

$$cdv + vdc = 0 \rightarrow \Delta v = -\frac{v \Delta c}{c} \rightarrow \Delta v = \frac{(4\pi a^3) v}{LA} + \dots$$

سؤال: حلقه این به شعاع r دارای بار Q است. اگر همان بار را در یک کره رسانا قرار دهیم...

برداریم جهت میدان الکتریکی در محل ساق سنبل را بدست آوریم.

$$m \frac{d\vec{v}}{dt} = q\vec{E} \rightarrow \vec{v}_f - \vec{v}_i = \frac{qE\tau}{m} \rightarrow \vec{v} = \frac{\vec{v}_i + \vec{v}_f}{2} = \vec{v}_i + \frac{qE\tau}{2m}$$

$$\vec{v}_D = \frac{qE\tau}{2m}, \quad \vec{v}_i = 0, \quad \tau = \bar{\tau}$$

$$m \frac{d\vec{v}}{dt} = \vec{F} = \alpha \vec{v}, \quad t \rightarrow \infty: \vec{v} \rightarrow \vec{v}_D \rightarrow \alpha = \frac{2m}{\tau}$$

$$\frac{d\vec{v}}{dt} + \frac{2}{\tau} \vec{v} = \frac{\vec{F}}{m} = \vec{f}, \quad e^{\frac{2t}{\tau}} \vec{v} = \vec{v}_0 \rightarrow$$

$$\frac{d\vec{v}}{dt} = e^{\frac{2t}{\tau}} \vec{f}_{(t)} \rightarrow \vec{v}_{(t)} = \vec{v}_{(0)} e^{-\frac{2t}{\tau}} + \int_0^t \vec{f}_{(t')} e^{\frac{2(t-t')}{\tau}} dt'$$

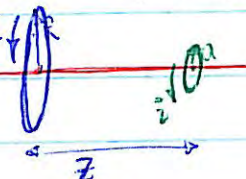
$$m \frac{d\vec{v}}{dt} = \vec{F} + \vec{A}_{(0)} \rightarrow \vec{v}_{(0)} = \vec{v}_0, \quad \vec{F} = \frac{2m\vec{v}_0}{\tau} + \vec{A}_{(0)} = 0 \rightarrow \vec{A}_{(0)} = -\frac{2m\vec{v}_0}{\tau}$$

برای زمان های دور  $\frac{d\vec{v}}{dt}$  صفر است.

$$B_z = \frac{\mu_0 I R^2}{2(R^2+z^2)^{3/2}}$$

الف) میدان را بر روی محور حلقه بدست آوریم. ب) معادلات نسل دو حلقه هم محور را در نظر بگیریم. نیرو وارد بر حلقه کوچکتر را بدست آوریم.

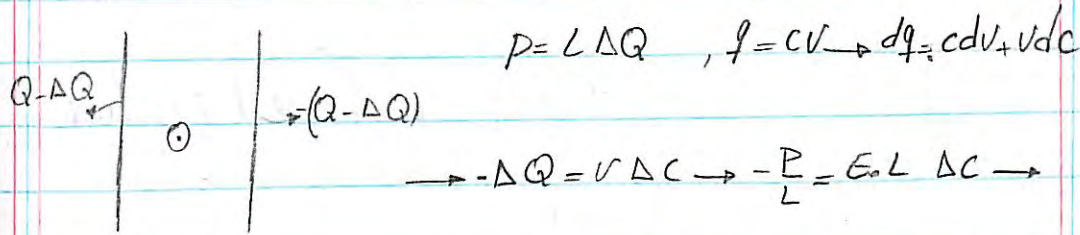
$$dB_z \times \pi \rho^2 + B_\rho \times 2\pi \rho dz = 0 \rightarrow B_\rho s - \frac{\rho}{2} \frac{dB_z}{dz} \rightarrow B_\rho s = \frac{3\mu_0 I z \rho}{4(R^2+z^2)^{5/2}}$$

$$d\vec{F}_z = i(d\vec{L} \times \vec{B}_\rho) \rightarrow \vec{F}_z = -\frac{3\mu_0 i \pi z I R^2 a^2}{2(R^2+z^2)^{5/2}} \hat{z}$$


سؤال: اگر یک ترمز را با این صفحات یک خازن قرار دهیم. تغییر در ساق سنبل چگونه است؟

دو شرایط نیز به تفاوت داریم.

میدان v



$$-\Delta Q = v \Delta c \rightarrow -\frac{P}{L} = E_0 L \Delta c \rightarrow \frac{4\pi \epsilon_0 a^3 E_0}{L} = E_0 L \Delta c \rightarrow \Delta c = -\frac{4\pi \epsilon_0 a^3}{L^2}$$

$$D^n x + D^{n-1} x a_{n-1} + \dots + a_0 x = f(t)$$

نکته: شکل  $(s^n + a_{n-1}s^{n-1} + \dots + a_0) e^{st} = 0 \rightarrow$  ریشه مختلط

$\frac{d}{dt}(ae^{at}) = ae^{at}$ ,  $e^0 = 1$ ,  $e^{i\omega t}$  را طوری تعریف کنیم که داشته باشیم  $e^{i\omega t} = f_{c, \omega} + i g_{c, \omega} \rightarrow f_{c, \omega} = \cos, g_{c, \omega} = \sin$

$e^{i\omega t} = f_{c, \omega} + i g_{c, \omega} \rightarrow f_{c, \omega} = \cos, g_{c, \omega} = \sin$

اگر  $s = b + i\omega$ ,  $\bar{s} = b - i\omega$  نیز جواب است

$$(\bar{z}_1 + \bar{z}_2) = \bar{z}_1 + \bar{z}_2$$

$$(D^n + a_{n-1}D^{n-1} + \dots + a_0)y = f \mid [P_{(0)}]y'' = 0, y^H = e^{s_1 t} z_{(1)}$$

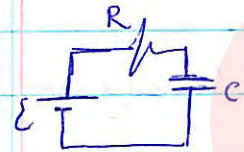
$$P_{(0)} = (D - s_1)^{k_1} \dots (D - s_{l_2})^{k_{l_2}} \mid [P_{(0)}](e^{s_1 t} z_{(1)}) = 0$$

$$P_{(s)} = (s - s_1) \dots (s - s_n)$$

$$k_1 + k_2 + \dots + k_{l_2} = n$$

$$\vec{D} = \frac{\tau}{2m} \vec{F} \rightarrow \vec{j} = \frac{\tau n q^2 c}{2m} \vec{E} \rightarrow \vec{j} = b \vec{E}$$

$$\vec{E}_{(r)} = (V_0 - V_1) \vec{e}_{(r)} \rightarrow \vec{j} = b(V_0 - V_1) \vec{e}_{(r)} \rightarrow I = b(V_0 - V_1) \int_{(r)} \vec{e}_{(r)} ds$$



$$\frac{d^n x}{dt^n} + a_{n-1} \frac{d^{n-1} x}{dt^{n-1}} + \dots + a_0 x = f, D = \frac{d}{dt}$$

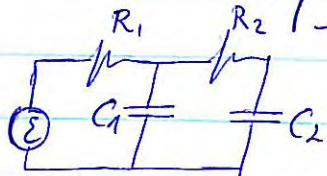
$$\rightarrow (D^n + a_{n-1}D^{n-1} + \dots + a_0)x^P = f \rightarrow (D^n + a_{n-1}D^{n-1} + \dots + a_0)(x - x^P) = 0$$

$$(D^n + a_{n-1}D^{n-1} + \dots + a_0)x = f$$

$x = x^P + x^H$  جواب عمومی معادله است  
جواب خاص

$$\frac{dx}{dt} = f_{(0)}, \begin{cases} \forall \epsilon > 0, \exists \delta > 0 \mid |x - x_0| < \delta \rightarrow |f_{(0)} - f_{(0,0)}| < \epsilon \\ \forall M > 0, \exists \delta > 0 \mid |x - x_0| < M\delta \rightarrow \dots \end{cases}$$

اگر  $P_{(b)} \neq 0$  در این صورت باید یک  $\tilde{Q}_{(t)}$  ضرب کنیم و آن  
 جواب مضاعف معادله بود ضرب می کنیم



$$\begin{cases} C_1 \frac{dV_1}{dt} + \frac{V_1 - E}{R_1} + \frac{V_1 - V_2}{R_2} = 0 \\ C_2 \frac{dV_2}{dt} + \frac{V_2 - V_1}{R_2} = 0 \end{cases} \rightarrow \begin{cases} C_1 \frac{dV_1}{dt} + \frac{V_1}{R_1} + \frac{V_1 - V_2}{R_2} = 0 \\ C_2 \frac{dV_2}{dt} + \frac{V_2 - V_1}{R_2} = 0 \end{cases}$$

$$\rightarrow \underbrace{\begin{pmatrix} C_1 D + \frac{1}{R_1} + \frac{1}{R_2} & -\frac{1}{R_2} \\ -\frac{1}{R_2} & C_2 D + \frac{1}{R_2} \end{pmatrix}}_{P_{(D)}} \underbrace{\begin{pmatrix} V_1 \\ V_2 \end{pmatrix}}_{\tilde{V}} = \underbrace{\begin{pmatrix} \frac{E}{R_1} \\ 0 \end{pmatrix}}_{\tilde{E}}$$

$$[P_{(D)}] V = \tilde{E} \rightarrow [P_{(D)}] V^P = \tilde{E}, \quad [P_{(D)}] V^H = 0$$

$$V_{(t)}^H = V^H e^{st} \rightarrow [P_{(D)}] V^H e^{st} = 0 \rightarrow [P_{(D)}] V^H = 0$$

$$D(e^{s_1 t} z_{(t)}) = s_1 e^{s_1 t} z_{(t)} + e^{s_1 t} D z_{(t)} = e^{s_1 t} (D + s_1) z_{(t)}$$

$$D^2(e^{s_1 t} z_{(t)}) = D(e^{s_1 t} (D + s_1) z_{(t)}) = e^{s_1 t} (D + s_1)(D + s_1) z_{(t)}$$

$$[P_{(D)}](e^{s_1 t} z_{(t)}) = e^{s_1 t} P_{(D+s_1)} z_{(t)}$$

$$P_{(D+s_1)} = D^{k_1} \dots (D + s_1 - s_j)^{k_2} \rightarrow$$

$$(D^{k_1} \dots (D + s_1 - s_j)^{k_2}) z_{(t)} = 0 \rightarrow (-D^{k_1}) z_{(t)} = 0 \rightarrow$$

$$z_{(t)} = \{1, t, \dots, t^{k_1-1}\} \rightarrow y_{(t)}^H = \{e^{s_1 t}, t e^{s_1 t}, \dots, t^{k_1-1} e^{s_1 t}\}$$

اگر  $f_{(t)}$  بصورت  $Q_{(t)} e^{bt}$  باشد در این صورت جواب خصوصی

می شود:  $y_{(t)}^P = \tilde{Q}_{(t)} e^{bt}$    
 اگر  $P_{(b)} \neq 0$  درجه اول از ریشه است

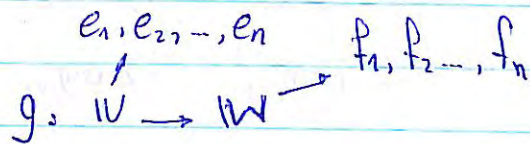
$$P_{(D)}[e^{bt} \tilde{Q}_{(t)}] = e^{bt} [P_{(D+b)}] \tilde{Q}_{(t)} = e^{bt} Q_{(t)} \rightarrow$$

$$[P_{(D+b)}] \tilde{Q} = Q$$

اگر  $e_1, \dots, e_n$  خط مستقل باشند و هر  $u$  به این مجموعه اضافه کنیم خط وابسته شود می توان ثابت کرد هر برداری را می توان بر حسب  $e_1, \dots, e_n$  نوشت و این نوشت.

اگر برداری داشته باشیم در فضای هر برداری را می توانیم بر حسب آن بنویسیم تمامی بردارهای فضای خط وابسته اند.

نقد و بعد قضاست.



$g(\alpha u + \beta v) = \alpha g(u) + \beta g(v)$  خطی

$g(u) = g(\sum_i u_i e_i) = \sum_i u_i g(e_i) = \sum_{i,a} u_i g_{ai} f_a =$

$\sum_a [g(u)]_a f_a \rightarrow [g(u)]_a = \sum_i g_{ai} u_i$

$\det[P_{est}] = 0$

۱۷ بردارها

IF میدان

+

x

بنده  
جانب چپ  
شماره تدریس  
عضو ضعیف  
عضو دایره

بنده  
جانب چپ  
شماره تدریس  
عضو ضعیف

کس

$IF \times V \rightarrow V$

$a \times v = v \times a \rightarrow$  تعریف نزن دادن است

$a'x'(b \times u) = (a \times b)x'u$

$(a+b)x'u = (ax'u) + (bx'u)$

$a \times (u+v) = a \times u + a \times v$

$1 \times u = u$

$\sum_i \alpha_i f_i = 0$  خط مستقل اند اگر  $\alpha_i$  ها صفر نباشند

$w \in \text{img}(T) \quad f_1, \dots, f_k \in \text{img}(T) \text{ است}$

$w = \sum_a w_a f_a \quad \exists e_a \in U \quad T(e_a) = f_a$

$U \supset e_1, \dots, e_k$

$\alpha_1 e_1 + \dots + \alpha_k e_k = 0 \rightarrow \alpha_1 T e_1 + \dots + \alpha_k T e_k = 0 \rightarrow$

$\alpha_1 f_1 + \dots + \alpha_k f_k = 0$

$A_{(t)} = a \cos(\omega t + \varphi) = \text{Re} [a e^{i\varphi} e^{-i\omega t}] = \text{Re} (A e^{-i\omega t})$

$V_{(t)} = R I_{(t)} \quad , \quad \text{Re}(V e^{-i\omega t}) = R \text{Re}(I e^{-i\omega t})$

$\rightarrow V = R I$

با در نظر گرفتن حالت چرخشی با سرعت  $\omega$

$d\phi = k \frac{(\vec{r} - \vec{r}') \cdot \vec{r}}{|\vec{r} - \vec{r}'|^3} \quad , \quad \vec{p} \Delta V = \vec{f}$

در فضای 3 بعدی

$g_{(ei)} = \sum_a g_{ai} f_a$

$h: U \rightarrow W \quad g \circ h: U \rightarrow W$   
 $\downarrow$   
 $d_1, \dots, d_k$

$(g \circ h)(d_\alpha) = g[h(d_\alpha)] = g\left[\sum_i h_{i\alpha} e_i\right] = \sum_i h_{i\alpha} g(e_i)$

$= \sum_{i,a} h_{i\alpha} g_{ai} f_a = \sum_a (g \circ h)_{a\alpha} f_a$

$(g \circ h)_{a\alpha} = \sum_i h_{i\alpha} g_{ai} = \sum_i g_{ai} h_{i\alpha}$

$T: U \rightarrow W$



$\text{ker}(T) = \{u \in U \mid T u = 0\}$

$\text{img}(T) = \{T u \mid u \in U\}$

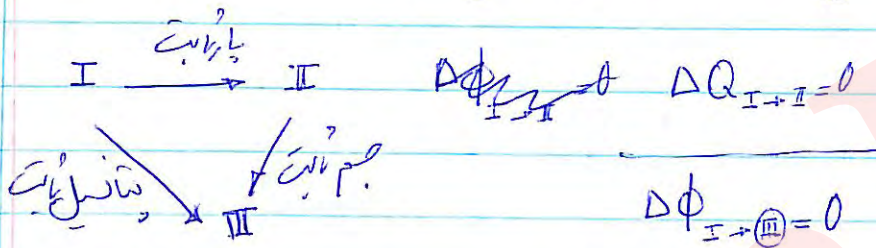
$\dim(\text{dom}(T)) = \dim(\text{ker}(T)) + \dim(\text{img}(T))$

