

Chapter 10: Rotation

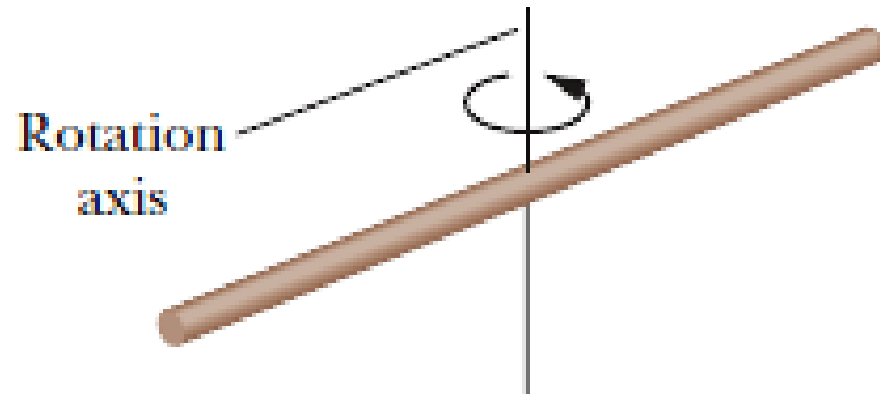
- ✓ **Angular Position, Velocity and Acceleration**
- ✓ **Rotational Kinematics**
- ✓ **Kinetic Energy of Rotation**
- ✓ **Rotational Inertia**
- ✓ **Torque**
- ✓ **Energy Consideration in Rotational Motion**

Chapter 10: Rotation

Session 21:

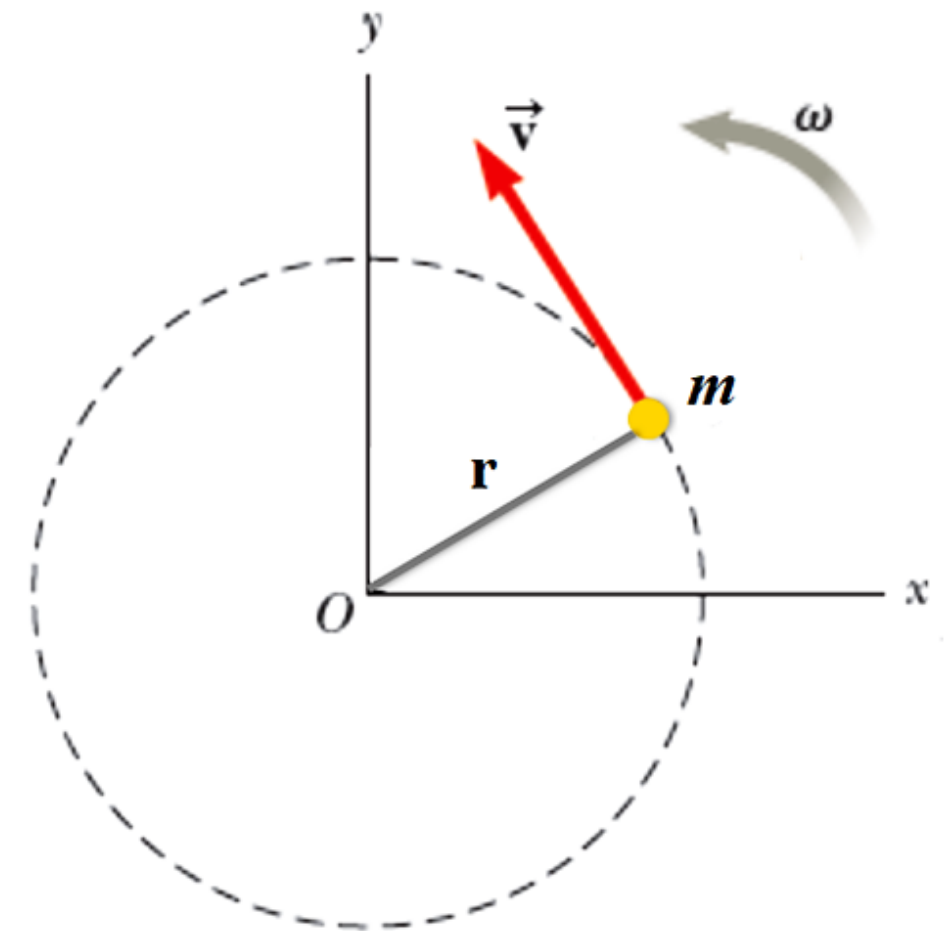
- ✓ **Kinetic Energy of Rotation**
- ✓ **Rotational Inertia**
- ✓ **Examples**

Kinetic Energy of Rotation



$$k = \frac{1}{2} M v_{com}^2 = 0$$

$$k = \frac{1}{2} m v^2 = \frac{1}{2} m (r \omega)^2 = \frac{1}{2} (m r^2) \omega^2$$



For a collection of rotating objects:

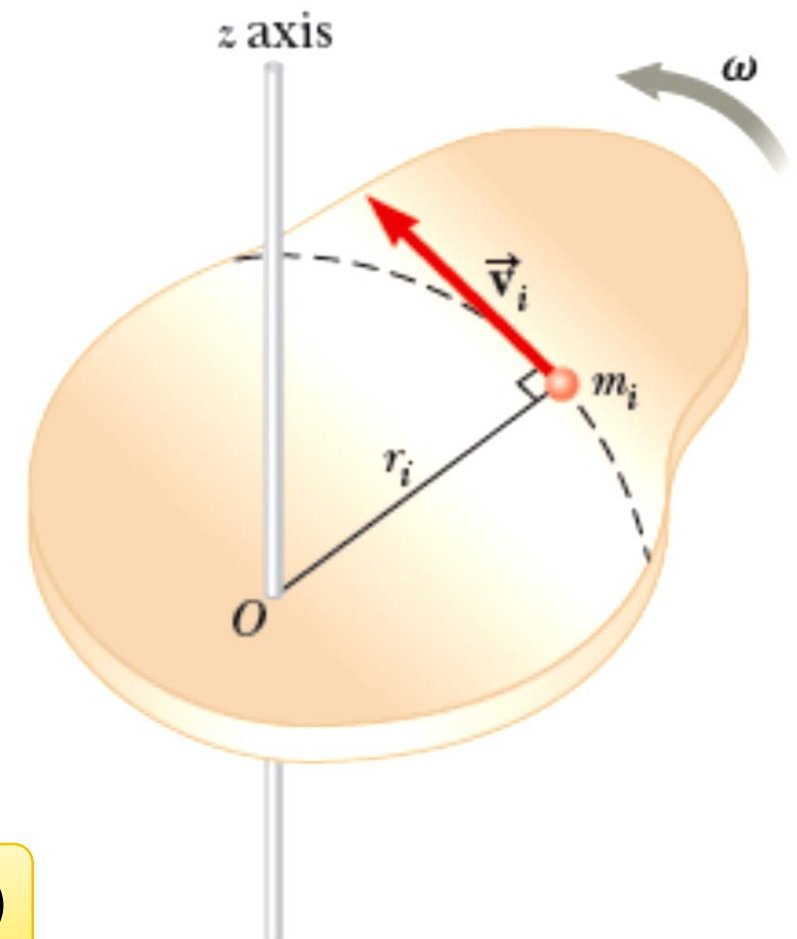
$$k = \sum_{i=1}^N k_i = \sum_{i=1}^N \frac{1}{2} (m_i r_i^2) \omega_i^2 = \frac{1}{2} \sum_{i=1}^N (m_i r_i^2) \omega_i^2$$

if $\omega = \text{constant}$

$$k = \frac{1}{2} \left(\sum_{i=1}^N m_i r_i^2 \right) \omega^2 = \frac{1}{2} I \omega^2$$

$$I = \sum_{i=1}^N m_i r_i^2$$

Rotational Inertial (kg.m²)



Kinetic Energy of Rotation

$$k = \frac{1}{2} \left(\sum_{i=1}^N m_i r_i^2 \right) \omega^2 = \frac{1}{2} I \omega^2$$

