t=t_2: \dot{x}_1 = \frac{m}{m_1+m_2+m} v_0 \rightarrow a\omega + \delta = \frac{m}{m_1+m_2+m} v_0$$

$$a = \frac{1}{\sqrt{\frac{k(m_1+m_2+m)}{m_2(m_1+m)}}} \left( \frac{m}{m_1+m_2+m} v_0 - \delta \right)$$

$$\begin{cases} -k\Delta x = m_2 \ddot{x}_2 \\ k\Delta x = m_1 \ddot{x}_1 \end{cases} \rightarrow \begin{cases} m_1 \ddot{x}_1 + m_2 \ddot{x}_2 = 0 \\ (m_1+m) \dot{x}_1 + m_2 \dot{x}_2 = m v_0 T \end{cases}$$

$$x_2' = \frac{m v_0 T - (m_1+m) x_1'}{m_2}, \quad \Delta x = (x_2' + l - d) - x_1' - l \rightarrow \Delta x = x_2' - x_1' - d$$

$$k x_1' - k d + \frac{k m v_0 T}{m_2} - \frac{k(m_1+m) x_1'}{m_2} = (m_1+m) \ddot{x}_1 \rightarrow \ddot{x}_1 + \frac{k(m_1+m_2+m)}{m_2(m_1+m)} x_1' = \frac{k m v_0 T}{m_2(m_1+m)} - \frac{k d}{m_1+m}$$

$$\rightarrow x_1' = a \sin(\omega T + \varphi') + \delta T - \frac{k d}{(m_1+m)\omega^2}$$

$$T=0: x_1' = 0 \rightarrow a \sin \varphi' = \frac{k d}{(m_1+m)\omega^2} \rightarrow a = \frac{k d}{(m_1+m)\omega^2} \rightarrow a = \frac{m_2}{m_1+m+m_2} d$$

$$T=0: \dot{x}_1 = v_0' \rightarrow a \cos \varphi' + \delta' = v_0' \rightarrow \cos \varphi' = 0 \rightarrow \varphi' = \frac{\pi}{2}, \quad \delta' = v_0' = \frac{m}{m_1+m_2+m} v_0$$

$$\rightarrow x_1' = \frac{m_2}{m_1+m+m_2} d \cos(\omega T) + \frac{m}{m_1+m_2+m} v_0 T - \frac{m_2}{m_1+m+m_2} d$$

$$x_1 = \frac{1}{m_1+m+m_2} \left( m_2 d (\cos(\omega(t-t_2)) - 1) + m v_0 (t-t_2) \right) + x_1(t_2)$$

$$x_2' = \frac{m v_0 T}{m_2} + \frac{(m_1+m) d}{m_1+m_2+m} (1 - \cos(\omega T)) - \frac{(m_1+m) m v_0}{m_2(m_1+m_2+m)} T$$

$$x_2 = \frac{1}{m_1+m+m_2} \left( (m_1+m) d (1 - \cos(\omega(t-t_2))) + m v_0 (t-t_2) \right) + x_2(t_2)$$

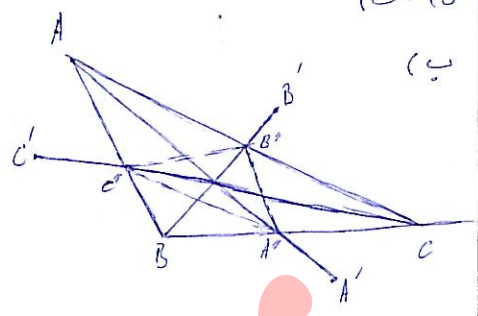
$$x_{1(t_2)} = \frac{m v_0}{m_1+m_2+m} \left( \frac{m_2 d}{m v_0} + \sqrt{\frac{m_2(m_1+m)}{k(m_1+m_2+m)}} \sin^{-1}\left(\frac{d}{m v_0} \sqrt{\frac{k(m_1+m)(m_1+m_2+m)}{m_2}}\right) \right)$$

$$x_{2(t_2)} = \frac{m v_0}{m_1+m_2+m} \left( \sqrt{\frac{m_2(m_1+m)}{k(m_1+m_2+m)}} \sin^{-1}\left(\frac{d}{m v_0} \sqrt{\frac{k(m_1+m)(m_1+m_2+m)}{m_2}}\right) - \frac{(m_1+m) d}{m v_0} \right)$$



(3 الف)