در این

$$= \sum_j \vec{P}_j \partial_i \vec{E}_j = \sum_j \epsilon_0 \chi \vec{E}_j \partial_i \vec{E}_j = \frac{\epsilon_0 \chi}{2} \sum_j \partial_i (\vec{E}_j \cdot \vec{E}_j)$$

$$\vec{F} = \frac{\epsilon_0 \chi}{2} \int \sum_j \partial_i (E_j^2) dx dy dz$$

در آنجا که  
 اگرچه  $\chi$  به اندازه‌ی کافی نزدیک به صفر است و نیروی  $z$  و  $y$  صفری خواهند بود  
 در همین جهت که ای به لبه‌ی دیگر نزدیک نباشد.



$$\Delta \phi_{II \rightarrow III} = 0, \Delta Q_{II \rightarrow III} = \Delta Q_{I \rightarrow III} \quad \Delta \phi_{I \rightarrow III} = \Delta \phi_{I \rightarrow II}$$

$$\Delta \phi_{II \rightarrow III} = -\Delta \phi_{I \rightarrow II}$$

$$\Delta U_{I \rightarrow III} = \Delta U_{I \rightarrow II} + \Delta U_{II \rightarrow III} = \frac{1}{2} Q \phi_{I \rightarrow II} +$$

$$\frac{1}{2} (\phi \Delta Q_{II \rightarrow III} + Q \Delta \phi_{II \rightarrow III}) = \frac{1}{2} Q \Delta \phi_{I \rightarrow II} + Q \Delta \phi_{II \rightarrow III}$$

$$m \ddot{\vec{r}} = q \vec{E} - m \gamma \dot{\vec{r}} - m \omega_0^2 \vec{r}$$

$$\rightarrow \vec{r}_f = \frac{q \vec{E}_f}{m(\omega_0^2 - \omega^2 - i \gamma \omega)} \rightarrow \vec{f} = \frac{n q^2 \Delta U}{m(\omega_0^2 - \omega^2 - i \gamma \omega)}$$

$$\rightarrow \chi = \frac{n q^2}{m \epsilon_0 (\omega_0^2 - \omega^2 - i \gamma \omega)}, \quad \chi = \sum \frac{n_a q_a^2}{m_a \epsilon_0 (\omega_a^2 - \omega^2 - i \gamma_a \omega)}$$

$$\sum f_a = 1, \quad \frac{n_a}{n} = \frac{f_a}{f} \rightarrow \chi = \frac{n q^2}{\epsilon_0 m} \sum \frac{f_a}{\omega_a^2 - \omega^2 - i \gamma_a \omega}$$

$$\rightarrow \omega = 0: \chi = \frac{n q^2}{m \epsilon_0} \sum \frac{f_a}{\omega_a^2} > 0 \rightarrow \text{البته اگر } \omega \text{ صفر شود}$$

نیز توانیم صفر بکنیم.

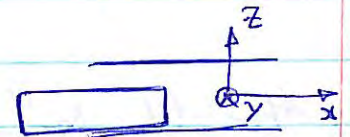
$$\omega_0 = 0, \quad \omega \rightarrow 0$$

$$\rightarrow -i \omega \chi = \frac{n q^2}{\epsilon_0 m} \times \frac{f_0}{\gamma_0} \xrightarrow{\frac{n q^2}{\epsilon_0}} \vec{f} = \left( \frac{f_0 n q^2}{m \gamma_0} \right) \vec{E}$$

$$-i \omega \chi \vec{E} \Rightarrow \frac{d\vec{r}}{dt}$$

$$\omega \rightarrow \infty, \quad \chi = -\frac{n q^2}{m \epsilon_0 \omega^2} < 0$$

$$\vec{f} = \vec{P} \cdot \nabla \vec{E} \Rightarrow \sum_j \vec{P}_j \partial_j \vec{E}_i = \vec{f}_i$$

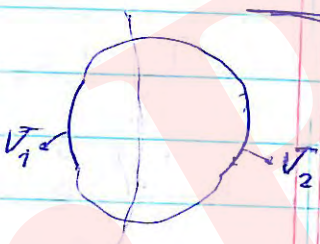


$$\vec{E} = \hat{n}(\vec{E}_0 \cdot \hat{n}) + \hat{t}(\vec{E}_0 \cdot \hat{t}) = \frac{\hat{n}(\vec{E}_0 \cdot \hat{n})\epsilon_0}{\epsilon} + \hat{t}(\vec{E}_0 \cdot \hat{t})$$

$$= \vec{E}_0 + (\hat{n}(\vec{E}_0 \cdot \hat{n}))\left(\frac{\epsilon_0}{\epsilon} - 1\right)$$

$$\vec{P} = (\epsilon - \epsilon_0)\vec{E} = (\epsilon - \epsilon_0)\left(\vec{E}_0 + \frac{\epsilon_0 - \epsilon}{\epsilon}\hat{n}(\vec{E}_0 \cdot \hat{n})\right) \rightarrow$$

$$\vec{U} = -\frac{1}{2}V\left[(\epsilon - \epsilon_0)\vec{E}_0 \cdot \vec{E}_0 - \frac{(\epsilon - \epsilon_0)^2}{\epsilon}(\vec{E}_0 \cdot \hat{n})^2\right]$$

$$\begin{cases} \vec{\nabla} \cdot (\epsilon \vec{E}) = 0 \\ \vec{\nabla} \cdot (\epsilon_0 \vec{E}) = 0 \end{cases} \xrightarrow{b_{(r)} = \alpha \epsilon_{(r)}} \phi_1 = \phi_2$$


$$\mathcal{I} = \int b \vec{E}_0 \cdot d\vec{s} = \alpha \int \epsilon \vec{E} \cdot d\vec{s} = \alpha Q \rightarrow RC = \frac{1}{\alpha}$$

$$\begin{cases} \vec{\nabla} \cdot \vec{P} = -\rho_b \\ \vec{P} \cdot \hat{n} = b_b \end{cases}, \vec{P} = \epsilon_0 \chi \vec{E}$$

$$\begin{cases} \vec{P} = \sum_{n=1}^{\infty} \chi^n \vec{P}_{n-1} \\ \vec{E} = \sum_{n=1}^{\infty} \chi^{n-1} \vec{E}_{n-1} \end{cases} \rightarrow \vec{P}_n = \epsilon_0 \vec{E}_{n-1}$$

$$= -\frac{1}{2} Q \Delta \phi_{I \rightarrow II} = -\Delta U_{I \rightarrow II}$$

$$F = -\frac{\partial U}{\partial z} \Big|_{z=0} = \frac{\partial U}{\partial z} \Big|_{z=L} \quad , \quad U = \frac{1}{2} \int \rho \phi \, dV$$

$$U = \frac{1}{2} \int \vec{E}_0 \cdot \vec{D} \, dV \rightarrow \frac{1}{2} \left[ \int \vec{E}_0 \cdot \vec{D} \, dV - \int \vec{E}_0 \cdot \vec{D}_0 \, dV \right] = \vec{U}$$

$$\vec{U} = U - U_0$$

برای محاسبه انرژی الکتریکی در فضای آزاد، باید از انرژی الکتریکی در فضای آزاد کم کرد.

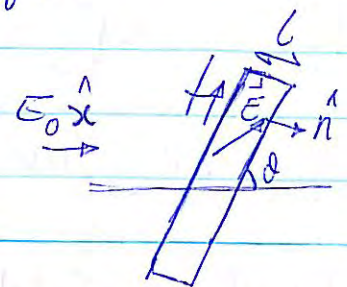
$$\Rightarrow \vec{U} = \frac{1}{2} \left[ \int \phi \vec{\nabla} \cdot \vec{D} \, dV - \int \phi_0 \vec{\nabla} \cdot \vec{D}_0 \, dV \right] =$$

$$\frac{1}{2} \left[ \int \phi \vec{\nabla} \cdot \vec{D}_0 \, dV - \int \phi_0 \vec{\nabla} \cdot \vec{P} \, dV \right] = \frac{1}{2} \left[ \int (\vec{E}_0 \cdot \vec{D} - \vec{E}_0 \cdot \vec{D}_0) \, dV \right]$$

$$= \frac{1}{2} \int \vec{E}_0 \cdot (\epsilon \vec{E} - \vec{D}) \, dV = -\frac{1}{2} \int \vec{E}_0 \cdot \vec{P} \, dV$$

$$\vec{E}_0 \cdot \hat{t} = \vec{E} \cdot \hat{t}$$

$$\epsilon_0 \vec{E}_0 \cdot \hat{n} = \epsilon \vec{E} \cdot \hat{n}$$



معادلات حرکت

$$\begin{cases} m \frac{dv_x}{dt} = q B v_y \\ m \frac{dv_y}{dt} = -q B v_x \end{cases} \rightarrow m \frac{d}{dt} (v_x + i v_y) = -i q B (v_x + i v_y)$$

$$\rightarrow (v_x + i v_y)_{(t)} = \underbrace{(v_x + i v_y)_0}_{v_0 e^{i\varphi}} e^{-\frac{i q B}{m} t} \rightarrow \begin{cases} v_x = v_0 \cos(\varphi - \omega t) \\ v_y = v_0 \sin(\varphi - \omega t) \end{cases}$$

$$\vec{F}_B (q' \rightarrow q_1) = \frac{\mu_0 q q'}{4\pi} \frac{\vec{v}_x (\vec{v}'_x (\vec{r} - \vec{r}'))}{|\vec{r} - \vec{r}'|^3}, \quad \vec{F}_e (q' \rightarrow q_1) = \frac{q q' (\vec{r} - \vec{r}')}{4\pi \epsilon_0 |\vec{r} - \vec{r}'|^3}$$

$$\rightarrow F_B \sim \frac{v v'}{c^2} F_e$$

$$\vec{B} = \frac{\mu_0 I}{4\pi} \oint \frac{d\vec{r}' \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} = \frac{\mu_0 I}{4\pi} \vec{\nabla}_x \oint \frac{d\vec{r}'}{|\vec{r} - \vec{r}'|}$$

$$\int \frac{d\vec{r}'}{|\vec{r} - \vec{r}'|} = \int d\vec{r}' \left\{ \frac{1}{r} + \frac{\vec{r} \cdot \vec{r}'}{r^3} + \dots \right\} = \frac{1}{r_0} \int d\vec{r}' (\vec{r} \cdot \vec{r}') + \dots$$

$$\vec{a} \cdot \int d\vec{r}' (\vec{r} \cdot \vec{r}') = \int d\vec{r}' [\vec{a} (\vec{r} \cdot \vec{r}')] = \int ds' \cdot \vec{\nabla}_x [\vec{a} (\vec{r} \cdot \vec{r}')] = \int ds' \cdot (\vec{r} \times \vec{a}) = \int (ds' \times \vec{r}) \cdot \vec{a}$$

$$= \int ds' \cdot (\vec{r} \times \vec{a}) = \int (ds' \times \vec{r}) \cdot \vec{a}$$

مفادیر

$$\vec{F}_B = q \vec{F}_B$$

(1) شاهد:  $q$

(2) شاهد: عدد برابری و ضرب با آن

$$(F_B)_i = q \sum_j B_{ij} v_j \rightarrow \sum_{i,j} v_i v_j B_{ij} = 0$$

$$\rightarrow \sum_{i,j} (v_i + v_i)(v_j + v_j) B_{ij} = 0 \rightarrow \sum_{i,j} (v_i v_j + v_j v_i) B_{ij} = 0$$

$$\rightarrow \sum_{i,j} v_i v_j (B_{ij} + B_{ji}) = 0 \rightarrow \text{باید ماتریس با متقارن است}$$

$$B = \begin{pmatrix} 0 & B_3 & -B_2 \\ -B_1 & 0 & B_1 \\ B_2 & -B_3 & 0 \end{pmatrix}$$

$$\sum_{i,j} v_i v_j B_{ij} = \sum_{i,j} v_i v_j B_{ji}$$

$$\rightarrow \vec{F} = q \vec{v} \times \vec{B}$$

$$\vec{E}' = q (\vec{E}' + \vec{v}' \times \vec{B}') = q (\vec{E}' + \vec{v}' \times \vec{B})$$

$$\vec{B} = \vec{B}', \quad \vec{E}' = \vec{E} - \vec{v}' \times \vec{B}$$



$$\frac{\partial}{\partial r_j} (r_i r_k)$$

$$\sum_j \int (r_k \frac{\partial r_i}{\partial r_j} + r_i \frac{\partial r_k}{\partial r_j}) j_j dV =$$

$$\sum_j \int dV \left[ \frac{\partial}{\partial r_j} (r_i r_k j_j) - r_i r_k \frac{\partial j_j}{\partial r_j} \right] = 0$$

$$\int r_i r_k j \cdot ds \quad \nabla \cdot j$$

$$\epsilon_{ijk} = \begin{cases} 1 & \text{جایگاری 123} \\ -1 & \text{جایگاری 321} \\ 0 & \text{در صورتی که یکی از اعداد تکرار شود} \end{cases}$$

$$(\vec{A} \times \vec{B})_i = \sum_{j,k} \epsilon_{ijk} A_j B_k$$

$$A_i B_j - A_j B_i = \sum_k \epsilon_{ijk} (\vec{A} \times \vec{B})_k$$

$$I = 0 + \sum_j \epsilon_{kij} \int \frac{1}{2} (\vec{r}_k j_j) dV = \sum_j \epsilon_{kij} m_j$$

$$\vec{B} = \vec{\nabla} \times \left\{ 0 + \frac{\mu_0}{4\pi r^3} \sum_k r_k \sum_j \epsilon_{ijk} m_j + \dots \right\} \rightarrow$$

$$\vec{B} = \vec{\nabla} \times \left( \frac{\mu_0}{4\pi r^3} \vec{m} \times \vec{r} \right)$$

$$\rightarrow \int \frac{d\vec{r}'}{|\vec{r} - \vec{r}'|^3} = \int \frac{ds \times \vec{r}'}{r^3} \Rightarrow \vec{B} = \frac{\mu_0}{4\pi} \vec{\nabla} \times \left( \frac{\vec{m} \times \vec{r}}{r^3} \right)$$

$$= \frac{\mu_0}{4\pi} \left\{ \vec{m} \cdot \vec{\nabla} \cdot \left( \frac{\vec{r}}{r^3} \right) - \vec{m} \cdot \nabla \left( \frac{1}{r^3} \right) \right\} = \frac{\mu_0}{4\pi} \left( -\frac{\vec{m}}{r^3} + \frac{3\vec{r}(\vec{m} \cdot \vec{r})}{r^5} \right)$$

$$\rightarrow \vec{B} = \frac{\mu_0}{4\pi} \frac{3\vec{r}(\vec{r} \cdot \vec{m}) - \vec{m} r^2}{r^3}, \quad \nabla' \cdot (\vec{r} \cdot \vec{r}') = 1$$

$$\vec{B}_{(\vec{r})} = \vec{\nabla} \times \left\{ \frac{\mu_0}{4\pi} \int dV' \frac{j(\vec{r}')}{|\vec{r} - \vec{r}'|^3} \right\}, \quad \frac{1}{|\vec{r} - \vec{r}'|^3} = \frac{1}{r} + \frac{\vec{r} \cdot \vec{r}'}{r^3} + \dots$$

$$\int j_i(\vec{r}') dV' = \int dV' \sum_j \delta_{ij} j_j(\vec{r}') = \int dV' \sum_j \left[ \frac{\partial r_i}{\partial r_j} j_j(\vec{r}') \right] =$$

$$\int dV' \sum_j \left\{ \frac{\partial}{\partial r_j} [r_i j_j(\vec{r}')] - r_i \frac{\partial j_j}{\partial r_j} \right\} = 0$$

$$\nabla' \cdot (r_i \vec{j}) - r_i \nabla' \cdot \vec{j}$$

$$\int \sum_k r_k r'_k j_i(\vec{r}') dV' = \sum_k r_k \int r'_k j_i(\vec{r}') dV'$$

$$\int r'_k j_i(\vec{r}') dV' = \frac{1}{2} \int (r_k j_i + r_i j_k) dV + \frac{1}{2} \int (r_k j_i - r_i j_k) dV = I$$

$$\int (r_k j_i + r_i j_k) dV = \sum_j \int (r_k \delta_{ij} + r_i \delta_{jk}) j_j =$$