For rotation about y axis:

$$I_y = \sum_{i=1}^4 m_i r_i^2 = Ma^2 + Ma^2 + m(0) + m(0) = 2Ma^2$$

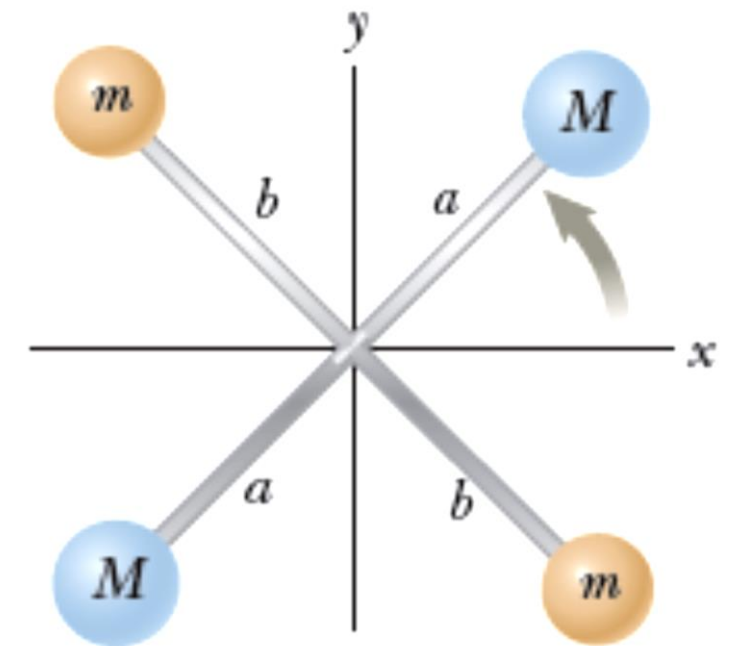
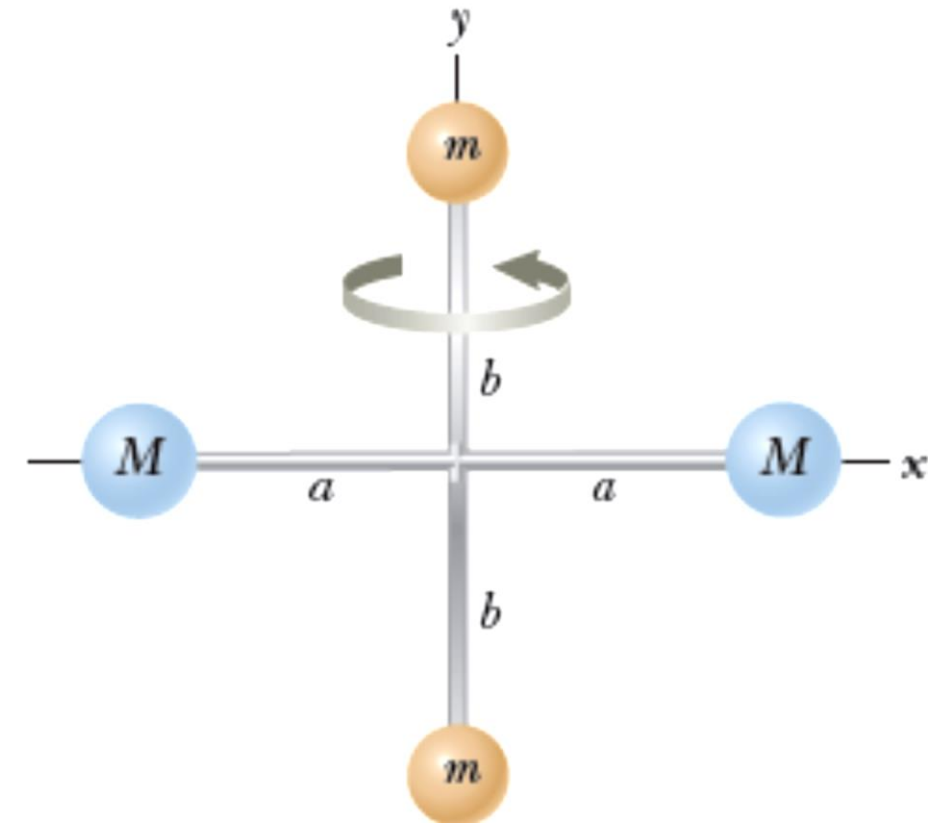
$$k_1 = \frac{1}{2} (2Ma^2) \omega^2 = Ma^2 \omega^2$$

For rotation about z axis:

$$I_z = \sum_{i=1}^4 m_i r_i^2 = Ma^2 + Ma^2 + mb^2 + mb^2 = 2Ma^2 + 2mb^2$$

$$k_2 = \frac{1}{2} (2Ma^2 + 2mb^2) \omega^2 = (Ma^2 + mb^2) \omega^2$$

$$k_2 > k_1$$

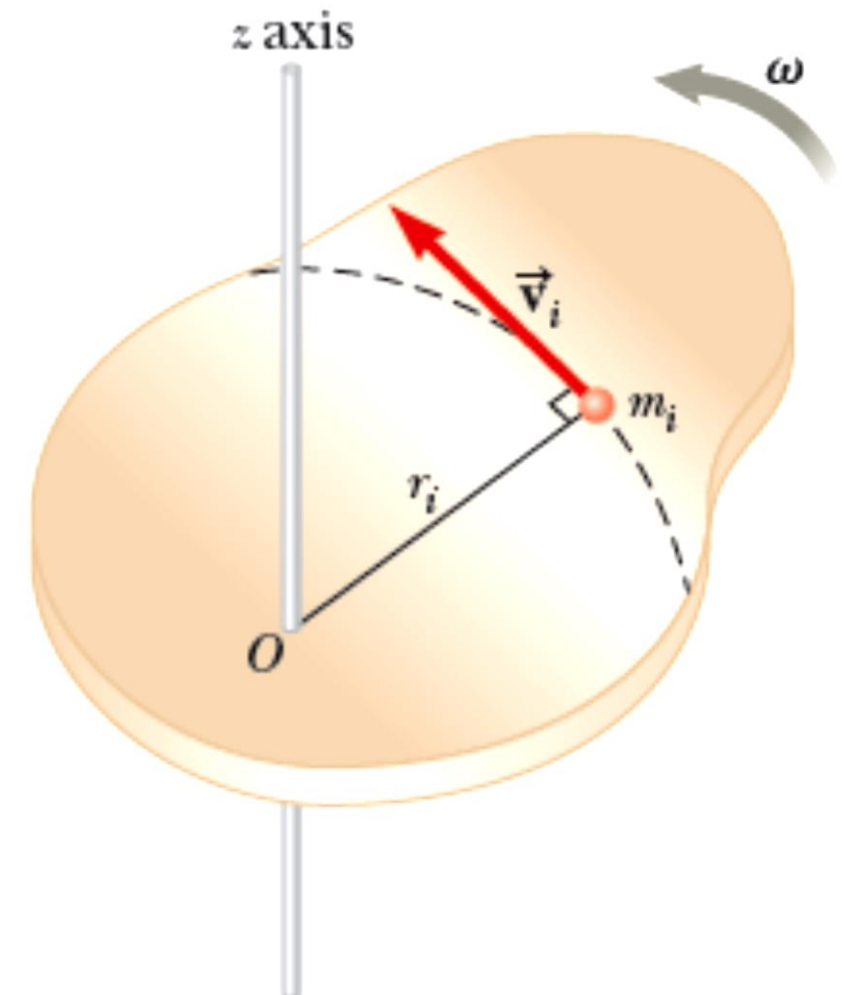


Rotational Inertia of A Rigid Body

$$I = \sum_{i=1}^N m_i r_i^2$$

$$I = \lim_{\Delta m_i \rightarrow 0} \sum_i r_i^2 \Delta m_i$$

$$I = \int r^2 dm$$



- 1) **Linear Mass Density** → mass per unit length : $\lambda = \frac{m}{L} \Rightarrow dm = \lambda dL$
- 2) **Surface Mass Density** → mass per unit surface, : $\sigma = \frac{m}{A} \Rightarrow dm = \sigma dA$
- 3) **Volumetric Mass Density** → mass per unit volume: $\rho = \frac{m}{V} \Rightarrow dm = \rho dV$

