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Add new research

Overview Research Experience Stats Scores Following Saved List

This preview is private - only you can see it on your profile

Business card

Your business card is a short summary of your profile which can be displayed to others across the platform.

Business card preview showing name, title, institution, and skills like MATLAB Simulation.

About me Edit

Introduction
Robot stability analysis in Banach space
Languages: English
Disciplines: Engineering Education
Skills and expertise: MATLAB Simulation

Stats overview View all

Stats overview showing 4,787 Reads, 0 Citations, 20,595 Recommendations, and 4,794 Total Research Interest.

Research

Research overview View all

Research overview showing 291 Research items, 248 Projects, 70 Questions, and 54 Answers.

Featured research Edit

Featured research list with titles like 'Investigating the Role of Lighting in the Security of Citizens' and 'Numerical investigation fluid velocity and heat transfer...'.

Projects

Project listing: Beiträge zur Disziplin- und Wissenschaftsgeschichte // Educational Science: Contributions to the History of Science and Education

Current affiliation Edit

Islamic Azad University, Garmzar Branch
Location: Varāmīn, Iran
Department: Department of Electrical and Electronic Engineering
Position: PhD Student
Time period: Feb 2017 - Present

Add missing details about your affiliation

Pooya Pasha's Lab

Lab head Pooya Pasha, Lab members (5)

Network

Following (2435)

- List of researchers being followed, including Giansimone Perrino, Yuichiro Okada, and Mohammad Beheshti-Atashgah.

Followers (1117)

- List of researchers following, including Yuichiro Okada, Kelta Tokumitsu, and Mohammed Ahmed Sultan.

Follow researchers with the same skills as you

- Researchers with similar skills: Jazel Rivera, Jade Elhalmer, Kartik Mungole.

View more researchers

Top co-authors View all

- Top co-authors: O.R. Seryasat, Pooya Yousefi, Sareh Sanei, Sina Ahmadi, Rassa Safaei Namin.

Add update

How to prove the complete stability of a state (a linear control system or a linear non-control system)

Project

Add update

How do we rewrite the equations of differential and differential (discrete-time) of the system written in Euclidean space and Hilbert space in Banach space?

Project

Add update