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{[\vec{r}' \times \vec{j}(\vec{r}')] \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dV'$$

$$\vec{B} = \nabla \times \vec{A} \rightarrow \nabla \cdot \vec{B} = 0 \rightarrow \vec{B} = \nabla \times \vec{A}' \rightarrow \vec{A}' - \vec{A} = \nabla \chi$$

$$\oint \vec{B} \cdot d\vec{s} = 0$$

$$\vec{F} = \int \vec{j} \times \vec{B} dV = \int \vec{j}_{(\vec{r})} \times [\vec{B}_0 + (\vec{r} - \vec{r}_0) \cdot \nabla \vec{B}_0 + \dots] dV$$

$$\Rightarrow F_i = \sum_{jk} \epsilon_{ijk} \int j_j \sum_l r_l \frac{\partial B_k}{\partial r_l} dV + \dots$$

$$= \sum_{jkl} \epsilon_{ijk} \frac{\partial B_k}{\partial r_l} \int dV (r_l j_j + \dots) = \sum_{j,k,l,n} \epsilon_{ijk} \epsilon_{ijn} \frac{\partial B_k}{\partial r_l} m_n$$

$$= \sum_{k,l,n} (\delta_{il} \delta_{kn} - \delta_{ln} \delta_{kl}) \frac{\partial B_k}{\partial r_l} m_n + \dots = \sum_k \frac{\partial B_k}{\partial r_i} m_k$$

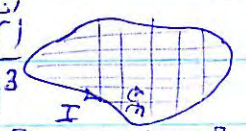
$$\rightarrow \vec{F} = \nabla (\vec{m} \cdot \vec{B})$$

$$\nabla \times \vec{B} = 0 \text{ اگر } \sum_k \frac{\partial B_k}{\partial r_i} m_k = \sum_k \frac{\partial B_i}{\partial r_k} m_k = (\vec{m} \cdot \nabla) B_i$$

$$\vec{m} = \int \frac{1}{2} (\vec{r} \times \vec{j}) dV = \int I d\vec{s}$$

$$\vec{j} = \rho_e \vec{v}, \text{ اگر } \rho_e = \rho_m \vec{v} \text{ باشد } \frac{q}{m} = \frac{v}{v}$$

$$\rightarrow \vec{m} = \frac{1}{2} \frac{q}{m} \vec{L}$$

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int dV' \frac{\vec{j}(\vec{r}')}{|\vec{r} - \vec{r}'|} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{s}' \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$


$$\rightarrow \vec{B}(\vec{r}) = \frac{\mu_0 I}{4\pi} \int \frac{3(\vec{r} - \vec{r}')((\vec{r} - \vec{r}') \cdot d\vec{s}') - [(\vec{r} - \vec{r}') \cdot (\vec{r} - \vec{r}')] d\vec{s}'}{|\vec{r} - \vec{r}'|^5}$$

$$\rightarrow \vec{B}(\vec{r}) = -\nabla \left\{ \frac{\mu_0 I}{4\pi} \int \frac{(\vec{r} - \vec{r}') \cdot d\vec{s}'}{|\vec{r} - \vec{r}'|^3} \right\}$$

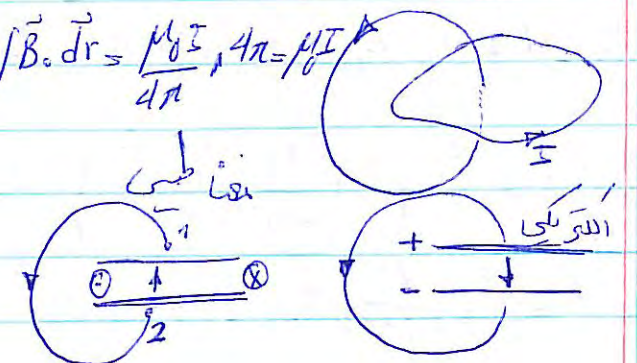
اینجا در صورتی که  $\vec{r}$  در بیرون حلقه باشد

$$\rightarrow \vec{B}(\vec{r}) = +\nabla \left\{ \frac{\mu_0 I}{4\pi} \Omega \right\} \rightarrow \vec{B}(\vec{r}) = +\frac{\mu_0 I}{4\pi} \nabla \Omega$$

اینجا در صورتی که  $\vec{r}$  در درون حلقه باشد

$$\int \vec{E} \cdot d\vec{r} = 0, \int \vec{B} \cdot d\vec{r} = \frac{\mu_0 I}{4\pi} \cdot 4\pi = \mu_0 I$$

$$\int_1^2 \vec{B} \cdot d\vec{r} = \phi_{m_1} - \phi_{m_2}$$



$$[\det(R)]^2 = 1 \rightarrow \det R = \pm 1$$

$$M\vec{u} = \lambda\vec{u} \xrightarrow{\text{بردار} \rightarrow \text{عدد}} (M - \lambda I)\vec{u} = 0 \rightarrow$$

$$\det(M - \lambda I) = 0 \quad \text{اگر برده بردار } \lambda \text{ و برده مقدار}$$

$$0 = n \text{ جمله اس از درجه } n$$

$$(M - \lambda_1 I)(M - \lambda_2 I) \dots (M - \lambda_n I) = 0 \quad \text{تصیی}$$

$$(R\vec{u}) \cdot (R\vec{u}) = \vec{u} \cdot \vec{u} \rightarrow (R\vec{u}^*) \cdot (R\vec{u}) = \vec{u}^* \cdot \vec{u}$$

$$\text{فرض: } R\vec{u} = \lambda\vec{u} \rightarrow R\vec{u}^* = \lambda^* \vec{u}^*$$

$$\rightarrow (\lambda^* \vec{u}^*) \cdot (\lambda \vec{u}) = \vec{u}^* \cdot \vec{u} \rightarrow (\lambda^* \lambda - 1) \underbrace{(\vec{u}^* \cdot \vec{u})}_{> 0} = 0$$

$$\rightarrow \lambda \lambda^* = 1 \rightarrow |\lambda| = 1$$

$$\det(R - \lambda I) = 0 \rightarrow (R_{11} - \lambda_1)(R_{22} - \lambda_2)(R_{33} - \lambda_3) = 0$$

اگر دو جریان <sup>حقیقی</sup> داشته باشیم که در یک سیم زغنه اند می توانیم با فرمول دو قطبی معادله را برقرار می کنیم

$$\vec{J} \rightarrow T_{\vec{a}} \vec{J} \quad (T_{\vec{a}} \vec{J})(\vec{r}) = \vec{J}(\vec{r} - \vec{a})$$

$$\vec{B} \rightarrow T_{\vec{a}} \vec{B} \quad (T_{\vec{a}} \vec{B})(\vec{r}) = \vec{B}(\vec{r} - \vec{a})$$

$$\vec{J} \rightarrow \vec{J}_{(\vec{r})} = (R(\vec{J}))(R^{-1}(\vec{r})), \quad (R\vec{u}) \cdot (R\vec{v}) = \vec{u} \cdot \vec{v}$$

$$\sum_{i,j} u_i u_j \delta_{ij} = \sum_{i,j} \left( \sum_k R_{ik} u_k \right) \left( \sum_l R_{jl} u_l \right) \delta_{ij}$$

$$= \sum_{k,l} \delta_{k,l} u_k u_l \quad \sum_{i,j} R_{ik} R_{jl} \delta_{ij} = \delta_{k,l}$$

$$\sum_i (R^{-1})_{ki} R_{il} = \delta_{kl} \rightarrow \sum_i (R^{-1})_{ki} R_{il} = \delta_{kl}$$

$$(R^{-1})_{ki} = R_{ik} \rightarrow \det(R^{-1}) = \det(R)$$

$$\det(AB) = (\det A)(\det B) \rightarrow \det(RR^{-1}) = 1 = \det R \det R^{-1}$$

$$= \sum_{i=2}^3 R'_{i2} e_i \quad \text{نویس خطی}$$

$$u, v \in \text{span}(e_2, e_3)$$

$$R\vec{u} = R'\vec{u} \quad , \quad R\vec{v} = R'\vec{v}$$

$$\vec{u} \cdot \vec{v} = (R\vec{u}) \cdot (R\vec{v}) = (R'\vec{u}) \cdot (R'\vec{v})$$

$$R = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \boxed{R'} \\ 0 & & \end{bmatrix}$$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} a & c \\ b & d \end{pmatrix} = \begin{pmatrix} a^2+b^2 & ac+bd \\ ac+bd & c^2+d^2 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$a^2+b^2=1 \quad , \quad c^2+d^2=1 \quad , \quad ac+bd=0$$

$$a = \cos\theta \rightarrow b = \pm \sin\theta = s \sin\theta \rightarrow d = \alpha \cos\theta \quad , \quad \alpha = \pm 1$$

$$\rightarrow c = -\alpha s \sin\theta \rightarrow R' = \begin{pmatrix} \cos\theta & s \sin\theta \\ -\alpha s \sin\theta & \alpha \cos\theta \end{pmatrix} \rightarrow \det R' = \alpha$$

$$\rightarrow \alpha=1: \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \quad \alpha=-1: \begin{pmatrix} \cos\theta & \sin\theta \\ \sin\theta & -\cos\theta \end{pmatrix}$$

$$s=1 \quad \quad \quad s=-1$$

$$(\lambda - \lambda_1)(\lambda - \lambda_2)(\lambda - \lambda_3) = 0 \rightarrow \lambda^3 + a\lambda^2 + b\lambda + c = 0$$

$$\rightarrow c = \det(R) = -\lambda_1 \lambda_2 \lambda_3 \quad , \quad \text{و}$$

$$a, b, c \text{ صحیح} \rightarrow (\lambda^*)^3 + a(\lambda^*)^2 + b\lambda^* + c = 0 \rightarrow$$

اگر  $\lambda$  مختلف داشته باشیم  $\lambda^*$  هم جواب است پس

$$\text{دیگری 1 است. } (\det(R)=1)$$

$$\text{متغیر حرف های با } (\det(R)=-1)$$

$$(R\vec{u}) \cdot (R\vec{v}) = \vec{u} \cdot \vec{v} \quad , \quad \vec{u} \cdot \vec{v} = 0 \quad , \quad \vec{u} \cdot \vec{v} = 0$$

$$\lambda (R\vec{u}) \cdot \vec{v} = \vec{u} \cdot \vec{v} = 0 \rightarrow (R\vec{u}) \cdot \vec{v} = 0$$

$$\text{چون } R e_1 = e_1, e_2, e_3$$

$$R e_j = \sum_i R_{ij} e_i \rightarrow R e_2 = \sum_i R_{i2} e_i = \sum_{i=2}^3 R_{i2} e_i$$

$$+ B_3 (\vec{R}^{-1} \vec{r}) [\hat{j}(\vec{R}^{-1} \vec{r})] \} = B_1 (\vec{R}^{-1} \vec{r}) \hat{p} + B_2 (\vec{R}^{-1} \vec{r}) \hat{\psi} + B_3 (\vec{R}^{-1} \vec{r}) \hat{z}$$

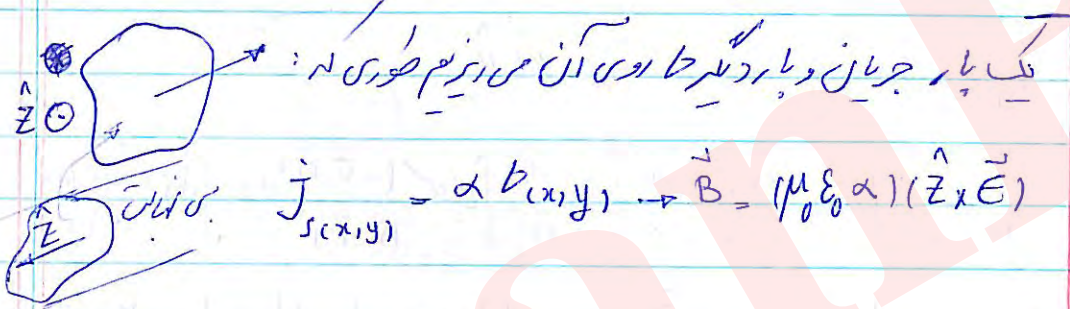
$$R (\hat{p}(\vec{R}^{-1} \vec{r})) = \hat{p}(\vec{r})$$

$$(\vec{R} \vec{j})(\vec{R}^{-1} \vec{r}) = -\vec{j} \rightarrow (\vec{R} \vec{B})(\vec{R}^{-1} \vec{r}) = -\vec{B}(\vec{r}) \rightarrow B_z = 0$$

$$\rightarrow \vec{B} = B_p \hat{\psi}$$

R انقاس نسبت به محور z

توان کمتر + دایره انقاس نسبت به محور z →  $\vec{j}_\varphi = 0$



$$\vec{A} = \frac{\mu_0}{4\pi} \int dV' \frac{\vec{M}(\vec{r}') \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} = \frac{\mu_0}{4\pi} \int dV' \vec{M}(\vec{r}') \times \nabla' \left( \frac{1}{|\vec{r} - \vec{r}'|} \right)$$

$$\frac{\mu_0}{4\pi} \int dV' \left\{ -\nabla' \left[ \frac{\vec{M}(\vec{r}')}{|\vec{r} - \vec{r}'|} \right] + \frac{(\nabla' \times \vec{M})_{(\vec{r}')}}{|\vec{r} - \vec{r}'|} \right\}$$

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{(\vec{R} \vec{j})(\vec{R}^{-1} \vec{r}) \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dV'$$

$$\vec{R} \vec{r}' = \vec{r}'' \rightarrow \vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{(\vec{R} \vec{j})(\vec{R}^{-1} \vec{r}'') \times (\vec{r} - \vec{r}'')}{|\vec{r} - \vec{r}''|^3} dV''$$

$$\frac{\mu_0}{4\pi} \int \frac{[\vec{R} \vec{j}(\vec{r}'')] \times [\vec{R}(\vec{R}^{-1} \vec{r} - \vec{r}'')]}{[R(\vec{R}^{-1} \vec{r} - \vec{r}'')]^3} dV''$$

$$= \frac{\mu_0}{4\pi} (\det R) R \int dV'' \frac{[\vec{j}(\vec{r}'')] \times (\vec{R}^{-1} \vec{r} - \vec{r}'')}{|\vec{R}^{-1} \vec{r} - \vec{r}''|^3}$$

$$\rightarrow \vec{B}(\vec{r}) = (\det R) [(\vec{R} \vec{B})(\vec{R}^{-1} \vec{r})]$$

تقارن :  $S_{ij} = S_{ji}$  ،  $A_{ij} = -A_{ji}$  ،  $T_{ij} = T_{ji}$

$$T_{a\hat{z}} \vec{j} = \vec{j} \rightarrow T_{a\hat{z}} \vec{B} = \vec{B} \rightarrow B(\vec{r}, a\hat{z}) = B(\vec{r})$$

$$\vec{j}(\vec{R} \vec{B})(\vec{R}^{-1} \vec{r}) = \vec{B}(\vec{r}) = B_1(\vec{r}) \hat{p} + B_2(\vec{r}) \hat{\psi} + B_3(\vec{r}) \hat{z}$$