Ex 6: Calculate the moment of inertia of a uniform thin rod of length **L** and mass **M** about an axis perpendicular to the rod and passing through its center of mass.

$$I = \int r^2 dm$$

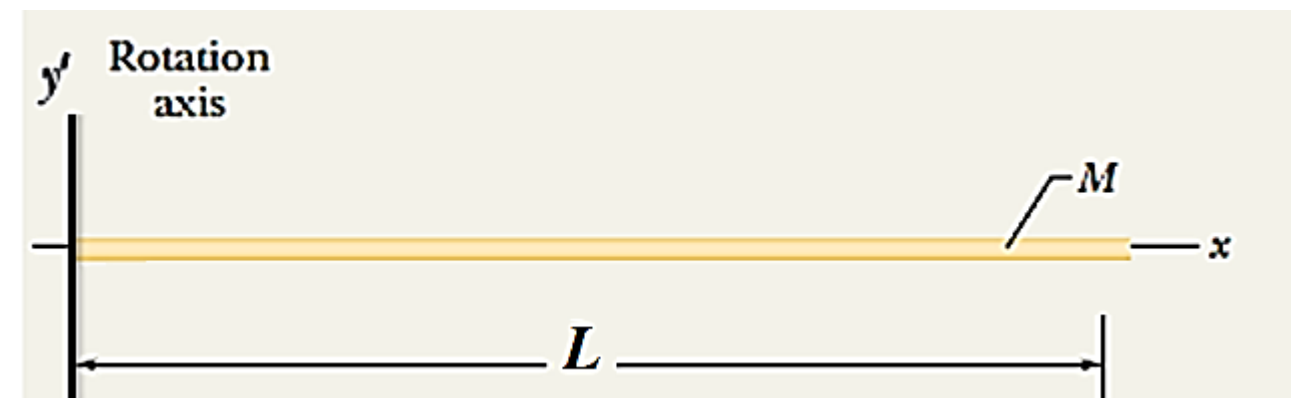
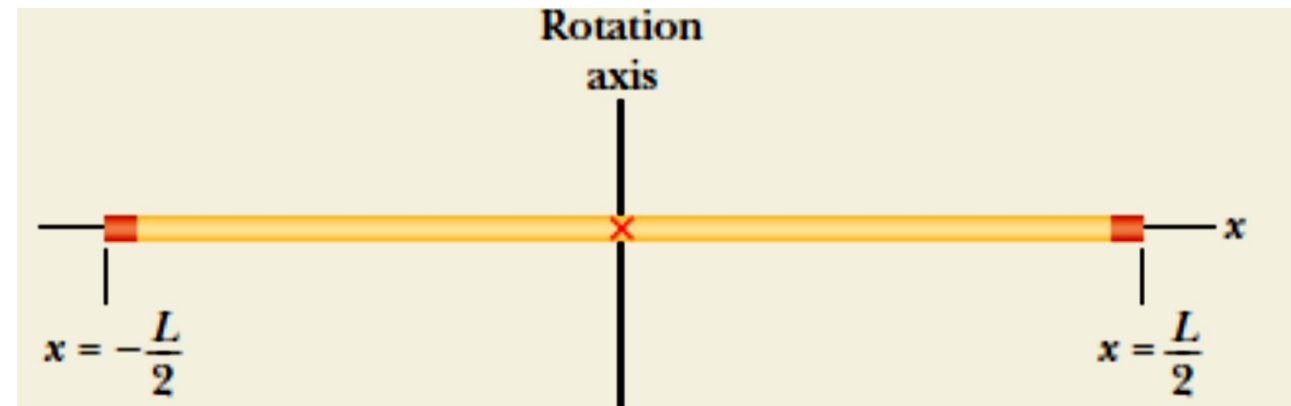
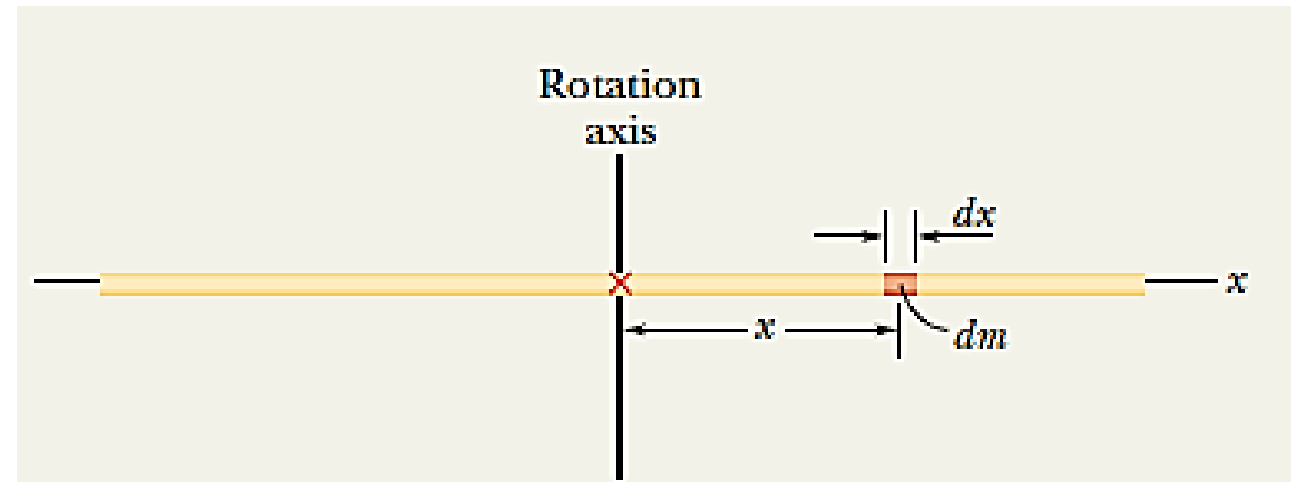
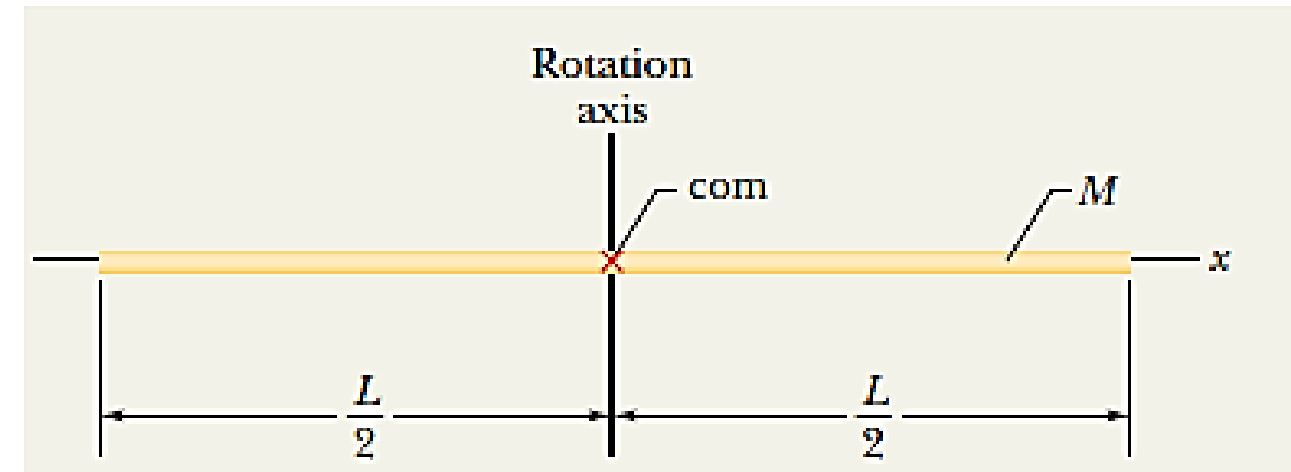
$$\lambda = \frac{M}{L} \quad \Rightarrow \quad dm = \lambda dx = \frac{M}{L} dx$$