$\frac{AC'}{BC'} = \frac{AB'}{B'C'} = 1 \rightarrow C'B' \parallel BC$   $\xrightarrow{\text{وزج}}$   $ABC' \sim ABC$   $\xrightarrow{\text{ترتيب}}$   
 $ABC' \cong A'C'B \cong C'AB'$

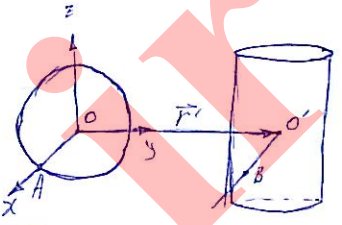


(ب)

$\phi_0 = \frac{\phi_0}{2} + \frac{\phi_{B'}}{2} + \frac{\phi_{A'}}{2} + \frac{\phi_{C'}}{2} \rightarrow \boxed{\phi_{A'} + \phi_{B'} + \phi_{C'} = \phi_0}$

$\vec{E}_{os} \times 2\pi r \times h = \frac{\rho \times \pi R^2 h}{\epsilon_0} \rightarrow \vec{E}_{os} = \left(\frac{\rho R^2}{2\epsilon_0}\right) \frac{\vec{r}}{r^2}$ ,  $\epsilon_{ic} = \frac{4}{3} \pi r^3 \times \frac{\rho}{\epsilon_0} \times \frac{1}{4\pi r^2} \rightarrow \vec{E}_{ic} = \frac{\rho \vec{r}}{3\epsilon_0}$

$\epsilon_{is} \times 2\pi r \times h = \frac{\rho \pi r^2 h}{\epsilon_0} \rightarrow \vec{E}_{is} = \left(\frac{\rho}{2\epsilon_0}\right) \vec{r}$ ,  $\epsilon_{oc} \times 4\pi r^2 = \frac{4\pi \rho R^3}{3\epsilon_0} \rightarrow \vec{E}_{oc} = \left(\frac{\rho R^3}{3\epsilon_0}\right) \frac{\vec{r}}{r^3}$



(4)

$\vec{E}_{ics} = \vec{E}_{os} + \vec{E}_{ic} = \left(\frac{\rho}{3\epsilon_0}\right) (\vec{x} + \vec{y} + \vec{z}) + \left(\frac{\rho R^2}{2\epsilon_0}\right) \frac{\vec{x} + \vec{y} - \vec{r}'}{(\vec{y} - \vec{r}')^2 + \vec{x}^2} \rightarrow \boxed{\vec{E}_{ics} = \frac{\rho}{\epsilon_0} \left( \frac{\vec{r}}{3} + \frac{R^2 (\vec{x} + (\vec{y} - 4R)\vec{j})}{2(x^2 + (\vec{y} - 4R)^2)} \right)}$

الف) برهم نهی کنیم.

$\vec{E}_{ocs} = \vec{E}_{oc} + \vec{E}_{os} = \left(\frac{\rho R^3}{3\epsilon_0}\right) \frac{\vec{r}}{r^3} + \frac{\rho R^2}{2\epsilon_0} \frac{\vec{x} + \vec{y} - \vec{r}'}{(\vec{y} - \vec{r}')^2 + \vec{x}^2} \rightarrow \boxed{\vec{E}_{ocs} = \frac{\rho R^2}{\epsilon_0} \left( \frac{R\vec{r}}{3r^3} + \frac{\vec{x} + (\vec{y} - 4R)\vec{j}}{2(x^2 + (\vec{y} - 4R)^2)} \right)}$

(ب)

$\vec{E}_{isc} = \vec{E}_{oc} + \vec{E}_{is} = \left(\frac{\rho R^3}{3\epsilon_0}\right) \frac{\vec{r}}{r^3} + \left(\frac{\rho}{2\epsilon_0}\right) \vec{r} \rightarrow \boxed{\vec{E}_{isc} = \frac{\rho}{\epsilon_0} \left( \frac{R^3 \vec{r}}{3r^3} + \frac{\vec{x} + (\vec{y} - 4R)\vec{j}}{2} \right)}$

(ج)

$V_A - V_B = - \int_0^R \vec{E}_{ic} \cdot d\vec{y} = - \frac{\rho R^2}{\epsilon_0} \left( \frac{R}{3} \int_0^R \frac{y dy}{(x^2 + y^2)^{3/2}} + \frac{1}{2} \int_0^R \frac{(y-4R) dy}{(x^2 + (y-4R)^2)} \right) = - \frac{\rho R^2}{\epsilon_0} \left( \frac{R}{3} \left[ \frac{1}{\sqrt{x^2 + y^2}} \right]_0^R - \frac{1}{4} \ln(x^2 + (y-4R)^2) \right) \rightarrow$