α نسبت به z

$$\rightarrow R \left\{ B_1(\vec{R}^{-1} \vec{r}) [\hat{p}(\vec{R}^{-1} \vec{r})] + B_2(\vec{R}^{-1} \vec{r}) [\hat{\psi}(\vec{R}^{-1} \vec{r})] \right\}$$

$$\frac{\partial}{\partial t} \Big|_{\vec{r}} = \frac{\partial}{\partial t} \quad , \quad \frac{\partial}{\partial t'} \Big|_{\vec{r}'} = \frac{\partial}{\partial t'}$$

$$(\vec{r}, t) \rightarrow (\vec{r}', t') \quad , \quad t = t' \quad , \quad \vec{r}' = \vec{r} + \vec{v}t \quad , \quad \vec{r} = \vec{r}' - \vec{v}t'$$

$$\frac{\partial}{\partial t'} = \frac{\partial t}{\partial t'} \frac{\partial}{\partial t} + \sum_i \frac{\partial r_i}{\partial t'} \frac{\partial}{\partial r_i} = \frac{\partial}{\partial t} - \sum_i v_i \frac{\partial}{\partial r_i}$$

$$\frac{\partial}{\partial r'_i} = \frac{\partial t}{\partial r'_i} \frac{\partial}{\partial t} + \sum_j \frac{\partial r_j}{\partial r'_i} \frac{\partial}{\partial r_j} = \frac{\partial}{\partial r_i}$$

$$\rightarrow \frac{\partial}{\partial t'} = \frac{\partial}{\partial t} - \vec{v} \cdot \vec{\nabla} \quad , \quad \vec{\nabla}' = \vec{\nabla}$$

$$\vec{\nabla}' \cdot (\vec{B}'(\vec{r}', t)) = \vec{\nabla} \cdot (\vec{B}(\vec{r}, t)) = 0 \quad \checkmark$$

$$\vec{\nabla}' \times \vec{E}' = \vec{\nabla}' \times (\vec{E} - \vec{v} \times \vec{B}) = \vec{\nabla}' \times \vec{E} - \vec{v} (\vec{\nabla}' \cdot \vec{B}) + (\vec{v} \cdot \vec{\nabla}') \vec{B}$$

$$\rightarrow \vec{\nabla}' \times \vec{E}' = \vec{\nabla}' \times \vec{E} + (\vec{v} \cdot \vec{\nabla}') \vec{B}$$

$$\frac{\partial \vec{B}}{\partial t} = 0 = \frac{\partial \vec{B}'}{\partial t'} + (\vec{v} \cdot \vec{\nabla}') \vec{B}' \quad \rightarrow \vec{\nabla}' \times \vec{E}' = - \frac{\partial \vec{B}'}{\partial t'} \quad \checkmark$$

$$\vec{a} \cdot \int dV (\vec{\nabla} \times \vec{c}) = \int dV \vec{\nabla} \cdot (\vec{c} \times \vec{a}) = \oint dS \cdot (\vec{c} \times \vec{a}) = \vec{a} \cdot \oint dS \times \vec{c}$$

$$(\vec{\nabla} \times \vec{c}) \cdot \vec{a} = \sum_{i,j,k} (\epsilon_{ijk} \partial_i c_j) a_k = \sum_i \partial_i \sum_{j,k} \epsilon_{ijk} c_j a_k = \sum_i \partial_i (\vec{c} \times \vec{a})_i$$

$$\nabla \cdot (\vec{A} \times \vec{B}) = \vec{\nabla} \cdot (\vec{A} \times \vec{B}) + \vec{\nabla} \cdot (\vec{A} \times \vec{B}) = \vec{B} \cdot (\vec{\nabla} \times \vec{A}) - \vec{A} \cdot (\vec{\nabla} \times \vec{B})$$

$$\rightarrow \vec{A}_{\text{بیرتی}} = \frac{\mu_0}{4\pi} \left[ \oint ds' \frac{\vec{M}_{(\vec{r}', t') \times \hat{n}'}}{|\vec{r} - \vec{r}'|} + \int dV' \frac{(\vec{\nabla}' \times \vec{M})_{(\vec{r}', t')}}{|\vec{r} - \vec{r}'|} \right]$$

$$\rightarrow \vec{j}_b = \vec{\nabla} \times \vec{M} \quad \vec{j}_{bs} = \vec{M} \times \hat{n}$$

$$p_M = -\vec{\nabla} \cdot \vec{M} \quad , \quad b_M = \vec{M} \cdot \hat{n}$$

$$\phi_M = \frac{\mu_0}{4\pi} \int dV' \frac{\vec{M}_{(\vec{r}', t')} \cdot (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} = \frac{\mu_0}{4\pi} \left[ \int dV' \frac{(-\vec{\nabla}' \cdot \vec{M})_{(\vec{r}', t')}}{|\vec{r} - \vec{r}'|} + \int ds' \frac{\hat{n}' \cdot \vec{M}_{(\vec{r}', t')}}{|\vec{r} - \vec{r}'|} \right]$$

شکل خطوط  $\vec{H}$  برای سیم لوله همان  $\vec{D}$  برای قضبان است.

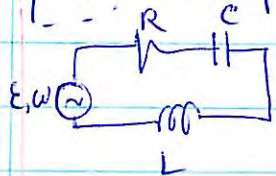
$$\vec{B}'_{(\vec{r}', t')} = \vec{B}_{(\vec{r}, t)} \quad , \quad \vec{E}'_{(\vec{r}', t')} = \vec{E}'_{(\vec{r}', t')} + \vec{v} \times \vec{B}'_{(\vec{r}', t')}$$

$$\vec{\nabla} \cdot \vec{B} = 0 \quad , \quad \vec{\nabla} \times \vec{E} = 0 \quad , \quad \frac{\partial \vec{E}}{\partial t} = 0 \quad , \quad \frac{\partial \vec{B}}{\partial t} = 0$$



$$-E + RI = \oint \vec{E} \cdot d\vec{r} = -\frac{d\psi_m}{dt} = -L \frac{dI}{dt}$$

چون L (خود القایی مدار) خطی نوب است مرتباً هم تقسیم و با هم تقسیم.

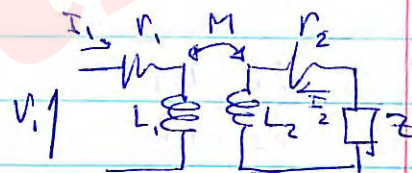


$$Z = \frac{E}{R - i\omega L + \frac{2}{\omega C}} = \frac{E}{R + i(\frac{1}{\omega C} - L\omega)}$$

$$\rightarrow \angle Z = \angle E + \tan^{-1}\left(\frac{\omega L - \frac{1}{\omega C}}{R}\right)$$

$$|Z| = \frac{|E|}{\sqrt{R^2 + (\omega L - \frac{1}{\omega C})^2}} \rightarrow I_{(t)} = |Z| \cos(\omega t - \angle Z - \tan^{-1}(\frac{\omega L - \frac{1}{\omega C}}{R}))$$

$$E = \text{Re}(E e^{i\omega t})$$



$$\nabla' \cdot \vec{E}' = \nabla' \cdot (\vec{E}' - \vec{v} \times \vec{B}') = \nabla' \cdot \vec{E}' + (\vec{v} \cdot \nabla') \vec{B}' =$$

$$- \left( \frac{\partial}{\partial t'} - \vec{v} \cdot \nabla' \right) \vec{B}' = - \frac{\partial \vec{B}'}{\partial t'}$$

$$\frac{\partial}{\partial t'} - \vec{v} \cdot \nabla' = \frac{\partial}{\partial t''}$$

$$\nabla' \cdot \vec{E}' + \frac{\partial \vec{B}'}{\partial t'} = 0, \quad \vec{B}' = \nabla' \times \vec{A}'$$

$$\nabla' \cdot (\vec{E}' + \frac{\partial \vec{A}'}{\partial t'}) = 0 \rightarrow \vec{E}' + \frac{\partial \vec{A}'}{\partial t'} = -\nabla' \phi' \rightarrow \vec{E}' = -\nabla' \phi' - \frac{\partial \vec{A}'}{\partial t'}$$

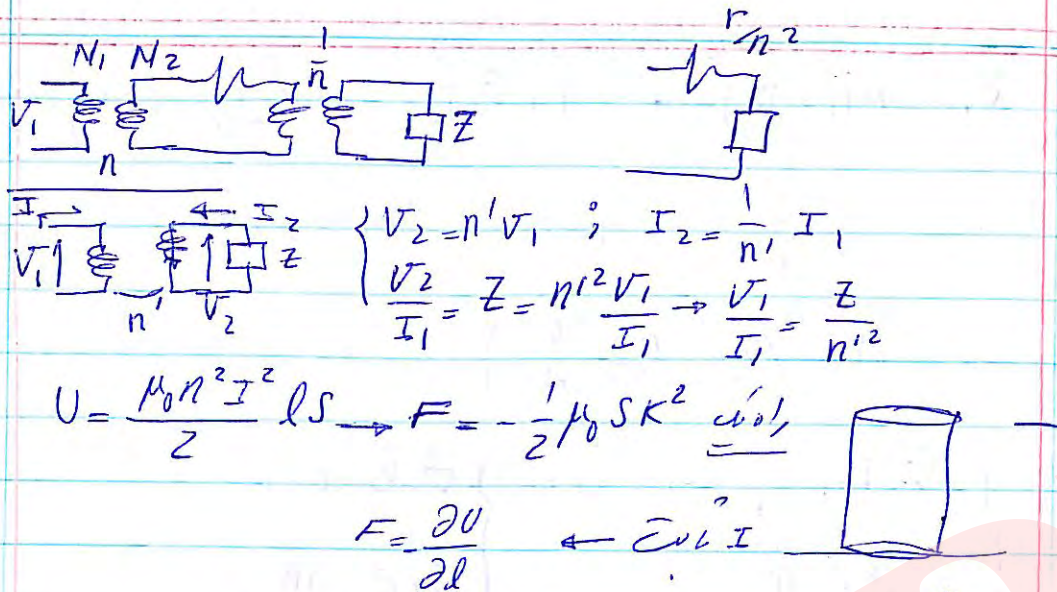
→  $\phi' = \phi - \frac{\partial \lambda}{\partial t}$  : اینجایم  $\vec{E}, \vec{B}$  تغییر کنند

$$\vec{A}' = \vec{A} + \nabla \lambda$$

$$emf = \oint (\vec{E}' + \vec{v} \times \vec{B}') \cdot d\vec{r} = - \int \frac{\partial \vec{B}'}{\partial t'} \cdot d\vec{s} + \oint (\vec{v} \times \vec{B}') \cdot d\vec{r}$$

$$= - \left[ \int \frac{\partial \vec{B}}{\partial t} \cdot d\vec{s} + \int (\vec{B} \times \vec{v}) \cdot d\vec{r} \right] = - \frac{d}{dt} \left( \int \vec{B} \cdot d\vec{s} \right)$$

$$\frac{d}{dt} \int \vec{B} \cdot d\vec{s} = \int \frac{\partial \vec{B}}{\partial t} \cdot d\vec{s} + \oint (\vec{v} \times d\vec{r}) \cdot \vec{B}$$

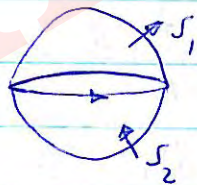


$$F_z = -2\pi a I n \int B_{z(\omega)} dz \quad \vec{\nabla} \cdot \vec{B} = 0 \quad F_z = 2\pi I n \int_0^a p dp \int \frac{\partial B_z}{\partial z} dz$$

$$B_z = 2\pi I n \int_0^a p dp [B_{z(\omega)} - B_{z(\omega)'}] = -\frac{5}{2} \mu_0 k^2$$

$$\int \vec{j} \cdot d\vec{s} = -\frac{d}{dt} \int p dV = -\frac{dQ_{(w)}}{dt}$$

$$\vec{\nabla} \cdot \vec{j} + \frac{\partial \rho}{\partial t} = 0$$



$$I_{s_1} + I_{s_2} = 0 \rightarrow I_{(S)} = 0 \rightarrow \vec{\nabla} \times \vec{B} = \mu_0 \vec{j} \quad \text{تسوية}$$

$$\begin{cases} V_1 = (r_1 - i\omega L_1) I_1 - i\omega M I_2 \\ V_2 = (r_2 - i\omega L_2) I_2 - i\omega M I_1 \end{cases}, \quad V_2 = -Z I_2$$

$$\rightarrow \frac{V_1}{V_2} = \frac{\omega^2 M^2 + (r_1 - i\omega L_1)(Z + r_2 - i\omega L_2)}{-i\omega M Z}$$

$$= \frac{\omega^2 (M^2 - L_1 L_2) - i\omega (L_1 Z + L_1 r_2 + L_2 r_1) + r_1 (Z + r_2)}{-i\omega M Z}$$

$$\rightarrow |M^2 - L_1 L_2| \approx 0$$

$$\frac{|L_1 Z + L_1 r_2 + L_2 r_1|}{L_1 L_2 - M^2} < \omega < \frac{(Z + r_2) r_1}{|L_1 Z + L_1 r_2 + L_2 r_1|}$$

$$\frac{L_1 |Z|}{L_1 L_2 - M^2} < \omega < \frac{r_1}{L_1}$$

$$L_1 r_2 + L_2 r_1 \ll L_1 |Z|$$

$$\rightarrow \frac{V_1}{V_2} = \frac{L_1}{M}$$



$$\rightarrow \frac{d\mathcal{E}_m}{dt} = -\frac{d}{dt} \left\{ \int \left( \frac{\epsilon_0}{2} \vec{E} \cdot \vec{E} + \frac{\vec{B} \cdot \vec{B}}{2\mu_0} \right) d\tau - \int \frac{\vec{E} \times \vec{B}}{\mu_0} \cdot d\vec{s} \right\}$$

$$u_e = \frac{\epsilon_0}{2} E^2 + \frac{1}{2\mu_0} B^2, \quad \vec{j} = \frac{\vec{E} \times \vec{B}}{\mu_0}$$

$$\frac{d\mathcal{E}_m}{dt} = \int \vec{j}_f \cdot \vec{E} d\tau = \int \left( -\vec{E} \cdot \frac{\partial \vec{D}}{\partial t} + (\vec{\nabla} \times \vec{H}) \cdot \vec{E} \right) d\tau$$

$$= \int \left[ -\vec{E} \cdot \frac{\partial \vec{D}}{\partial t} + \vec{H} \cdot \vec{\nabla} \times \vec{E} - \vec{\nabla} \cdot (\vec{E} \times \vec{H}) \right] d\tau =$$

$$- \int (\vec{E} \times \vec{H}) \cdot d\vec{s} - \int \left( \vec{E} \cdot \frac{\partial \vec{D}}{\partial t} + \vec{H} \cdot \frac{\partial \vec{B}}{\partial t} \right) d\tau$$

$$- \int (\vec{E} \times \vec{H}) \cdot d\vec{s} - \frac{\partial}{\partial t} \int \left( \frac{\vec{E} \cdot \vec{D}}{2} + \frac{\vec{H} \cdot \vec{B}}{2} \right) d\tau, \quad \text{برای محیط خطی}$$

$$\rightarrow u_e = \frac{\vec{E} \cdot \vec{D}}{2} + \frac{\vec{H} \cdot \vec{B}}{2} \quad \text{اما نه لزوماً همین}$$

$$\delta U_e = \int d\tau (\vec{E} \cdot \delta \vec{D} + \vec{H} \cdot \delta \vec{B})$$

$$\delta U_e + \delta \mathcal{E}_m = -\delta t \oint \vec{j}_e \cdot d\vec{s}$$

$$\vec{E} = \frac{-\vec{j}}{\epsilon_0}, \quad B_\varphi = \frac{\mu_0 \rho j}{2} \rightarrow \vec{j} = -\frac{\rho j^2}{2\epsilon_0} \hat{\rho} \quad \text{مثال}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 (\vec{j} + \vec{j}_D) \rightarrow \vec{\nabla} \cdot \vec{j} + \vec{\nabla} \cdot \vec{j}_D = 0 \rightarrow \vec{\nabla} \cdot \vec{j}_D - \epsilon_0 \vec{\nabla} \cdot \frac{\partial \vec{E}}{\partial t} = 0$$

$$\rightarrow \vec{j}_D = \epsilon_0 \frac{\partial \vec{E}}{\partial t} \quad \text{فرض کنیم} \quad \text{یا جریبی موجود}$$

$$\rightarrow \vec{\nabla} \times \vec{B} = \mu_0 \vec{j} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\begin{cases} \vec{\nabla} \cdot \vec{D} = \rho_f \\ \vec{\nabla} \times \vec{H} - \frac{\partial \vec{D}}{\partial t} = \vec{j}_f \end{cases} \quad \begin{cases} \vec{\nabla} \cdot \vec{B} = 0 \\ \vec{\nabla} \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0 \end{cases}$$