$$I_y = \int r^2 dm = \int_{-L/2}^{L/2} x^2 \left(\frac{M}{L} dx \right)$$

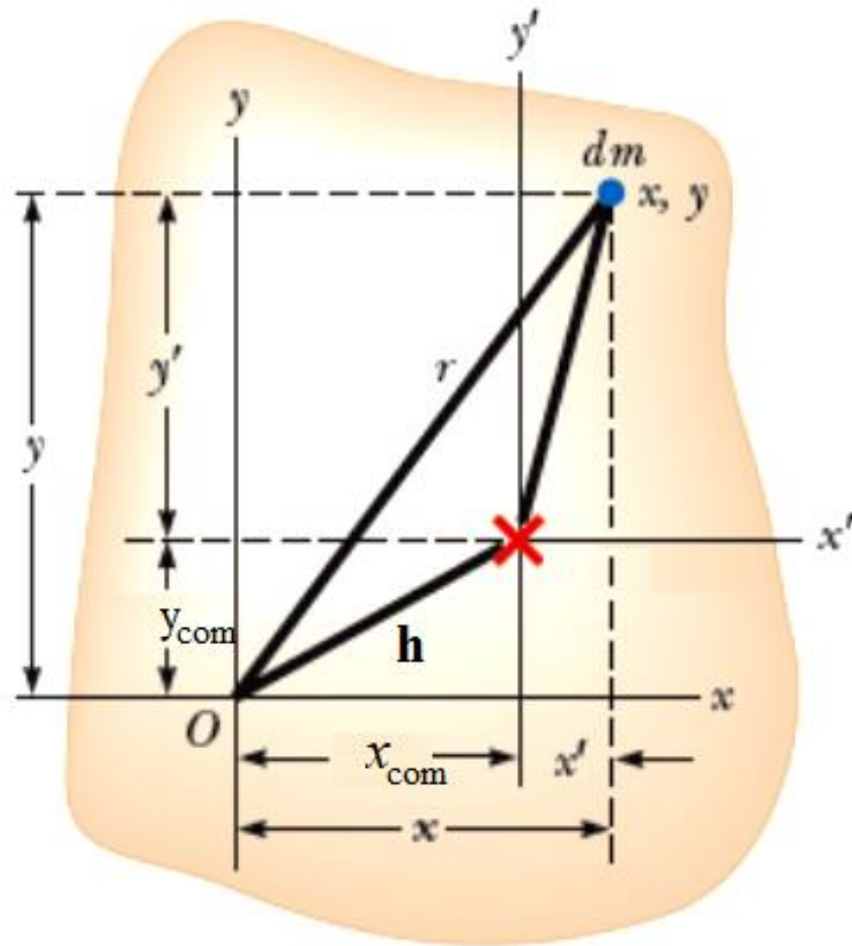
$$I_y = 2 \left(\frac{M}{L} \right) \frac{x^3}{3} \bigg|_0^{L/2} = 2 \left(\frac{M}{L} \right) \frac{L^3}{24} = \frac{1}{12} M L^2$$

$$I_{y'} = \int r^2 dm = \int_0^L x^2 \left(\frac{M}{L} dx \right) = \frac{1}{3} M L^2$$

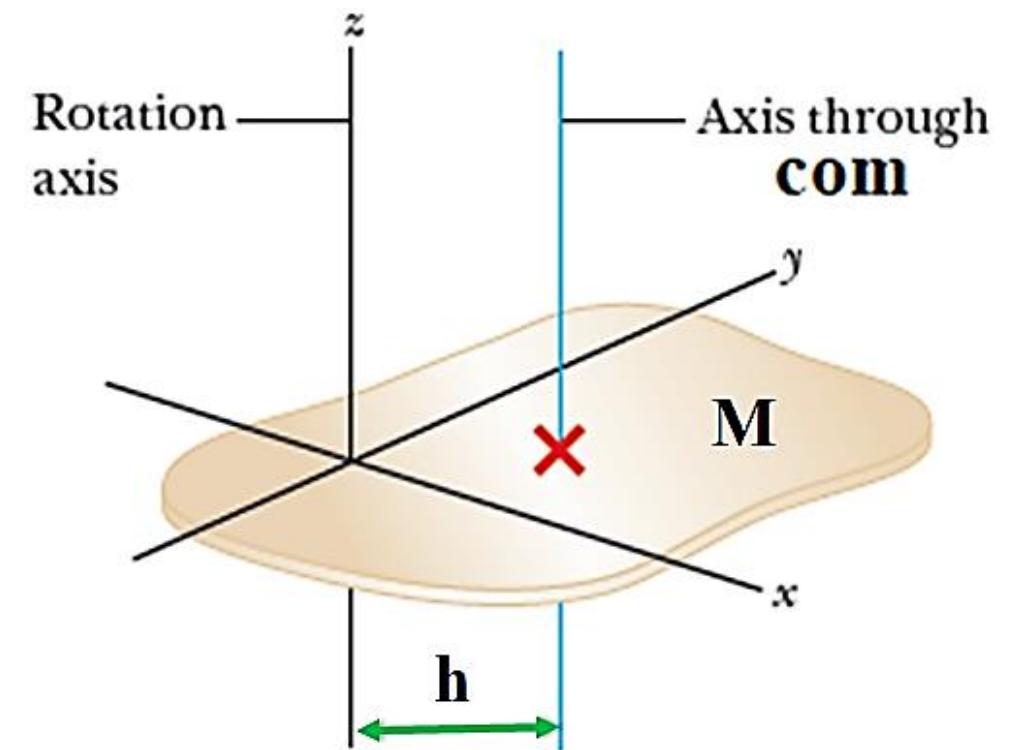
$$I_{y'} > I_y$$



Parallel-Axis Theorem



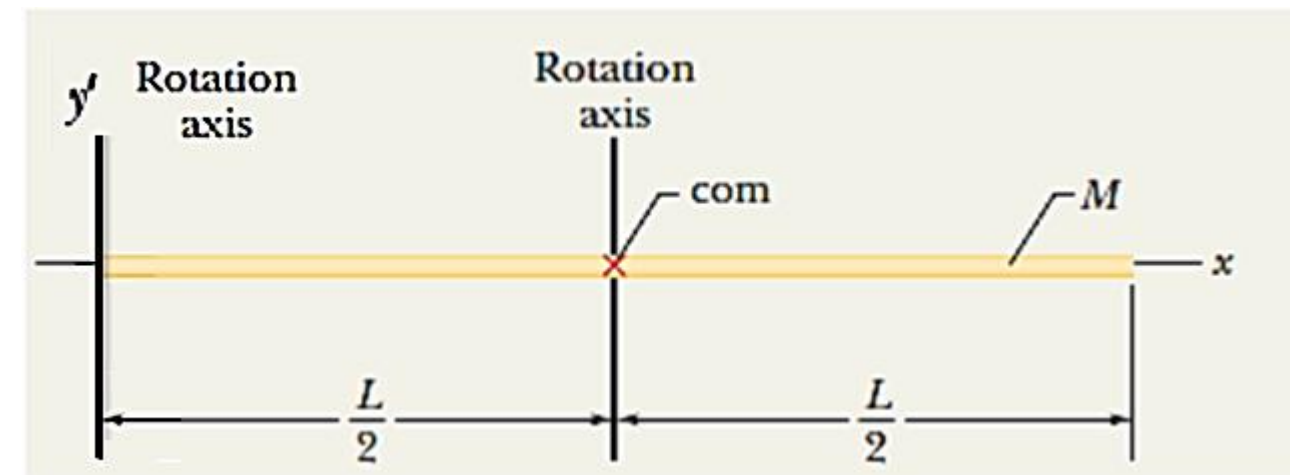
$$I_z = I_{com} + M h^2$$



$$I_z = \int r^2 dm = \int (x^2 + y^2) dm = \int [(x' + x_{com})^2 + (y' + y_{com})^2] dm$$

$$I_z = \underbrace{\int (x'^2 + y'^2) dm}_{I_{com}} + 2x_{com} \underbrace{\int x' dm}_0 + 2y_{com} \underbrace{\int y' dm}_0 + \underbrace{(x_{com}^2 + y_{com}^2)}_{h^2} \int dm_M$$

$$I_{y'} = I_{com} + M h^2 = \frac{1}{12} M L^2 + M \left(\frac{L}{2} \right)^2 = \frac{1}{3} M L^2$$