(د)

$V_A - V_B = - \frac{\rho R^2}{\epsilon_0} \left( \frac{R}{3} \left( \frac{1}{R} - \frac{1}{R\sqrt{17}} \right) + \frac{1}{4} \ln\left(\frac{R^2}{17R^2}\right) \right) \rightarrow \boxed{V_A - V_B = - \frac{\rho R^2}{\epsilon_0} \left( \frac{\sqrt{17} - 1}{3\sqrt{17}} - \frac{\ln(17)}{4} \right)}$

$V_0 - V_{0'} = - \int \vec{E}_{ics} \cdot d\vec{y} + \int \vec{E}_{ocs} \cdot d\vec{y} + \int \vec{E}_{isc} \cdot d\vec{y} = - \frac{\rho}{\epsilon_0} \left( \frac{1}{3} \int_0^R y dy + \frac{R^2}{2} \int_0^R \frac{dy}{y-4R} + \frac{R^2}{3} \int_0^R \frac{dy}{y^2} + \frac{R^2}{2} \int_0^R \frac{dy}{y-4R} + \frac{R^3}{3} \int_0^R \frac{dy}{y^2} + \frac{1}{2} \int_0^R (y-4R) dy \right) \rightarrow$

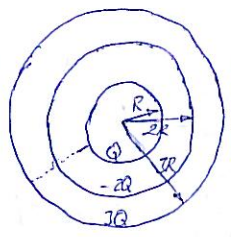
(ه)

$= - \frac{\rho}{\epsilon_0} \left( \frac{R^2}{6} + \frac{R^2}{2} \ln\left(\frac{3}{4}\right) + \frac{R^3}{3} \left( \frac{1}{R} - \frac{1}{3R} \right) + \frac{R^2}{2} \ln\left(\frac{1}{3}\right) + \frac{R^3}{3} \left( \frac{1}{3R} - \frac{1}{4R} \right) + \frac{1}{4} (-R^2) \right) = - \frac{\rho R^2}{\epsilon_0} \left( \frac{1}{6} + \frac{2}{9} + \frac{1}{36} - \frac{1}{4} + \frac{\ln\left(\frac{1}{4}\right)}{2} \right) \rightarrow$

$V_0 - V_{0'} = - \frac{\rho R^2}{\epsilon_0} \left( \frac{6+8+1-9}{36} - \ln(2) \right) \rightarrow \boxed{V_0 - V_{0'} = - \frac{\rho R^2}{\epsilon_0} \left( \frac{1}{6} - \ln(2) \right)}$

$\vec{E} = \begin{cases} 0 & r < R \\ \frac{kQ}{r^2} & R < r < 2R \\ -\frac{kQ}{r^2} & 2R < r < 3R \\ \frac{2kQ}{r^2} & 3R < r < \infty \end{cases}$  (الف)  $V_{(R)} = \frac{kQ}{R} - \frac{2kQ}{2R} + \frac{3kQ}{3R} \rightarrow \boxed{V_{(R)} = \frac{kQ}{R}}$   
 $V_{(2R)} = \frac{kQ}{2R} - \frac{2kQ}{2R} + \frac{3kQ}{3R} \rightarrow \boxed{V_{(2R)} = \frac{kQ}{2R}}$   
 $V_{(3R)} = \frac{kQ}{3R} + \frac{3kQ}{3R} \rightarrow \boxed{V_{(3R)} = \frac{2kQ}{3R}}$

(ب)



(5)

$U = \frac{1}{2} \cdot \frac{kQ^2}{R} \left( (-1+1) - 2 \times \left( \frac{1}{2} + 1 \right) + 3 \left( -\frac{1}{3} \right) \right) = \frac{kQ^2}{2R} \times (-3-1) \rightarrow \boxed{U = -\frac{4kQ^2}{R}}$

(ج)

$q_1 + q_2 = 4Q \rightarrow \boxed{q_2 = \frac{7}{2} Q}$   $\xrightarrow{\text{وحدت}}$   $\frac{Q}{18} = \frac{q_{12}}{9} \rightarrow \boxed{q_{12} = \frac{Q}{2}} \rightarrow \boxed{q_{02} = 3Q}$

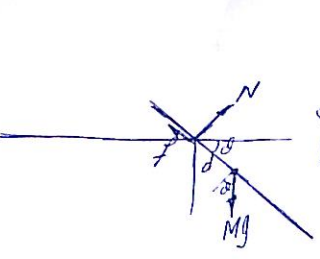
(د)