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B}) \rightarrow dW = q\vec{v} \cdot \vec{E} = \rho \vec{v} \cdot \vec{E} d\tau = \vec{j} \cdot \vec{E} d\tau$$

$$\rightarrow \frac{d\mathcal{E}_m}{dt} = \int \vec{j} \cdot \vec{E} d\tau \quad \text{قوانین آمپس}$$

$$\frac{d}{dt} (\mathcal{E}_m + \mathcal{E}_e) = -\oint \vec{j}_e \cdot d\vec{s}$$

$$\frac{d\mathcal{E}_m}{dt} = \int \vec{E} \cdot \left( \frac{1}{\mu_0} \vec{\nabla} \times \vec{B} - \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right) d\tau = \int \left[ \frac{\partial}{\partial t} \left( -\frac{\epsilon_0}{2} \vec{E} \cdot \vec{E} \right) \right] d\tau$$

$$+ \int \left[ (\vec{\nabla} \times \vec{E}) \cdot \frac{\vec{B}}{\mu_0} - \frac{\vec{\nabla} \cdot (\vec{E} \times \vec{B})}{\mu_0} \right] d\tau$$

$$\underbrace{\begin{pmatrix} m_1 & 0 \\ 0 & m_2 \end{pmatrix}}_M \ddot{x} = - \underbrace{\begin{pmatrix} K_1+K_2 & -K_2 \\ -K_2 & K_3+K_2 \end{pmatrix}}_K x$$

$$x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} e^{st} = \chi e^{st}$$

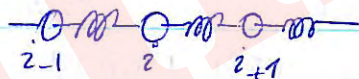
$$M \ddot{x} = -Kx \rightarrow \chi (K + Ms^2) = 0 \rightarrow \det(Ms^2 + K) = 0$$

$$(m_1 s^2 + K_1 + K_2)(m_2 s^2 + K_2 + K_3) = K_2^2$$

$$\Re[a_{(1)} e^{-i\omega_{(1)}t} x_{(1)}] + \Re[a_{(2)} e^{-i\omega_{(2)}t} x_{(2)}]$$

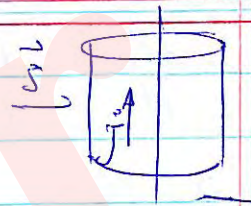
$$= |a_{(1)}| \cos[\omega_{(1)}t - \varphi_{(1)}] \begin{pmatrix} 1 \\ 1 \end{pmatrix} + |a_{(2)}| \cos[\omega_{(2)}t - \varphi_{(2)}] \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$m \ddot{z}_i = k (\ddot{z}_{i+1} + \ddot{z}_{i-1} - 2\ddot{z}_i)$$



$$z_{j(t)} = z_j e^{st} = z_j e^{-i\omega t}$$

$$\rightarrow z_{i+1} + \left(\frac{m\omega^2}{k} - 2\right) z_i + z_{i-1} = 0 \rightarrow z_i = u^i$$



$$\begin{cases} \vec{\nabla} \cdot \vec{E} = \frac{\rho_f}{\epsilon} \\ \vec{\nabla} \times \vec{B} - \mu \epsilon \frac{\partial \vec{E}}{\partial t} = \mu \vec{j}_f \end{cases} \rightarrow \vec{\nabla} \times (\vec{\nabla} \times \vec{E}) + \mu \epsilon \frac{\partial \vec{E}}{\partial t} = -\mu \frac{\partial \vec{j}_f}{\partial t}$$

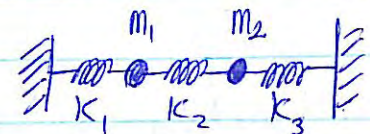
$$\rightarrow \vec{\nabla} (\vec{\nabla} \cdot \vec{E}) - \nabla^2 \vec{E} + \mu \epsilon \frac{\partial \vec{E}}{\partial t^2} = -\mu \frac{\partial \vec{j}_f}{\partial t}$$

$$(\nabla^2 - \mu \epsilon \frac{\partial^2}{\partial t^2}) \vec{E} = \frac{\vec{\nabla} \rho_f}{\epsilon} + \mu \frac{\partial \vec{j}_f}{\partial t}$$

$$\text{برون جنبه: } (\nabla^2 - \mu \epsilon \frac{\partial^2}{\partial t^2}) \vec{E} = 0, \quad \vec{\nabla} \cdot \vec{E} = 0$$

$$(\nabla^2 - \mu \epsilon \frac{\partial^2}{\partial t^2}) \vec{B} = -\mu \vec{\nabla} \times \vec{j}_f, \quad \vec{\nabla} \cdot \vec{B} = 0$$

$$\begin{cases} m_1 \ddot{x}_1 = -K_1 x_1 + K_2 (x_2 - x_1) \\ m_2 \ddot{x}_2 = K_2 (x_1 - x_2) - K_3 x_2 \end{cases}$$



$$M \ddot{z}_{(x,t)} = K [z_{(x+\Delta,t)} + z_{(x-\Delta,t)} - 2z_{(x,t)}] \rightarrow$$

$$-M\omega^2 = K [e^{-iK\Delta} + e^{iK\Delta} - 2] = 2K(\cos K\Delta - 1)$$

$$\rightarrow \omega^2 = 4 \frac{K}{M} \sin^2\left(\frac{K\Delta}{2}\right) \quad \text{رابطه‌ی پراشده}$$

$$\rightarrow 0 \leq \omega \leq 2\sqrt{\frac{K}{M}} \quad \text{رشته‌ی پیرامیت}$$

$$\text{حرکت واحدی با بار و } \omega > 2\sqrt{\frac{K}{M}}$$

$$\cos(K\Delta) = 1 - \frac{M\omega^2}{2K} = 1 - \frac{2\omega^2}{\omega_c^2} < -1 \quad ; \quad K\Delta = \pi + \tilde{\gamma}$$

$$\cos(\pi + \tilde{\gamma}) = 1 - \frac{2\omega^2}{\omega_c^2} \quad \cos \tilde{\gamma} = \frac{2\omega^2}{\omega_c^2} - 1 > 1 \rightarrow$$

$$\cosh(i\tilde{\gamma}) = \frac{2\omega^2}{\omega_c^2} - 1 \rightarrow i\tilde{\gamma} = \pm \cosh^{-1}\left(\frac{2\omega^2}{\omega_c^2} - 1\right)$$

$$K\Delta = \pi \pm i \cosh^{-1}\left(\frac{2\omega^2}{\omega_c^2} - 1\right) \rightarrow ikx = \frac{i\pi x}{\Delta} \pm \left(-1\right) \cosh^{-1}\left(\frac{2\omega^2}{\omega_c^2} - 1\right) \frac{x}{\Delta}$$

$$\Delta K = \pi + i \cosh^{-1}\left(\frac{2\omega^2}{\omega_c^2} - 1\right) \rightarrow e^{ikx} = e^{\frac{i\pi x}{\Delta}} e^{-\frac{x}{\Delta} \cosh^{-1}\left(\frac{2\omega^2}{\omega_c^2} - 1\right)}$$

$$\rightarrow u + \frac{1}{u} + \left(\frac{m\omega^2}{K} - 2\right) = 0 \rightarrow u^2 + \left(\frac{m\omega^2}{K} - 2\right)u + 1 = 0$$

$$\rightarrow \tilde{z}_i = Au e^{i\omega t} + Bu e^{-i\omega t}$$

$$u = e^{i\theta} \quad |u|=1 \quad \text{رشته‌ی پیرامیت}$$

$$\frac{m\omega^2}{K} = 2(1 - \cos\theta) \rightarrow 0 \leq \omega^2 \leq \frac{4K}{m} \rightarrow 0 \leq \omega \leq 2\sqrt{\frac{K}{m}}$$

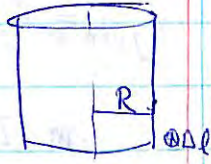
$$\omega = 2\sqrt{\frac{K}{m}} \sin\left(\frac{\theta}{2}\right) \quad \tilde{z}_{i,j}(t) = e^{i\omega t - i\left(2\sqrt{\frac{K}{m}} \sin\frac{\theta}{2}\right)x}$$

پیرامیت است. یعنی  $\omega$  پیرامیت است

$$\int_0^{2\pi} d\theta [A_{+,\omega} \tilde{z}_{+,\omega} + A_{-,\omega} \tilde{z}_{-,\omega}]$$

$$U = \frac{\pi R^2 L (\mu_0 n I)^2}{2\mu_0} \rightarrow \left(\frac{\partial U}{\partial R}\right)_I = \frac{2\pi R L (\mu_0 n I)^2}{2\mu_0}$$

$$P = \frac{(\mu_0 n I)^2}{2\mu_0} = \frac{B^2}{2\mu_0}$$



$$\frac{B}{2} (n I \Delta z) \Delta l \quad ; \quad \bar{B} (n I \Delta z) \Delta l$$

N جواب (درج صغیر) داریم.

$$k\Delta \ll 1: \omega^2 = \frac{K}{M} \Delta^2 k^2 \rightarrow \frac{\omega}{k} = \Delta \sqrt{\frac{K}{M}}$$

$$v_p = \frac{\Delta x}{\Delta t} = \frac{\omega}{k} \rightarrow \text{سرعت پهنای سیگنال}$$

$$M \ddot{z} = K (\Delta^2 \ddot{z} + \frac{1}{12} \Delta^2 \ddot{z} + \dots) \rightarrow \rho \ddot{z} = F \ddot{z}$$

$$\rightarrow -\rho \omega^2 = -FK^2 \quad ; \quad K\Delta = F, \quad \frac{M}{\Delta} = \rho$$

$$f\left(\frac{\partial}{\partial t}, \frac{\partial}{\partial x}\right) \psi(x,t) = 0 \rightarrow f(-i\omega, ik) = 0$$

$$\frac{F}{\rho} = v^2 \rightarrow -\ddot{z} + v^2 z'' = 0 \rightarrow (-D_t^2 + v^2 D_x^2) z = 0$$

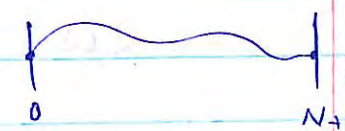
$$\rightarrow (-D_t + v D_x)(D_t + v D_x) z = 0 \rightarrow D_t D_x z = 0$$

$$D_z = \frac{\partial t}{\partial \xi} D_t + \frac{\partial x}{\partial \xi} D_x$$

$$\text{طول موج} = \frac{\Delta}{\text{Arg}^{-1}\left(\frac{2\omega^2}{\omega_0^2} - 1\right)}$$

$$v_p = \frac{\omega}{k} \quad \text{کفین} \quad \omega^2 \sim \frac{K}{M} \Delta^2 k^2 \quad \text{برابر با هم}$$

$$\rightarrow v_p = \Delta \sqrt{\frac{K}{M}}$$

$$z = e^{-i\omega t} (a e^{ikx} + b e^{-ikx})$$


$$x=0: b = -a \rightarrow z = e^{-i\omega t} \sin(kx)$$

$$\sin kL = 0 \rightarrow k = \frac{n\pi}{L} = \frac{n\pi}{\Delta(N+1)}$$

$$\sin(kx) = \sin(kj\Delta) = \sin\left(\frac{jn\pi}{N+1}\right)$$



$$\sin(j(k\Delta + \pi)) = \sin(j(k\Delta - \pi)) \quad ; \quad k\Delta - \pi = -k'\Delta$$

$$\left. \begin{array}{l} \text{ii} \downarrow \\ 0 < k\Delta < \pi \end{array} \right\} \Rightarrow \sin(-jk'\Delta) = -\sin(jk'\Delta) \rightarrow$$

$$n\pi < u_n < (n + \frac{1}{2})\pi$$

$$n \gg 1: u_n + n\pi + \delta_n \rightarrow \delta_n = \frac{m}{M} \times \frac{1}{\pi n}$$

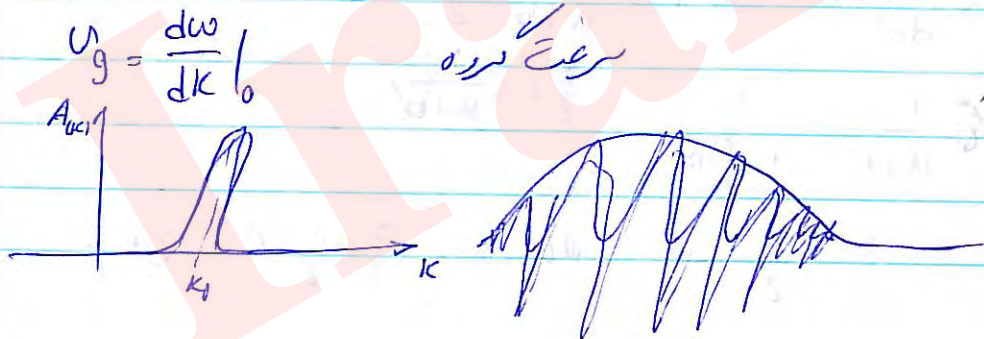
$$n=0: \frac{m}{M} \ll 1 \rightarrow u_0 = \sqrt{\frac{m}{M}} \frac{\sqrt{K_{slr} L}}{m/L} \quad u_0^2 = \frac{m}{M + \frac{m}{3}}$$

$$\rightarrow \omega_0 = \frac{u_0}{L} \sqrt{\frac{F}{P}} = \sqrt{\frac{m}{M + \frac{m}{3}}} \sqrt{\frac{K_{slr} L}{m/L}} \times \frac{1}{L}$$

$$\rightarrow \omega_0 = \sqrt{\frac{K_{slr}}{M + \frac{m}{3}}}$$

$$\Psi(x,t) = \int A(k) e^{i(kx - \omega t)} dk = \int A_k e^{i(k_0 x - \omega_0 t) + i[(k - k_0)x - \frac{d\omega}{dk}|_{k_0} t]} dk$$

$$= e^{i(k_0 x - \omega_0 t)} \int A(k) dk e^{i(k - k_0)(x - \frac{d\omega}{dk}|_{k_0} t)} = e^{i k_0 (x - u_g t)} g(x - u_g t)$$

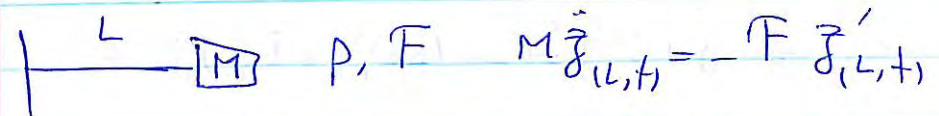


$$\begin{cases} \frac{\partial t}{\partial \xi} = \alpha \\ \frac{\partial t}{\partial \eta} = -\alpha \end{cases} \quad \begin{cases} \frac{\partial x}{\partial \xi} = \alpha u \\ \frac{\partial x}{\partial \eta} = \alpha u \end{cases} \rightarrow \begin{cases} t = \alpha(\xi - \eta) \\ x = \alpha u(\xi + \eta) \end{cases}$$

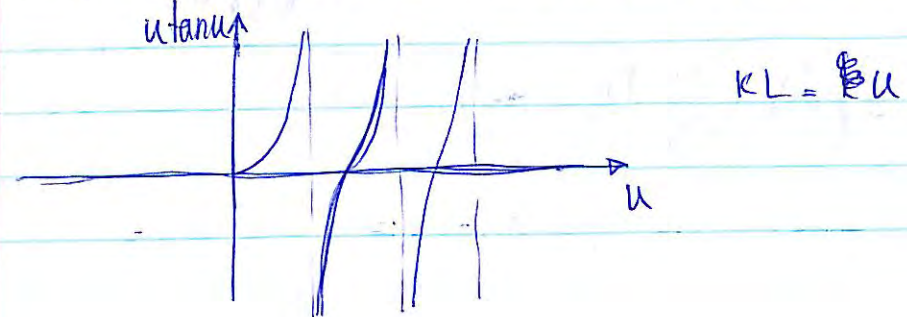
$$\rightarrow \begin{cases} \xi = \frac{x + ut}{2\alpha u} \\ \eta = \frac{x - ut}{2\alpha u} \end{cases} \quad \alpha = \frac{1}{2u} \quad \begin{cases} \xi = x + ut \\ \eta = x - ut \end{cases}$$

$$D_\eta D_\xi \bar{\psi} = 0 \rightarrow D_\xi \bar{\psi} = f(\xi) \rightarrow \bar{\psi} = f(\xi) + g(\eta)$$

$$\rightarrow \bar{\psi} = f(x + ut) + g(x - ut)$$



$$\rightarrow -M\omega^2 \sin(kL) = FK \sin(kL) \rightarrow kL \tan(kL) = \frac{m}{M}$$