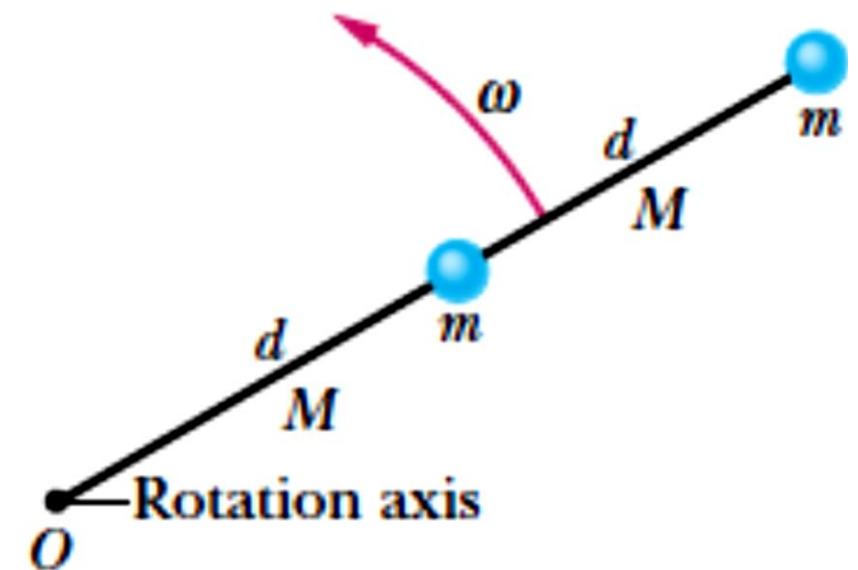


Ex 7: (Problem 10. 41 Halliday)

Two particles, each with mass $m = 0.85 \text{ kg}$, are fastened to each other, and to a rotation axis at O, by two thin rods, each with length $d = 5.6 \text{ cm}$ and mass $M = 1.2 \text{ kg}$. The combination rotates around the rotation axis with the angular speed $\omega = 0.30 \text{ rad/s}$. Measured about O, what are the combination's (a) rotational inertia and (b) kinetic energy?

Two particles:

$$I_1 = m d^2 + m (2d)^2 = 5 m d^2$$



Two rods:

$$I_2 = \left[\frac{1}{12} M d^2 + M \left(\frac{d}{2} \right)^2 \right] + \left[\frac{1}{12} M d^2 + M \left(\frac{3d}{2} \right)^2 \right] = \frac{8}{3} M d^2$$

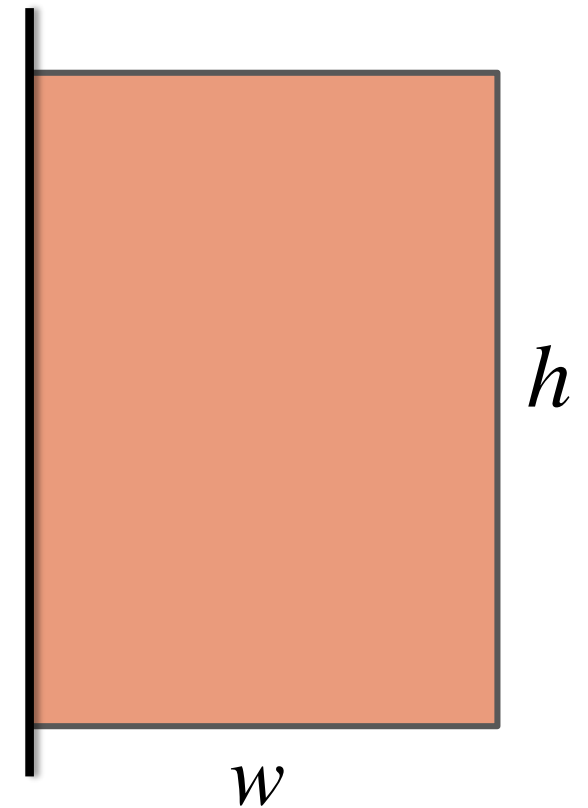
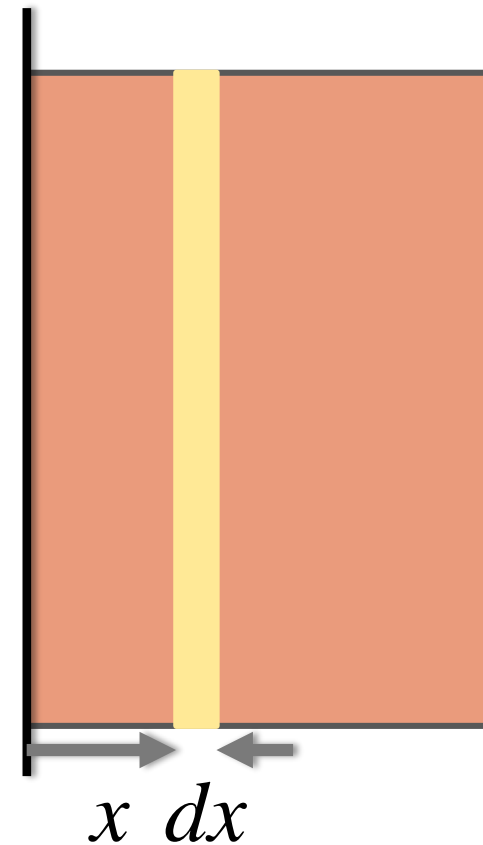
$$I_T = I_1 + I_2 = 5 m d^2 + \frac{8}{3} M d^2 = (5 \times 0.85 + \frac{8}{3} \times 1.2) (0.056)^2 = 0.023 \text{ kg.m}^2$$

$$k = \frac{1}{2} I_T \omega^2 = \frac{1}{2} (0.023) (0.30)^2 = 1.03 \times 10^{-3} \text{ J}$$

Ex 8: A uniform, thin, solid door has height **2.20 m**, width **0.870 m**, and mass **23 kg**. Find its **rotational inertia** for rotation on its **hinges**.

$$I = \int r^2 dm$$

$$\sigma = \frac{M}{A} \quad \Rightarrow \quad dm = \sigma dA = \frac{M}{A} h dx$$



$$I = \int r^2 dm = \int_0^w x^2 \left(\frac{M}{A} h dx \right) = \frac{M}{A} h \int_0^w x^2 dx = \frac{M}{A} h \frac{w^3}{3}$$

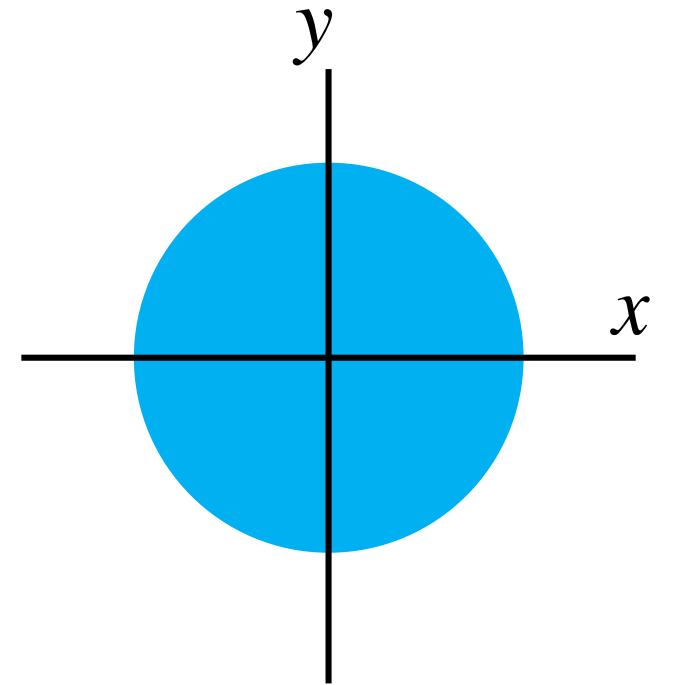
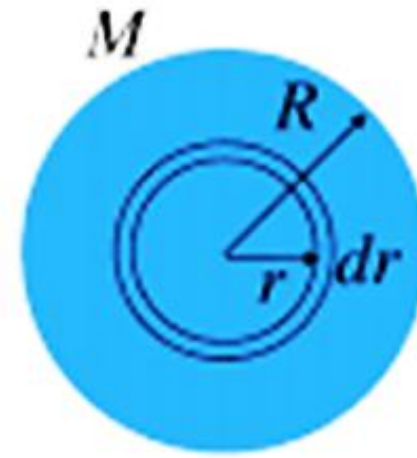
$$A = wh$$