$\frac{q_1}{3R} - \frac{2Q}{2R} + \frac{q_2}{R} = \frac{q_1}{3R} - \frac{2Q}{3R} + \frac{q_2}{3R} \rightarrow \frac{Q}{3} = \frac{2q_1}{3} \rightarrow \boxed{q_1 = \frac{Q}{2}} \rightarrow \boxed{q_{11} = 0}, \boxed{q_{01} = \frac{Q}{2}}$

$U = \frac{kQ^2}{2R} \left( \left( \frac{7}{2} - 1 \right) + \left( \frac{1}{4} + 1 \right) \times -2 + 3 \left( -\frac{3}{2} \right) \right) \rightarrow U = \frac{kQ^2}{2R} \cdot \frac{1-15-9}{6} \rightarrow \boxed{U = -\frac{25kQ^2}{12R}}$

(ه)





$$Mgd \sin \theta = \frac{1}{2} I \dot{\theta}^2 \rightarrow \omega^2 = \frac{2Mgd \sin \theta}{I}$$

$$I = \int r^2 dm = \frac{M}{3L} \int_{L/2-d}^{L/2+d} r^3 = \frac{M}{3L} \left[ 2d \left( \frac{L^2}{2} + 2d^2 + \frac{L^2}{4} - d^2 \right) \right] \rightarrow I = \frac{4Md}{3L} \left( d^2 + \frac{3L^2}{2} \right)$$

$$\omega^2 = \frac{2Mgd \sin \theta}{\frac{4Md}{3L} \left( d^2 + \frac{3L^2}{2} \right)} \rightarrow \omega^2 = \frac{129L \sin \theta}{2d^2 + 3L^2} \rightarrow \omega = \sqrt{\frac{129L \sin \theta}{2d^2 + 3L^2}}$$

$$Mg \cos \theta - N = M d \ddot{\theta} \rightarrow N = M \left( g \cos \theta - \frac{69Ld \cos \theta}{2d^2 + 3L^2} \right) \rightarrow N = \frac{Mg \cos \theta (2d^2 + 3L^2 - 6Ld)}{2d^2 + 3L^2}$$

$$Mg d \cos \theta \dot{\theta} = I \dot{\theta} \ddot{\theta} \rightarrow \ddot{\theta} = \frac{Mg d \cos \theta}{\frac{4Md}{3L} (2d^2 + 3L^2)} \rightarrow \ddot{\theta} = \frac{69L \cos \theta}{2d^2 + 3L^2}$$

$$f = Mg \sin \theta + M \omega^2 d \rightarrow f = Mg \sin \theta \left( 1 + \frac{12Ld}{2d^2 + 3L^2} \right) \rightarrow Mg \sin \theta (2d^2 + 3L^2 + 12Ld) = \mu Mg \cos \theta (2d^2 + 3L^2 - 6Ld)$$

$$\tan \theta_0 = \mu \frac{3L^2 + 2d^2 - 6Ld}{2d^2 + 3L^2 + 12Ld}$$

$$2T_0 \sin \theta_0 = M \omega^2 R_{cm} \rightarrow T_0 = \frac{M \omega^2 R_{cm}}{2 \sin \theta_0}$$

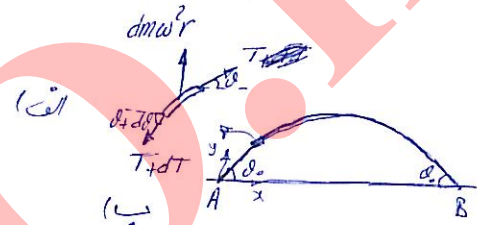
$$-d T_{\theta} = dm \omega^2 r$$

$$dT_{\theta} = 0 \rightarrow T \cos \theta = T_0 \cos \theta_0 \rightarrow T = \frac{T_0 \cos \theta_0}{\cos \theta}$$