درستی بالایی دارد و پایین نیز بدون

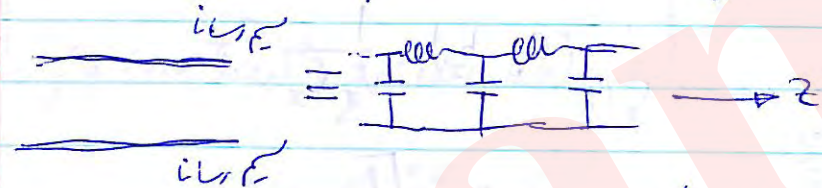
$$\rho \frac{\partial^2 \bar{z}}{\partial t^2} = F \frac{\partial^2 \bar{z}}{\partial x^2} - p\gamma \frac{\partial \bar{z}}{\partial t}$$

$$\bar{z}_{(x=0)} = \bar{z}_{(x=L)} = 0 ; \quad \bar{z} \sim e^{-i\omega t + ikx}$$

$$-\rho\omega^2 = -FK^2 + ip\gamma\omega \rightarrow \omega^2 = v^2 K^2 - i\gamma\omega$$

$$\bar{z} \sim e^{-i\omega t} \sin(kx) \quad \sin kd = 0 \rightarrow kd = n\pi \rightarrow k = \frac{n\pi}{d}$$

$$\omega = \frac{-i\gamma \pm \sqrt{-\gamma^2 + 4v^2 k^2}}{2} \rightarrow \bar{z} \sim \sin\left(\frac{n\pi x}{d}\right) e^{\frac{-\gamma}{2}t} e^{\frac{-i \pm \sqrt{4v^2 k^2 - \gamma^2}}{2}t}$$



$$\nabla \times \vec{E} = 0 \rightarrow 0 = \vec{B}_z \rightarrow \frac{\partial B_z}{\partial t} \rightarrow \text{حالتی را در نظر میگیریم که}$$

دری صوری  $z=c$  در توانیم بیان کنیم

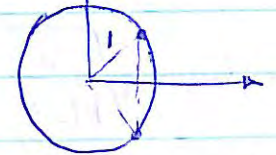
$$m\ddot{z}_j = K(\dot{z}_{j+1} + \dot{z}_{j-1} - 2\dot{z}_j) - \gamma m \dot{z}_j$$

$$\rightarrow -m\omega^2 z_j = K(z_{j+1} + z_{j-1} - 2z_j) + im\gamma\omega z_j$$

$$-m\omega^2 = K\left(u + \frac{1}{u} - 2\right) \rightarrow u^2 + 2b'u + 1 = 0, \quad b' = -\frac{im\gamma\omega}{K}$$

$$\text{با توجه به } u^2 - \left(2 - \frac{m\omega^2}{K} - \frac{im\gamma\omega}{K}\right)u + 1 = 0$$

$$\delta b' = \frac{im\gamma\omega^2}{K}$$



من خواهم ببینم برای لایه دوپ جواب ها چه می شود. صعبا پس

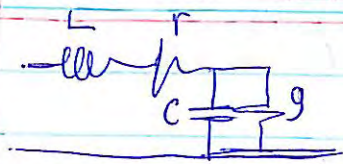
بیرون رفته باید داخل باشد هم. پس اگر بیرون افتاد بیرون هم بیرون

$$\angle \frac{du}{db'} = \angle u + \angle \frac{-1}{u+b} + \frac{\pi}{2}$$

$$\frac{1}{u+b'} = \frac{1}{+i\sin\theta} \quad -\frac{\pi}{2} + \angle \frac{1}{u+b'}$$

$$-\frac{\pi}{2} - \frac{\pi}{2} = -\pi \quad \text{و ل}$$

$$\frac{\pi}{2} - \frac{\pi}{2} = 0 \quad \text{این}$$



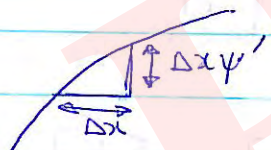
$$-i\omega L + r = -i\omega \left( L - \frac{r}{i\omega} \right)$$

$$-i\omega C + g = -i\omega \left( C - \frac{g}{i\omega} \right)$$

$$\frac{\partial V}{\partial z} = i\omega L I = i\omega L I - rI + -L \frac{\partial I}{\partial t} = rI$$

$$\frac{\partial I}{\partial z} = (i\omega C - g)V$$

$$\Delta x \sqrt{1 + \psi'^2} = \Delta x \left( 1 + \frac{\psi'^2}{2} \right) \rightarrow$$



$$\delta U = \frac{1}{2} K \left[ \Delta x - \Delta x_0 + \frac{1}{2} \psi'^2 \Delta x \right]^2$$

$$= \frac{1}{2} K (\Delta x - \Delta x_0)^2 + \frac{1}{2} K (\Delta x - \Delta x_0) \Delta x \psi'^2 + \dots \rightarrow U = \frac{1}{2} \int F \psi'^2 dx$$

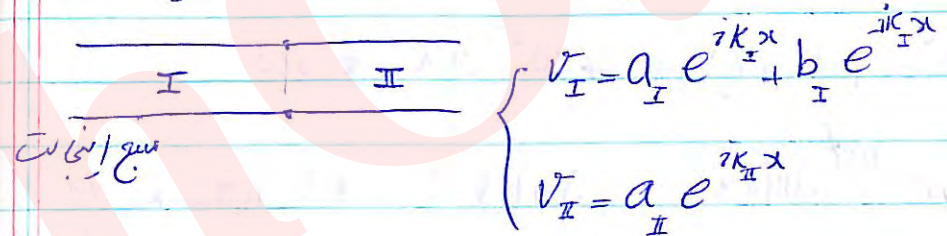
$$P = -F \psi' \dot{\psi} = \frac{F}{v} \dot{\psi}^2 = \sqrt{FP} \dot{\psi}^2 = Z \dot{\psi}^2$$

$$\frac{F}{P} = v^2, \quad \sqrt{FP} = Z$$

$$V(z) = V(z + \Delta z) + L \Delta z \frac{\partial I}{\partial t} \rightarrow$$

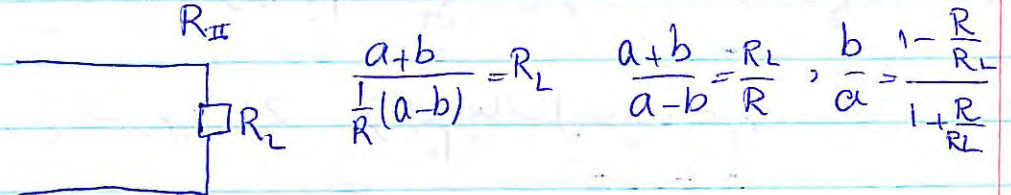
$$\frac{\partial V}{\partial z} = -L \frac{\partial I}{\partial t}, \quad \frac{\partial I}{\partial z} = -C \frac{\partial V}{\partial t}$$


$$\rightarrow \frac{\partial^2 V}{\partial z^2} = LC \frac{\partial^2 V}{\partial t^2}, \quad v = \frac{1}{\sqrt{LC}}$$



$$\begin{cases} V_{I(0)} = V_{II(0)} \\ I_{I(0)} = I_{II(0)} \end{cases} \rightarrow \begin{cases} a_I + b_I = a_{II} \\ \frac{1}{v_I l_I} (a_I - b_I) = \frac{1}{v_{II} l_{II}} a_{II} \end{cases}$$

$$\frac{b_I}{a_I} = \frac{1 - \frac{R_{II}}{R_I}}{1 + \frac{R_{II}}{R_I}}, \quad R = \sqrt{\frac{L}{C}} = v l$$





$$\begin{aligned} \rightarrow & : v n C_1 (T_0 - \lambda \frac{\partial T}{\partial x}) \\ \leftarrow & : v n C_1 (T_0 + \lambda \frac{\partial T}{\partial x}) \end{aligned}$$

$$\rightarrow \vec{j} = v n C_1 \lambda \frac{\partial T}{\partial x} \rightarrow \kappa = \lambda v C_1$$

$$\rightarrow \frac{c^2}{\lambda v} = \frac{c}{\lambda} = 10^3 D \rightarrow \text{دانه بر سانتیمتر}$$

$$\delta p = P e^{-i\omega t + i\vec{k} \cdot \vec{r}} \quad \vec{v} = \frac{\vec{k}}{\omega} P$$

دانه بر سانتیمتر

$$P_{\text{توان}} = \int \vec{I} \cdot d\vec{s}$$

$$u_k = \frac{1}{2} \rho \vec{v} \cdot \vec{v}$$

$$u_p = \frac{1}{2} \frac{(\delta p)^2}{B}$$

کتابخانه سنجش

$$|P| \sim 3 \times 10^{-5} \text{ Pa} \rightarrow 10^{-11} \text{ m}$$

در دریا

$$|P| \sim 30 \text{ Pa} \rightarrow 10^{-5} \text{ m}$$

$$\begin{cases} \vec{\nabla} \cdot (\rho \vec{u}) + \frac{\partial \rho}{\partial t} = 0 \\ \rho \left[ \frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \vec{\nabla} \vec{u} \right] = -\nabla p \end{cases} \quad \begin{cases} \vec{u}_0 = 0 \\ p_0, P_0 \text{ عیب} \end{cases}$$

$$\begin{cases} \frac{\partial}{\partial t} \delta p + \rho_0 \vec{\nabla} \cdot (\delta \vec{u}) = 0 \rightarrow \frac{\rho_0}{B} \frac{\partial}{\partial t} (\delta p) + \rho_0 \vec{\nabla} \cdot (\delta \vec{u}) = 0 \end{cases}$$

$$\begin{cases} \rho_0 \frac{\partial}{\partial t} (\delta \vec{u}) = -\vec{\nabla} (\delta p) \rightarrow \frac{\rho_0}{B} \frac{\partial^2}{\partial t^2} (\delta p) - \nabla^2 (\delta p) = 0 \end{cases}$$

$$\frac{\delta p}{\rho_0} = \frac{B}{\rho_0}$$

$$\vec{j} = -\kappa \vec{\nabla} T \quad ; \quad \int \vec{j} \cdot d\vec{s} = \int c \frac{\partial T}{\partial t} dV \rightarrow$$

$$\kappa \nabla^2 T = -c \frac{\partial T}{\partial t} \rightarrow \frac{c}{\tau} \sim \frac{\kappa}{l^2} \rightarrow \tau \sim \frac{l^2}{\kappa}$$

زمان لازم برای هم دما شدن

$$\frac{c l^2}{\kappa} \begin{cases} \ll 1 & \text{هم دما} \\ \gg 1 & \text{بی دما} \end{cases}$$



$$\begin{cases} u_x = \frac{A\omega}{\sinh(kh)} \cosh(k(h+y)) \cos(\omega t - kx) \\ u_y = -\frac{A\omega}{\sinh(kh)} \sinh(k(h+y)) \sin(\omega t - kx) \end{cases}$$

$$\frac{\bar{T}}{\text{طول}} = \frac{1}{2} \rho \times \frac{1}{2} \frac{A^2 \omega^2}{\sinh^2(kh)} \int_{-h}^0 dy (\cosh^2 0 + \sinh^2 0)$$

$$\frac{\rho A^2 \omega^2 \cosh(kh)}{4K \sinh(kh)} \quad ; \quad \frac{\bar{U}_g}{\text{طول}} = \frac{\rho g A^2}{4} = \frac{1}{2} \rho g A^2 \langle \cos^2(\omega t - kx) \rangle$$

$$L = \int \sqrt{1 + \psi'^2} dx = \int \left( \frac{1}{2} \psi'^2 + 1 \right) dx \rightarrow \frac{\bar{U}_g}{\text{طول}} = \frac{1}{4} A^2 k^2 \tau$$

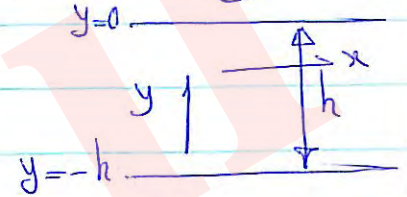
$$\bar{U}_g + \bar{U}_\tau = \bar{T} \rightarrow \rho g + k^2 \tau = \frac{\rho \omega^2}{k \tanh(kh)}$$

برای  $\tau \ll 0 \Rightarrow \omega^2 = gk \tanh(kh)$  / طول موج بسیار بزرگتر از عمق

برای  $kh \ll 1$  عمق بسیار کم  $\Rightarrow \frac{\omega}{k} = \sqrt{gh}$

برای  $kh \gg 1$  عمق بسیار زیاد  $\Rightarrow \omega^2 = gk$

عشق تابع و ابعاد فیزیکی آن برآورد است.



$$\psi(x,t) = A \cos(\omega t - kx)$$

$$\begin{cases} \vec{\nabla} \cdot \vec{v} = 0 \\ \vec{\nabla}_x \vec{v} = 0 \rightarrow \vec{v} = + \vec{\nabla} \phi \end{cases} \rightarrow \nabla^2 \phi = 0$$

شرایط مرزی  $u_y(y=-h) = 0$  ;  $u_y(y=0) = -A\omega \sin(\omega t - kx)$

$$\rightarrow \frac{\partial \phi}{\partial y} \Big|_{y=-h} = 0 \quad ; \quad \frac{\partial \phi}{\partial y} \Big|_{y=0} = -A\omega \sin(\omega t - kx)$$

$$\phi = \sin(\omega t - kx) f(y) \rightarrow -k^2 f_{(y)} \sin(\omega t - kx) + f''_{(y)} \sin(\omega t - kx) = 0$$

$$\rightarrow f'' = k^2 f \rightarrow f = B \cosh(k(y+h))$$

$$\frac{\partial \phi}{\partial y} = Bk \sin(\omega t - kx) \sinh(k(y+h)) \rightarrow B = -\frac{A\omega}{k \sinh(kh)}$$

$$\phi = -\frac{A\omega}{k \sinh(kh)} \sin(\omega t - kx) \cosh(k(h+y))$$

$$\left[ O\left(\frac{\partial}{\partial t}, \nabla\right) \right] \left[ R \vec{\Psi}(t, R^{-1}\vec{r}_1) \right] = R \left( O \vec{\Psi} \right) (t, R^{-1}\vec{r}_1)$$

$$\left[ O(-i\omega, iR\vec{k}) \right] (R \vec{\Psi}) = R \left[ O(-i\omega, i\vec{k}) \right] \vec{\Psi}$$

$$\left[ O(-i\omega, iR\vec{k}) \right] R = R \left[ O(-i\omega, i\vec{k}) \right]$$

$$\text{برابر } R\vec{k} = \vec{k}, \quad \left[ O(-i\omega, i\vec{k}) \right] R = R \left[ O(-i\omega, i\vec{k}) \right]$$

$$OR(\vec{\Psi}_{\parallel} + \vec{\Psi}_{\perp}) = RO(\vec{\Psi}_{\parallel} + \vec{\Psi}_{\perp}) \rightarrow$$

$$O(\vec{\Psi}_{\parallel} + R\vec{\Psi}_{\perp}) = RO\vec{\Psi}_{\parallel} + RO\vec{\Psi}_{\perp} \rightarrow \text{برابر}$$

$$O(\vec{\Psi}_{\parallel} - \vec{\Psi}_{\perp}) = RO\vec{\Psi}_{\parallel} + RO\vec{\Psi}_{\perp} \xrightarrow{\vec{\Psi}_{\perp}=0} O\vec{\Psi}_{\parallel} = RO\vec{\Psi}_{\parallel}$$

$$\rightarrow O\vec{\Psi}_{\parallel} = \lambda_{\parallel} \vec{\Psi}_{\parallel} \equiv Mu = \lambda u$$

$$\text{(دران 180)} : R(O\vec{\Psi}_{\perp}) = -O\vec{\Psi}_{\perp} \rightarrow (O\vec{\Psi}_{\perp}) \cdot \vec{k} = 0$$

$$\rightarrow 0 = \begin{bmatrix} O_{\parallel} & \\ & O_{\perp} \end{bmatrix}$$

$Ae^{i\vec{k}_I \cdot \vec{r}} + Be^{i\vec{k}_{II} \cdot \vec{r}} = Ce^{i\vec{k} \cdot \vec{r}}$   
 $\vec{k}_I = \vec{k}_{II} = \vec{k}_{\parallel} = \vec{k}_{\parallel}$   
 متن در پایین:

$$\sin \theta_r = \frac{k_{\perp}}{k_{\parallel}} \rightarrow \frac{\sin \theta_r}{\sin \theta_i} = \frac{k_{\perp}}{k_{\parallel}} = \frac{v_{\perp}}{v_{\parallel}}$$

$$\left[ O\left(\frac{\partial}{\partial t}, \nabla\right) \right] \vec{\Psi}(t, \vec{r}) = 0 \rightarrow \vec{\Psi} = \vec{\psi} e^{-i\omega t + i\vec{k} \cdot \vec{r}}$$

$$\left[ O(-i\omega, i\vec{k}) \right] \vec{\psi} = 0 \rightarrow \det \left[ O(-i\omega, i\vec{k}) \right] = 0$$

$$\vec{\Psi} = \vec{\psi} = R \vec{\Psi}(t, R^{-1}\vec{r}_1) \quad \text{در دوران } R$$

$$R \vec{\psi} e^{-i\omega t + i\vec{k} \cdot (R^{-1}\vec{r}_1)}$$

$$\left[ O(-i\omega, i\vec{k}) \right] (R\vec{\psi}_{\perp}) + \left[ O(-i\omega, i\vec{k}) \right] \vec{\psi}_{\parallel} = 0$$

$$R\vec{k} = \vec{k}, \quad \vec{\psi} = \psi_{\parallel} + \vec{\psi}_{\perp}$$

C.C, Complex Conjugate



$$\vec{E}_{\vec{r}} = K \frac{3(\vec{r} \cdot \hat{r})\hat{r} - \vec{r}}{r^3} \rightarrow (\vec{E}_{\vec{r}})_i = \sum_j \left[ \frac{K 3r_i r_j - \vec{r} \cdot \vec{r} \delta_{ij}}{r^5} \right] \vec{r}_j$$

$$\vec{E}_{\vec{r}} = M \vec{r} \rightarrow \vec{E}_{\vec{r}} = \sum_a M_a \vec{r}_a = \sum_a (M_a)_i \vec{r}_a$$

$$\sum_i M_{ii} = K \frac{3\vec{r} \cdot \vec{r} - \vec{r} \cdot \vec{r} (3)}{r^5} = 0 \rightarrow \vec{E}_{\vec{r}} = 0$$

$$\begin{cases} \vec{\nabla} \times \vec{B} = \mu \epsilon (-i\omega \vec{E}) + \mu \sigma \vec{E} \\ \vec{\nabla} \cdot \vec{E} - i\omega \vec{B} = 0 \end{cases} \quad \begin{cases} \sigma \gg \epsilon \omega & \epsilon, \mu \text{ constant} \\ i\omega \epsilon \rightarrow \sigma \\ \epsilon \rightarrow -\frac{\sigma}{i\omega} \end{cases}$$

$$\alpha = \frac{1}{\sqrt{\mu \epsilon}} = \frac{1}{\sqrt{i\mu \sigma}} \quad , \quad \kappa = \frac{\omega}{v} = \frac{\omega \sqrt{i\mu \sigma}}{\omega} \rightarrow \kappa^2 = i\mu \sigma \omega$$

$$\rightarrow \nabla^2 \psi = -\mu \sigma \frac{\partial \psi}{\partial t}$$

$$\sqrt{i} = \sqrt{e^{i\pi/2}} = e^{i\pi/4} = \frac{1+i}{\sqrt{2}} \quad , \quad \vec{\kappa} = \kappa \hat{\kappa} \text{ (direction)}$$

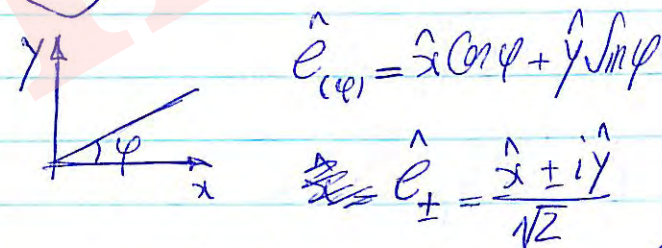
$$\vec{E} = E (\alpha \hat{x} + \beta \hat{y}) \quad ; \quad |\alpha|^2 + |\beta|^2 = 1$$

$$\frac{\beta}{\alpha} = \frac{\text{مقدار عمود}}{\text{مقدار موازی}} \rightarrow \vec{E} = E (\alpha \hat{x} + \beta \hat{y}) \cos \omega t \hat{z}$$

$$\frac{\beta}{\alpha} = +i \rightarrow \text{مقدار موازی} \rightarrow \vec{E} = \frac{E}{\sqrt{2}} (\hat{x} \cos \omega t + \hat{y} \sin \omega t) \hat{z}$$

$$\hookrightarrow \text{Re}[(\hat{x} + i\hat{y}) e^{-i\omega t}]$$

$$\vec{E} = E (\alpha \cos \omega t \hat{x} + |\beta| \hat{y} \cos(\omega t - \theta)) \hat{z}$$



$$\hat{e}_{(\phi)} = \hat{x} \cos \phi + \hat{y} \sin \phi$$

$$\hat{e}_{\pm} = \frac{\hat{x} \pm i\hat{y}}{\sqrt{2}}$$

$$\hat{x} = \frac{\hat{e}_+ + \hat{e}_-}{\sqrt{2}} \quad \hat{y} = \frac{\hat{e}_+ - \hat{e}_-}{i\sqrt{2}}$$

$$\hat{e}_{(\phi)} = \frac{1}{\sqrt{2}} (e^{-i\phi} \hat{e}_+ + \hat{e}_- e^{i\phi})$$

$$\frac{1}{\sqrt{2}} [\hat{e}_+ e^{-i\phi + i\kappa \cdot l} + \hat{e}_- e^{i\phi + i\kappa \cdot l}] = \frac{1}{\sqrt{2}} [\hat{e}_+ e^{-i\phi + i\frac{\kappa - \kappa}{2} l} + \hat{e}_- e^{i\phi}]$$

$$P_m = m n = P_{m_0} + m(n - n_0) = P_{m_0} + \delta P_m$$

$$P_e = (n - n_0) q = \frac{q}{m} \delta P_m \quad \text{ن سب } n \quad \text{نایت ها } n_0$$

$$\begin{cases} \frac{\partial n}{\partial t} + \vec{\nabla} \cdot (n \vec{v}) = 0 \\ P_m \left( \frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \vec{\nabla} \vec{v} \right) = -\vec{\nabla} P + n q \vec{E} \end{cases} \quad \begin{cases} P_m \frac{dP}{dP_m} = B \\ \vec{\nabla} \cdot \vec{E} = \frac{P_e}{\epsilon_0} \end{cases}$$

$$\begin{cases} \frac{\partial \delta n}{\partial t} + n_0 \vec{\nabla} \cdot \vec{v} = 0 \\ m n_0 \frac{\partial \vec{v}}{\partial t} + \vec{\nabla}(\delta P) = n_0 q \vec{E} \end{cases} \quad \begin{cases} \frac{\delta P}{\delta n} = \frac{B}{n_0} \\ \frac{n_0}{B} \frac{\partial(\delta P)}{\partial t} + n_0 \vec{\nabla} \cdot \vec{v} = 0 \end{cases}$$

$$\vec{\nabla} \cdot \vec{E} = \frac{q \delta n}{\epsilon_0} \quad m n_0 \frac{\partial \vec{\nabla} \cdot \vec{v}}{\partial t} = -\nabla^2(\delta P) + n_0 q \frac{q \delta n}{\epsilon_0}$$

$$\frac{\partial^2(\delta P)}{\partial t^2} + \frac{B}{m n_0} \left[ -\nabla^2(\delta P) + \frac{n_0 q^2}{\epsilon_0 B} \delta P \right] = 0 \rightarrow$$

$$\frac{B}{m n_0} \nabla^2(\delta P) = \left( \frac{\partial^2}{\partial t^2} + \frac{n_0 q^2}{m \epsilon_0} \right) \delta P \rightarrow \nabla^2 \nabla^2(\delta P) = \left( \frac{\partial^2}{\partial t^2} + \omega_p^2 \right) \delta P$$

$$\rightarrow \omega^2 k^2 = \omega^2 - \omega_p^2 \rightarrow \omega_p = \frac{\sqrt{\omega^2 k^2 + \omega_p^2}}{k}, \quad \omega_g = \frac{\omega^2}{\omega_p}$$

$$R = \sqrt{\mu_0 \omega} \frac{1+i}{\sqrt{2}} = \frac{1+i}{\delta}, \quad \delta = \sqrt{\frac{2}{\mu_0 \omega}}$$

$$(\nabla^2 + k^2) \vec{E} = 0, \quad \vec{E} = \hat{z} E_{(p,z)} \quad \text{از پرتاب } \quad \text{نایت ها}$$



$$\left( \frac{1+i}{\delta} \right)^2 = \frac{2i}{\delta^2} \rightarrow \frac{1}{p} \frac{\partial}{\partial p} \left( p \frac{\partial E}{\partial p} \right) + \frac{2i}{\delta^2} E = 0, \quad \vec{E} = E_p \hat{z}$$

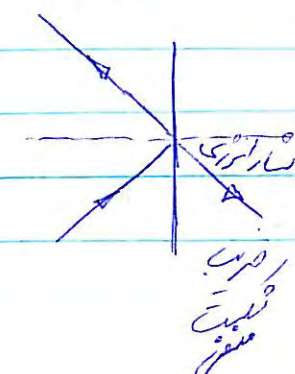
$$\delta \gg R: \quad \frac{\partial^2 E}{\partial p^2} + \frac{1}{p} \frac{\partial E}{\partial p} + \frac{2i}{\delta^2} E = 0,$$

$$E = E_0 + p E_1 + p^2 E_2 + \dots \rightarrow 2E_2 + \frac{E_1}{p} + 2E_2 + \frac{2i}{\delta^2} E_0 = 0$$

$$E_1 = 0, \quad E_2 = -\frac{i}{2\delta^2} E_0, \quad E_3 = 0, \quad E_4 = -\frac{E_0}{16\delta^4}$$

$$\rightarrow E_p = E_0 \left( 1 - \frac{i}{2\delta} p^2 - \frac{p^4}{16\delta^4} \right) \rightarrow |E|^2 = |E_0|^2 \left( 1 + \frac{p^4}{8\delta^4} \right)$$

$\delta \ll R$ : رفتار نایبی است.



$$i \vec{k} \times \vec{E} - i \omega \vec{B} = 0 \rightarrow \vec{H} = \frac{\vec{k} \times \vec{E}}{\mu \omega} \quad \mu_0 \epsilon_0$$

$$\vec{S} = \frac{1}{2} \text{Re} (\vec{E} \times \vec{H}^*) = \frac{E^2}{2\mu \omega} \vec{k}$$

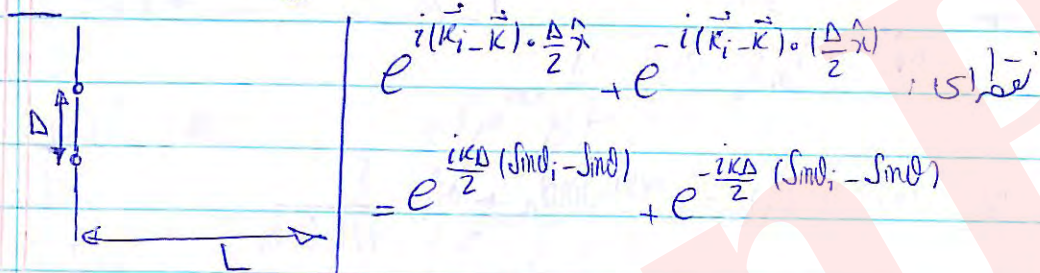
$$A_{(\theta, \theta_i)} = \int_{-D/2}^{D/2} dx' e^{ik(\sin\theta_i - \sin\theta)x'} = \frac{e^{\frac{iKD}{2}(\sin\theta_i - \sin\theta)} - e^{-\frac{iKD}{2}(\sin\theta_i - \sin\theta)}}{ik(\sin\theta_i - \sin\theta)}$$

$$\rightarrow A = \left( \frac{\sin\left(\frac{KD}{2}(\sin\theta_i - \sin\theta)\right)}{\frac{KD}{2}(\sin\theta_i - \sin\theta)} \right) = \left( \frac{\text{Sinc } a}{a} \right)$$

$$\theta_i = 0, \frac{\sin\left(\frac{KD}{2}\sin\theta\right)}{\frac{KD}{2}\sin\theta} \rightarrow \frac{KD \sin\theta}{2} = \pi$$

نوار تاب اول

$$\rightarrow \theta \sim \frac{2\pi}{KD} = \frac{\lambda}{D}$$



$$= \cos\left[\frac{KD}{2}(\sin\theta_i - \sin\theta)\right] \Rightarrow \frac{KD \theta}{2} = n\pi \rightarrow \theta = \frac{n\lambda}{D}$$

$$\int ds' e^{i(\vec{k}_i - \vec{k}) \cdot \vec{r}'} = \int_j \int_j e^{i(\vec{k}_i - \vec{k}) \cdot \vec{r}'} = \int_j e^{i(\vec{k}_i - \vec{k}) \cdot \vec{R}_j} \int_j e^{i(\vec{k}_i - \vec{k}) \cdot \vec{r}''} ds''$$

در سطح پلانک :  $\epsilon = \epsilon_0 (1 + \chi) = \epsilon_0 \left(1 - \frac{\omega_p^2}{\omega^2}\right)$   $\omega \gg \omega_p$

$$k^2 = \epsilon \mu \omega^2 = \frac{\omega^2}{c^2} \left(1 - \frac{\omega_p^2}{\omega^2}\right), \quad c^2 k^2 = \omega^2 - \omega_p^2$$

$$\rightarrow v_p = c \frac{\sqrt{k^2 + \frac{\omega_p^2}{c^2}}}{k}, \quad v_g = \frac{ck}{\sqrt{k^2 + \frac{\omega_p^2}{c^2}}}$$

$$A_{(\vec{r})} = \int ds' \frac{e^{i(\vec{k}_i \cdot \vec{r}' + k|\vec{r} - \vec{r}'|)}}{|\vec{r} - \vec{r}'|}$$



$$\varphi = \vec{k}_i \cdot \vec{r}' + k|\vec{r} - \vec{r}'|$$

$$\rightarrow A_{(\vec{r})} = \int ds' e^{i\varphi} = \int ds' e^{i(\vec{k}_i - \vec{k}) \cdot \vec{r}'}$$

$$|\vec{r} - \vec{r}'| \approx r - \frac{\vec{r} \cdot \vec{r}'}{r}, \quad \vec{r} \gg \vec{r}', \quad r \gg r'$$

$$\rightarrow \vec{k} = k\hat{r} = k \frac{\vec{r}}{r}$$

$$\varphi = k(x' \sin\theta_i - x' \sin\theta) \quad ; \quad \vec{k}_i = k \left( \hat{z} \cos\theta_i + \hat{x} \sin\theta_i \right)$$