$$I = \frac{1}{3} M w^2 = \frac{1}{3} (23) (0.87)^2 = 5.80 \text{ kg.m}^2$$



Ex 9: Find the moment of inertia of a uniform thin **disc** of radius **R** and mass **M** about an axis perpendicular to the disc and passing through its center of mass.

$$I = \int r^2 dm$$



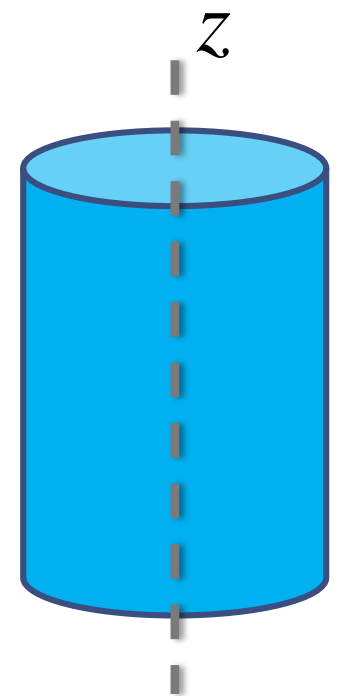
$$\sigma = \frac{M}{A} \quad \longrightarrow \quad dm = \sigma dA = \frac{M}{A} (2\pi r dr)$$