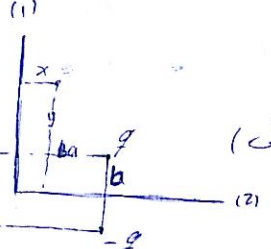
$$-T_0 \cos \theta_0 d(\tan \theta) = \frac{M \omega^2}{L} ds_x r \rightarrow -T_0 \cos \theta_0 \frac{\sin \theta d\theta}{\cos^2 \theta} = \frac{M \omega^2}{L} r dr \rightarrow r^2 = \frac{2LT_0 \cos \theta_0}{M \omega^2} \left( \frac{1}{\cos \theta_0} - \frac{1}{\cos \theta} \right)$$

$$\frac{1}{\cos^2 \theta} = 1 - \frac{\cos \theta_0}{\cos \theta} \rightarrow \frac{\cos \theta_0}{\cos \theta} = 1 - \frac{M \omega^2}{2LT_0} r^2 \rightarrow T = T_0 \left( 1 - \frac{M \omega^2}{2LT_0} r^2 \right)$$

$$r^2 = \frac{2LT_0}{M \omega^2} (1 - \cos \theta_0)$$



$$r = kq \left( \frac{1}{\sqrt{(y-b)^2 + (a-x)^2 + z^2}} + \frac{1}{\sqrt{(y+b)^2 + (x+a)^2 + z^2}} - \frac{1}{\sqrt{(x+a)^2 + (y-b)^2 + z^2}} - \frac{1}{\sqrt{(y+b)^2 + (a-x)^2 + z^2}} \right)$$



$$\vec{E} = kq \int \left[ \frac{x-a}{\left[ (y-b)^2 + (x-a)^2 + z^2 \right]^{3/2}} - \frac{x+a}{\left[ (y+b)^2 + (x+a)^2 + z^2 \right]^{3/2}} - \frac{x+a}{\left[ (x+a)^2 + (y-b)^2 + z^2 \right]^{3/2}} + \frac{x-a}{\left[ (y+b)^2 + (a-x)^2 + z^2 \right]^{3/2}} \right] dx dy$$

$$\vec{E} = 2kaq \left[ \frac{1}{\left[ (y+b)^2 + a^2 + z^2 \right]^{3/2}} - \frac{1}{\left[ (y-b)^2 + a^2 + z^2 \right]^{3/2}} \right] \hat{x}$$

$$E_{(1)} = \frac{2aq}{\pi} \left[ \frac{1}{\left[ (y+b)^2 + a^2 + z^2 \right]^{3/2}} - \frac{1}{\left[ (y-b)^2 + a^2 + z^2 \right]^{3/2}} \right]$$

$$E_{(2)} = \frac{2bq}{\pi} \left[ \frac{1}{\left[ (x+a)^2 + b^2 + z^2 \right]^{3/2}} - \frac{1}{\left[ (x-a)^2 + b^2 + z^2 \right]^{3/2}} \right]$$

$$Q_2 = \frac{2bq}{\pi} \left[ \int_0^z \frac{z}{\left[ (x+a)^2 + b^2 + z^2 \right]^{3/2}} dz - \int_0^z \frac{z}{\left[ (x-a)^2 + b^2 + z^2 \right]^{3/2}} dz \right]$$

$$Q_2 = \frac{2bq}{\pi} \left[ \int_0^a \frac{d(x+a)}{b^2 + (x+a)^2} - \int_0^a \frac{d(x-a)}{b^2 + (x-a)^2} \right] \rightarrow Q_2 = \frac{2q}{\pi} \left[ \tan^{-1} \left( \frac{a}{b} \right) + \tan^{-1} \left( \frac{-a}{b} \right) \right]$$

$$Q_2 = -\frac{2q}{\pi} \tan^{-1} \left( \frac{a}{b} \right) \rightarrow Q_1 = -\frac{2q}{\pi} \tan^{-1} \left( \frac{b}{a} \right) \rightarrow Q_1 + Q_2 = -\frac{2q}{\pi} \left[ \tan^{-1} \left( \frac{a}{b} \right) + \tan^{-1} \left( \frac{b}{a} \right) \right] \rightarrow Q_1 + Q_2 = -q$$

$$-\mu(mg + N) = m(\ddot{r} - \omega^2 r) \rightarrow \ddot{r} + \omega^2 r = \mu g + 2\mu \omega r \rightarrow \omega^2 e^{at} - a^2 e^{at} = 2\mu \omega a e^{at} \rightarrow a^2 + 2\mu \omega a - \omega^2 = 0$$

$$N = m \ddot{r} \omega^2 \rightarrow a = (-\mu \pm \sqrt{\mu^2 + 1}) \omega \rightarrow r_{(1)} = A e^{a_1 t} + B e^{a_2 t}$$

$$N_{th} = 2m \omega \dot{r}_{(1)} \quad \vec{L} = m r^2 \dot{\theta} \hat{z} \rightarrow \dot{\vec{L}} = m \omega r^2 \hat{z} \rightarrow \vec{\tau} = m \omega r^2 \hat{z} \rightarrow \dot{\vec{L}} = 2m \omega r \dot{r} \hat{z}$$