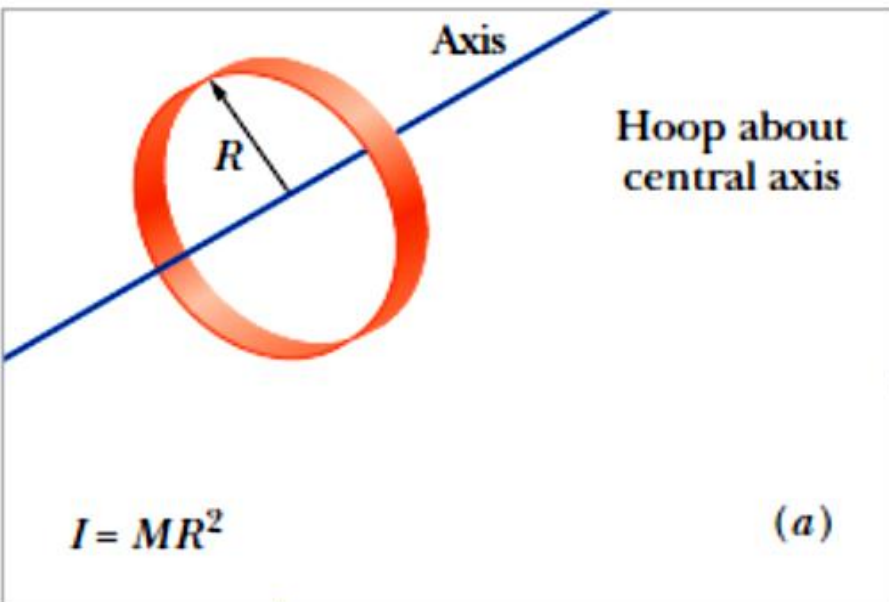
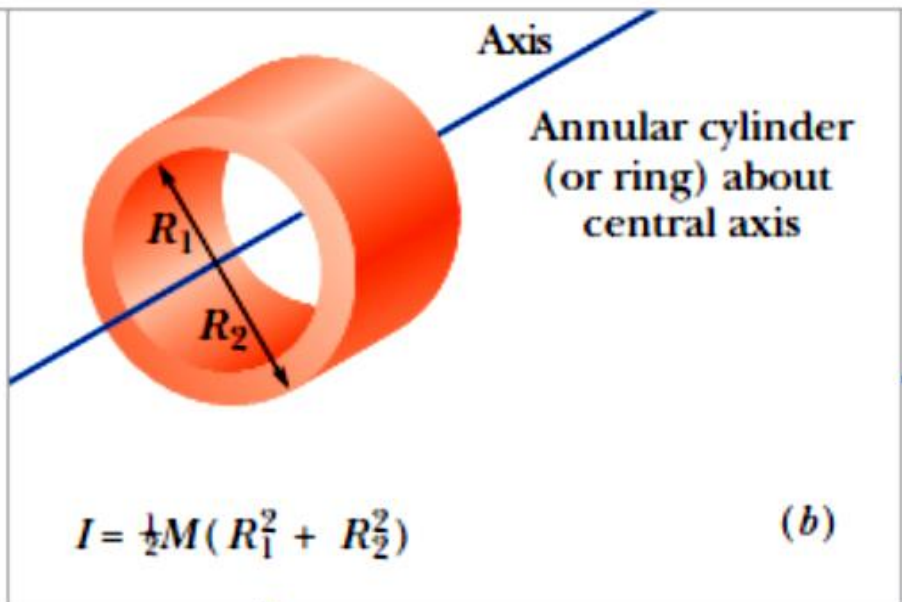
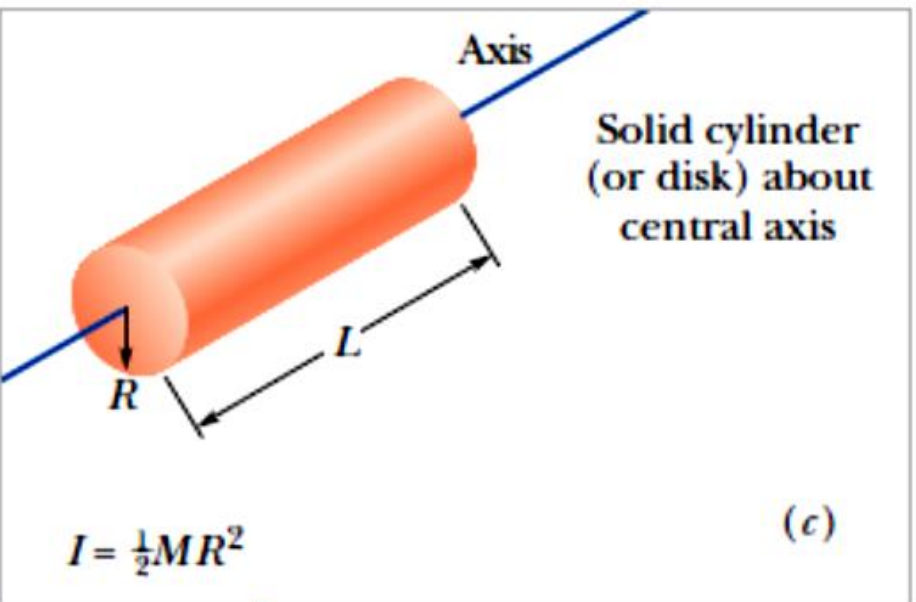
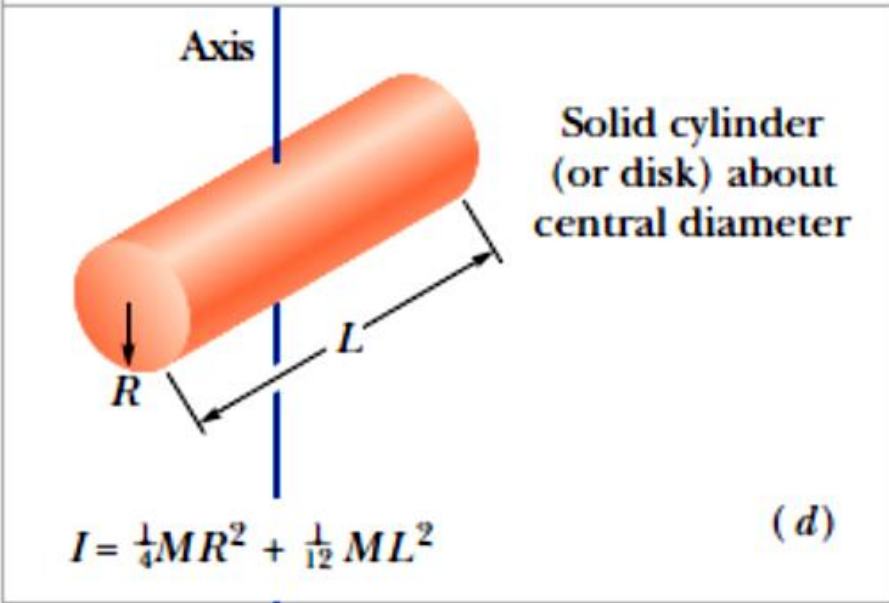
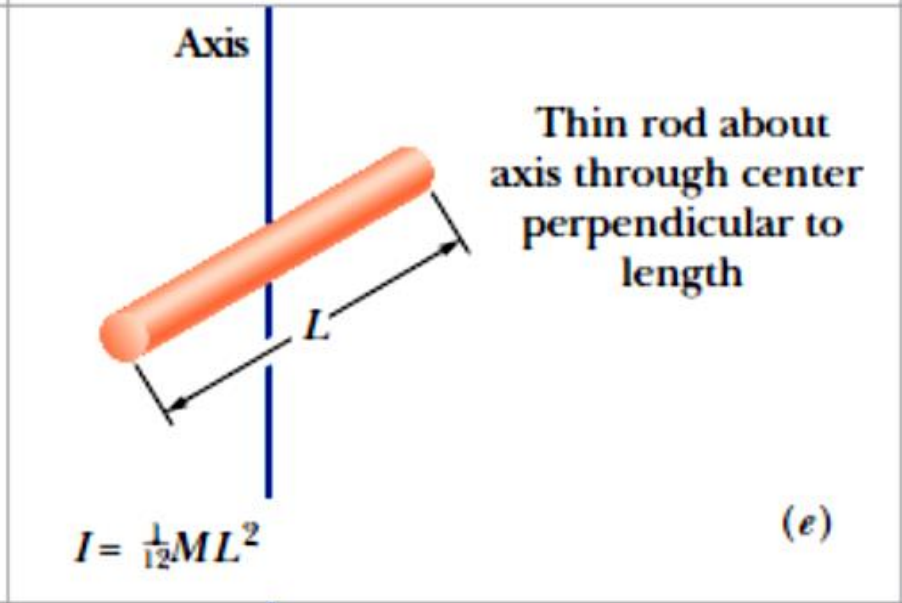
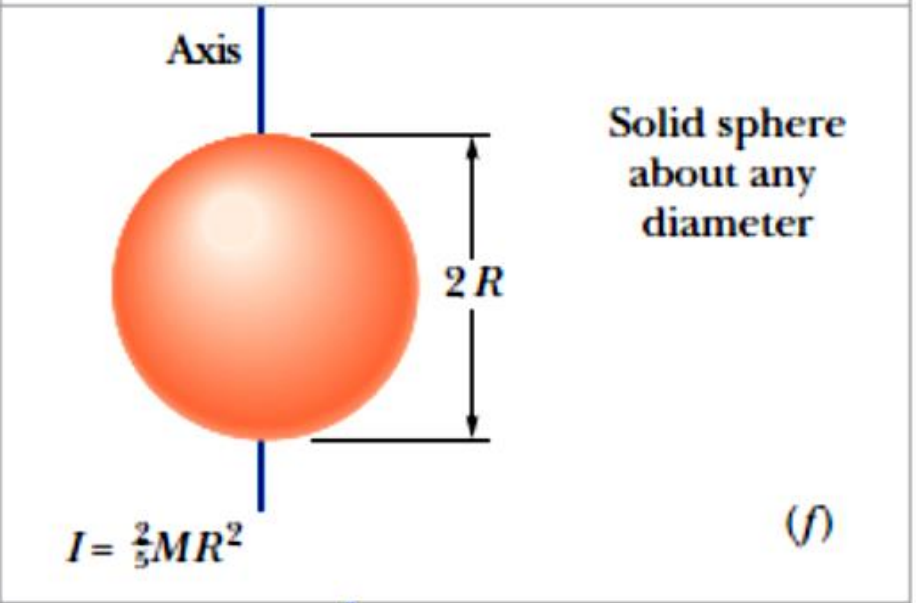
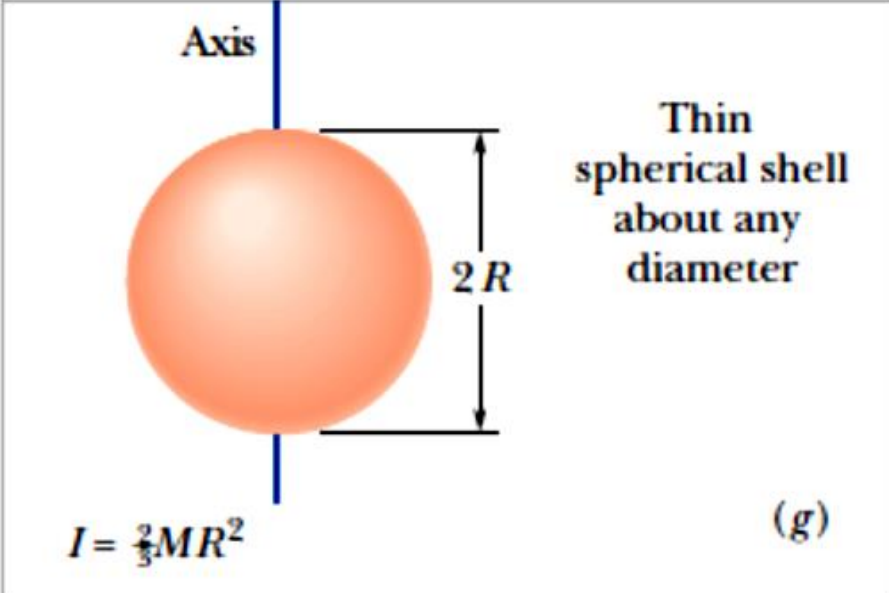
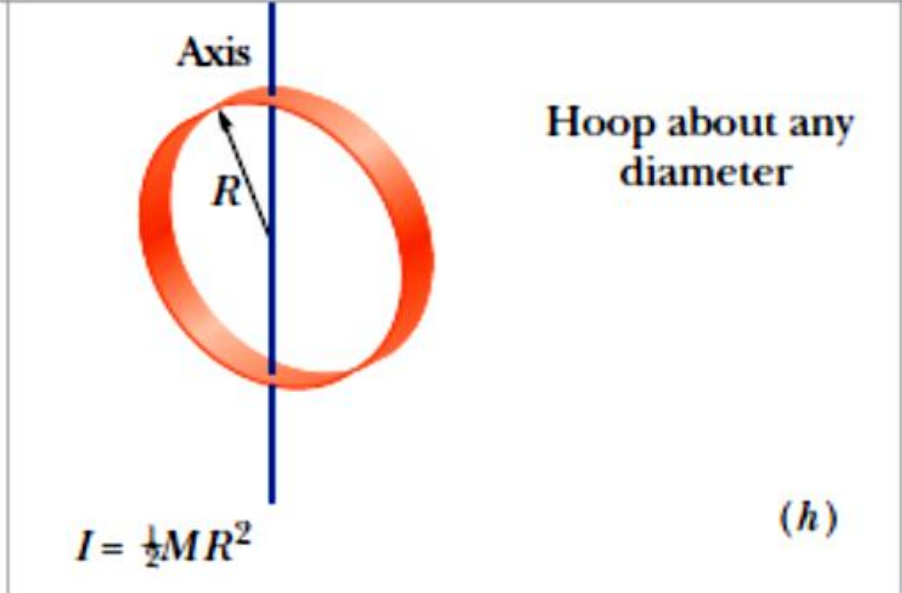
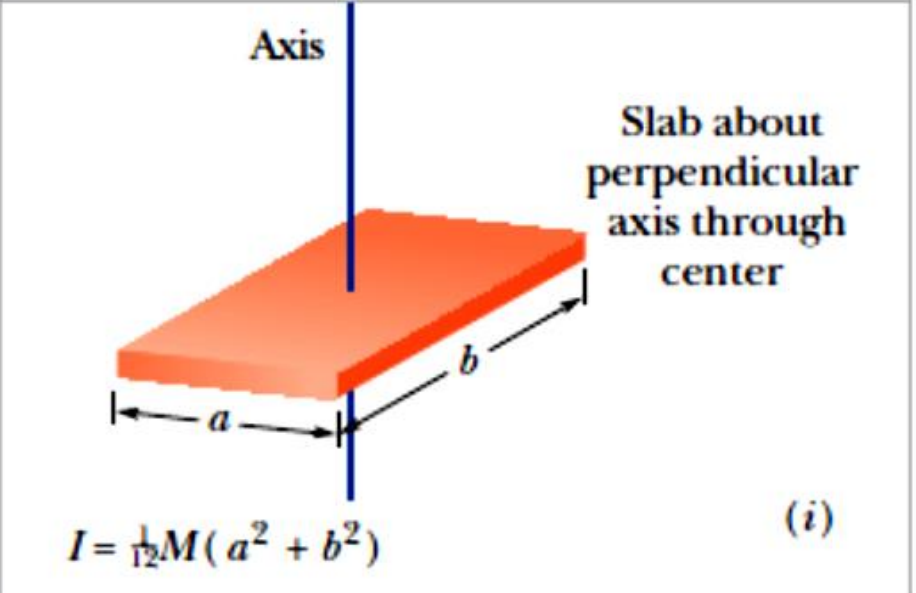
$$I_z = \int_0^R r^2 \left[\frac{M}{A} (2\pi r dr) \right] = 2\pi \frac{M}{A} \int_0^R r^3 dr = 2\pi \frac{M}{A} \frac{R^4}{4} \quad A = \pi R^2$$

$$I_z = \frac{1}{2} MR^2$$

$$I_z = I_x + I_y = 2I_x = 2I_y \quad \longrightarrow \quad I_x = I_y = \frac{1}{4} MR^2$$



Some Rotational Inertias

 <p>Hoop about central axis</p> <p>$I = MR^2$ (a)</p>	 <p>Annular cylinder (or ring) about central axis</p> <p>$I = \frac{1}{2}M(R_1^2 + R_2^2)$ (b)</p>	 <p>Solid cylinder (or disk) about central axis</p> <p>$I = \frac{1}{2}MR^2$ (c)</p>
 <p>Solid cylinder (or disk) about central diameter</p> <p>$I = \frac{1}{4}MR^2 + \frac{1}{12}ML^2$ (d)</p>	 <p>Thin rod about axis through center perpendicular to length</p> <p>$I = \frac{1}{12}ML^2$ (e)</p>	 <p>Solid sphere about any diameter</p> <p>$I = \frac{2}{5}MR^2$ (f)</p>
 <p>Thin spherical shell about any diameter</p> <p>$I = \frac{2}{3}MR^2$ (g)</p>	 <p>Hoop about any diameter</p> <p>$I = \frac{1}{2}MR^2$ (h)</p>	 <p>Slab about perpendicular axis through center</p> <p>$I = \frac{1}{12}M(a^2 + b^2)$ (i)</p>

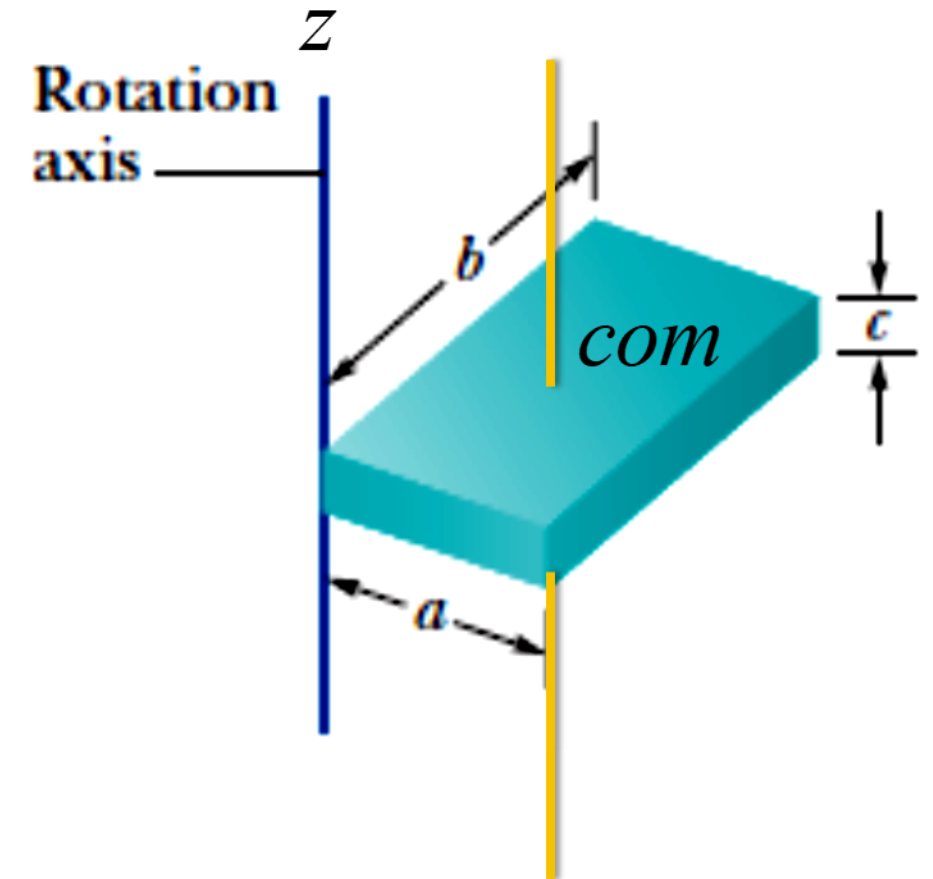
Ex 10: (Problem 10. 43 Halliday)

The uniform solid block has mass **0.172 kg** and edge lengths **a = 3.5 cm**, **b = 8.4 cm**, and **c = 1.4 cm**. Calculate its rotational inertia about an axis through one corner and perpendicular to the large faces.

$$I_z = I_{com} + M h^2$$

$$I_z = \frac{1}{12} M(a^2 + b^2) + M \left(\sqrt{\frac{a^2}{4} + \frac{b^2}{4}} \right)^2 = \frac{1}{3} M(a^2 + b^2)$$

$$I_z = \frac{1}{3} (0.172) \left[(0.35)^2 + (0.84)^2 \right] = 0.048 \text{ kg.m}^2$$



$$I = \int r^2 dm$$

$$\rho = \frac{M}{V} \quad \Rightarrow \quad dm = \rho dV = \frac{M}{V} (c \, dx \, dy)$$

$$I_z = \int_0^a \int_0^b (x^2 + y^2) \left[\frac{M}{V} (c \, dx \, dy) \right] = \frac{M}{V} c \left(\int_0^a \int_0^b x^2 \, dx \, dy + \int_0^a \int_0^b y^2 \, dx \, dy \right) = \frac{M}{V} c \left(\frac{ba^3}{3} + \frac{ab^3}{3} \right)$$

$$V = abc$$

$$I_z = \frac{1}{3} M(a^2 + b^2)$$