تایید: از کل ابعاد داریم:  $P \sim \frac{K \omega^4}{c^3}$

پهنای پهنای است یا اینکه از زمان میگذرد (تویا)  $\omega \sim M$

$$\vec{E} \approx K \frac{3\hat{r}(\hat{r} \cdot \vec{r}) - \vec{r}}{r^3} e^{i\vec{k} \cdot \vec{r}} = K e^{i\vec{k} \cdot \vec{r}} \vec{E}, \quad \vec{B} \approx 0$$

$$\vec{\nabla} \times \vec{E} - i\omega \vec{B} = 0 \rightarrow \vec{\nabla} \times \vec{E} - iKc\vec{B} = 0$$

$$\vec{\nabla} \times \vec{B} + \frac{i\omega}{c^2} \vec{E} = 0 \rightarrow$$

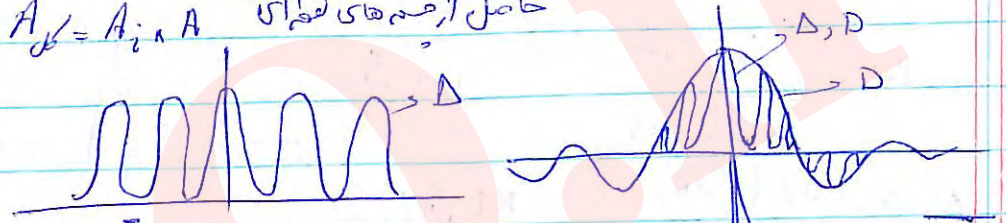
$$\begin{cases} \vec{\nabla} \times (e^{i\vec{k} \cdot \vec{r}} \vec{E}) - iK(e^{i\vec{k} \cdot \vec{r}} \vec{B}) = 0 \\ \vec{\nabla} \times (e^{i\vec{k} \cdot \vec{r}} \vec{B}) + iK(e^{i\vec{k} \cdot \vec{r}} \vec{E}) = 0 \end{cases} \Rightarrow \begin{cases} \vec{E} = K e^{i\vec{k} \cdot \vec{r}} \vec{E} \\ c\vec{B} = K e^{i\vec{k} \cdot \vec{r}} \vec{B} \end{cases}$$

$$\vec{E}_0 = \frac{3\hat{r}(\hat{r} \cdot \vec{r}) - \vec{r}}{r^3}, \quad \vec{B}_0 = 0$$

$$\begin{cases} \vec{\nabla} \times \vec{E} + iK\hat{r} \times \vec{E} - iK\vec{B} = 0 \\ \vec{\nabla} \times \vec{B} + iK\hat{r} \times \vec{B} + iK\vec{E} = 0 \end{cases} \Rightarrow \begin{cases} \vec{\nabla} \cdot \vec{E} + iK\hat{r} \cdot \vec{E} = 0 \\ \vec{\nabla} \cdot \vec{B} + iK\hat{r} \cdot \vec{B} = 0 \end{cases}$$

اگر همه ها مثل هم باشند:  $= A_{\theta i} \sum_j e^{i(\vec{k}_i - \vec{k}_j) \cdot \vec{r}_j}$

حاصل از همه های تقوای  $A_{\theta} = A_i \times A$



$$\sum_{j=0}^{N-1} e^{i(k_1 - \sin \theta) j D} = \frac{1 - e^{-iKN\Delta \sin \theta}}{1 - e^{-iK\Delta \sin \theta}} = \left( \frac{\sin(\frac{NK\Delta \sin \theta}{2})}{\sin(\frac{K\Delta \sin \theta}{2})} \right)$$

$$\sin \theta_n = \frac{2n\pi}{K\Delta} = \frac{n\lambda}{\Delta}$$

$$\frac{NK\Delta \sin(\theta_n + \Delta \theta_n)}{2} = \pi + \frac{NK\Delta \sin \theta_n}{2} \rightarrow \Delta \theta_n = \frac{\lambda}{N\Delta \cos \theta_n}$$

$$\lambda \rightarrow \theta_n, \quad \lambda + \Delta \lambda \rightarrow \theta_n + \Delta \theta_n$$

$$\sin(\theta_n + \Delta \theta_n) = \frac{n(\lambda + \Delta \lambda)}{\Delta} \rightarrow \cos \theta_n \Delta \theta_n = \frac{n\Delta \lambda}{\Delta} \rightarrow \Delta \theta_n = \frac{n\Delta \lambda}{\Delta \cos \theta_n}$$

$$\rightarrow \frac{n\Delta \lambda}{\Delta \cos \theta_n} = \frac{\lambda}{N\Delta \cos \theta_n} \rightarrow \frac{\Delta \lambda}{\lambda} = \frac{1}{nN}$$


$$\vec{S} = \frac{1}{2} \vec{E} \times \vec{H} = \frac{K^2 k^4}{2\mu_0 c} \frac{[(\vec{v} \times \vec{r}) \times \hat{r}] \times (\vec{v} \times \vec{r})}{r} = \frac{K^2 k^4}{2\mu_0 c} \frac{r |\vec{v} \times \hat{r}|^2}{r^2}$$

$$\rightarrow P = \frac{K^2 k^4}{2\mu_0 c} \int |\vec{v} \times \hat{r}|^2 d\Omega \rightarrow P = \frac{K k^4 c v^2}{3}$$

$$\rightarrow P = \frac{K q^2 |\vec{R}|^2 \omega^4}{3c^3} = \frac{K q^2}{3c^3} |\vec{a}|^2 = \frac{2K q^2}{3c^3} \vec{a}^2$$

برای شتاب سینوسی (دقیقه)  $\vec{a}$  داشته باشیم

$$P_{(t)} = \frac{2K q^2}{3c^3} a^2 \left(1 - \frac{R}{c}\right) \quad \text{برای غیر سینوسی (سرعت کم)}$$

$$\frac{dE}{dt} = \frac{K q^2}{c^3} \left(\frac{K q^2}{m r^2}\right)^2 = -\frac{K q^2}{r^2} \frac{dr}{dt} \rightarrow \frac{dr^3}{dt} = -\frac{(K q^2)^2}{m^2 c^3}$$


$$\rightarrow \tau = \frac{m^2 c^3 R_0^3}{(K q^2)^2} \rightarrow \tau = 10^{-9} \text{ s}$$

$$\vec{B} = \frac{1}{r} \vec{v} \times \hat{r}, \quad \vec{E} = \frac{1}{r} \vec{v} \times (\vec{v} \times \hat{r}) + \frac{1}{r^2} (\vec{v} \cdot \hat{r}) \hat{r} + \frac{1}{r^3} (\hat{r} \cdot \hat{r}) \hat{r}$$

$$\vec{\nabla} \times \vec{B}_1 + iK \vec{E}_0 = 0, \quad \vec{B}_1 = \alpha K \frac{\vec{v} \times \hat{r}}{r^3}$$

$$\vec{\nabla} \times \vec{B}_1 = \alpha K \vec{E}_0 \rightarrow \alpha = -i \rightarrow \vec{B}_1 = -iK \frac{\vec{v} \times \hat{r}}{r^3}$$

$$\vec{\nabla} \times \vec{E}_1 + iK \vec{v} \times \vec{E}_0 = 0 \rightarrow \vec{\nabla} \times \vec{E}_1 + iK \frac{\vec{v} \times \hat{r}}{r^3} = 0$$

$$\vec{\nabla} \cdot \vec{E}_1 + iK \vec{v} \cdot \vec{E}_0 = 0, \quad \vec{E}_1 = \beta K \frac{\vec{v}}{r^2} + \gamma K \frac{(\vec{v} \cdot \hat{r}) \hat{r}}{r^4}$$

$$\vec{\nabla} \times \vec{E}_1 = \beta K \frac{-2\hat{r} \times \vec{v}}{r^3} + \gamma K \frac{\vec{v} \times \hat{r}}{r^3} \rightarrow 2\beta + \gamma + i = 0$$

$$\vec{\nabla} \cdot \vec{E}_1 = \beta K \frac{-2\vec{v} \cdot \hat{r}}{r^3} \rightarrow \gamma = -3i$$

$$\rightarrow \vec{E}_1 = -iK \left[ \frac{3\vec{v} \cdot \hat{r} \hat{r} - \vec{v} r^2}{r^5} \right] = -iK r \vec{E}_0$$

$$\vec{B}_2 = \delta K^2 \frac{\vec{v} \times \hat{r}}{r^2} \rightarrow \vec{\nabla} \times \vec{B}_2 = \delta K^2 \left[ \frac{r 3\vec{v} \cdot \hat{r} \hat{r} - \vec{v} r^2}{r^5} + \hat{r} \times \frac{\vec{v} \times \hat{r}}{r^3} \right]$$

$$\rightarrow \delta = -1 \rightarrow \vec{B}_2 = -K^2 \frac{\vec{v} \times \hat{r}}{r^2}, \quad \vec{E}_2 = +K \frac{2\vec{v} \cdot \hat{r} \hat{r} - \vec{v} r^2}{r}$$

$$\int \vec{j} \cdot \vec{E} dV = IV = \left[ \text{Re} (v e^{-i\omega t}) \right] \left[ \text{Re} (j e^{-i\omega t}) \right]$$

$$= |v| \cos(\omega t - \hat{v}) |j| \cos(\omega t - \hat{j}) \rightarrow$$

$$\bar{P} = \frac{1}{2} |j| |v| \left( \cos(2\omega t - \hat{v} - \hat{j}) + \cos(\hat{v} - \hat{j}) \right)$$

$$\rightarrow \bar{P} = \frac{1}{2} |j| |v| \cos(\hat{v} - \hat{j})$$

$$v = |v| e^{i\hat{v}}$$

$$j = |j| e^{i\hat{j}}$$

$$\bar{P} = \frac{1}{2} |j| |v| \text{Re} \left( e^{i(\hat{v} - \hat{j})} \right) = \frac{1}{2} \text{Re} (v j^*)$$

100



$$\mathcal{E}_{(T_1, T_2, \dots, T_n)} = T_{11} \mathcal{E}_{(e_1, T_2, \dots, T_n)} + T_{21} \mathcal{E}_{(e_2, T_2, \dots, T_n)} + \dots$$

$$+ \dots = T_{11} \mathcal{E}_{(e_1, \tilde{T}_2, \dots, \tilde{T}_n)} + T_{21} \mathcal{E}_{(e_2, \tilde{T}_2, \dots, \tilde{T}_n)} + \dots$$

که  $\tilde{T}_i$  اول صفر

$$\det T = T_{11} \det(\tilde{T}_2, \dots, \tilde{T}_n) + T_{21} (-1) \det(\tilde{T}_2, \dots, \tilde{T}_n)$$

$$T_{ij} (-1)^{i+j} \quad \text{برای همین صفر و صفت}$$

$\dim[\ker(M)] + \dim[\text{img}(M)] = n$

$$\mathcal{E}(me_1, me_2, \dots, me_n) = 0 \rightarrow \det M = 0$$

$$\det \begin{pmatrix} C_1 s + \frac{1}{R_1} + \frac{1}{R_2} & -\frac{1}{R_2} \\ -\frac{1}{R_2} & C_2 s + \frac{1}{R_2} \end{pmatrix} = 0$$



ماتریس معادلات

$$\Delta_{ij} = (-1)^{i+j} \det \tilde{M}_{ij}$$

$$M^{-1} = \frac{\Delta_{ij}}{\det(M)}$$

$$M = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & -1 \\ 2 & 0 & 1 \end{pmatrix} \rightarrow \Delta = \begin{pmatrix} 1 & -2 & -2 \\ -2 & -5 & 4 \\ - & - & - \end{pmatrix}$$

$$\det(M) = 4 = (1 \times 1) + (2 \times -2) + (3 \times -2) =$$

$$(0 \times -2) + (-5 \times 1) + (4 \times -1)$$

$$V = \alpha_1 V_1^H e^{s_1 t} + \alpha_2 V_2^H e^{s_2 t}$$

برای زمان های بزرگ جویان هکل صفر می شود

$$I_1 = C_1 \frac{dV_1}{dt}$$

$$P = \int q_a \vec{v}_a \cdot \vec{E} = \int (\vec{j} \cdot dV) \cdot \vec{E}$$

$$\mathcal{E}(u, u) = \mathcal{E}(u_1 e_1 + u_2 e_2, u_1 e_1 + u_2 e_2) = (u_1 u_2 - u_2 u_1) \mathcal{E}(e_1, e_2)$$

برای 3 تا هم می توان کاری مشابه کرد.

برای  $\mathcal{E}'(u, u)$  با تعریف  $\mathcal{E}'$  از خواص  $\mathcal{E}$  استفاده می کنیم.

$$\mathcal{E}'(u, u) = (u_1 u_2 - u_2 u_1) \mathcal{E}'(e_1, e_2)$$

پس  $\alpha \mathcal{E}'(u, u) + \beta \mathcal{E}(u, u) = 0$  می تواند ثابت کند.

$$\mathcal{E}(e_1, e_2, e_3) = -\mathcal{E}(e_2, e_1, e_3) = \mathcal{E}(e_2, e_3, e_1)$$

پهناور جابجایی طایفه می توانیم.

$$T: V \rightarrow V$$

$$\mathcal{E}(e_1, e_2, \dots, e_n) \neq 0$$

$$\mathcal{E}(Tu_1, Tu_2, \dots, Tu_n) = \tilde{\mathcal{E}}(u_1, \dots, u_n)$$

$$\tilde{\mathcal{E}}(\alpha u_1 + \alpha' u'_1, \dots) = \mathcal{E}(T(\alpha u_1 + \alpha' u'_1), \dots) =$$

$$\mathcal{E}(\alpha Tu + \alpha' Tu', \dots) \rightarrow \tilde{\mathcal{E}}(u_1, u_2, \dots, u_n) = [\det(T)] \mathcal{E}(u_1, u_2, \dots, u_n)$$

$$\rightarrow \det(T) = \frac{\mathcal{E}(Te_1, Te_2, \dots, Te_n)}{\mathcal{E}(e_1, e_2, \dots, e_n)}$$

$$\mathcal{E}(sTe_1, sTe_2, \dots, sTe_n) =$$

$$(\det(s)) \mathcal{E}(Te_1, Te_2, \dots, Te_n) =$$

$$(\det(s)) (\det(T)) \mathcal{E}(e_1, e_2, \dots, e_n)$$

$$\rightarrow \det(sT) = \det(s) \det(T)$$

$$\text{mat}(T) = ((Te_1), (Te_2), \dots, (Te_n)) = (T_1, T_2, \dots, T_n)$$

$$\det(T) = \frac{\mathcal{E}(T_1, T_2, \dots, T_n)}{\mathcal{E}(e_1, e_2, \dots, e_n)}$$

$$T_1 = T_{11} e_1 + T_{21} e_2 + \dots + T_{n1} e_n$$

باریوسته داخله است در صحت هم بیانیه در نظر بین  
 در باریوسته در باریوسته آورده ثابت کنید  
 نیرو خاص در باریوسته داخله مشخص کنید

رابطه بین بیانیه در باریوسته چنین است:  $\varphi_s(A_0 + \frac{B_0}{r}) + \delta(A_1 r + \frac{B_1}{r^2})$

آستان 87 - آزمون 2 - سنی  $\sigma(x < 2a) = (\rho a + 2\rho a + \sigma_1 + \sigma_2) \delta = \rho a$

$\sigma_1 + \sigma_2 = -3\rho a$   $\sigma(x < a) = E_1 s \frac{\sigma_1}{\epsilon_0} + \frac{\rho x}{\epsilon_0}$

$\sigma(x < 2a) = E_2 s (E_1)_{x=2a} + \frac{2\rho x}{\epsilon_0} s (\frac{\sigma_1 + \rho a}{\epsilon_0}) + \frac{2\rho x}{\epsilon_0}$

$\Delta v_1 s v_1 x - v_0 s = \frac{1}{\epsilon_0} \int (\sigma_1 + \rho x) dx s - (\frac{\rho x^2}{2\epsilon_0})$

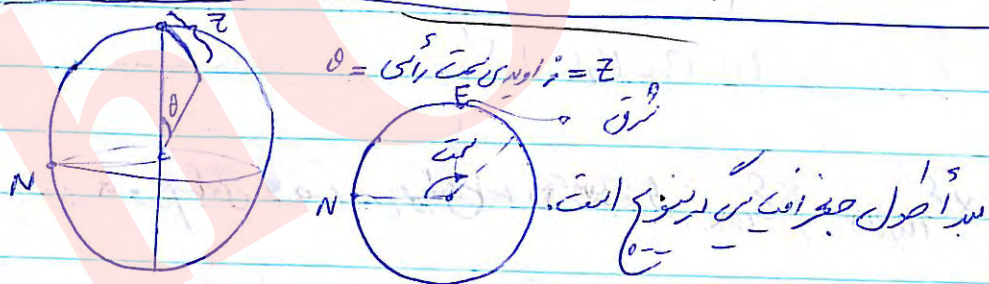
$v_1 |_{x=2a} s - (\frac{\rho_1 a}{\epsilon_0} + \frac{\rho a^2}{2\epsilon_0}) \rightarrow \Delta v_2 s - \int E_2 dx s - (\frac{\rho_1 + \rho a}{\epsilon_0}) x -$

$\frac{2\rho (\frac{x^2}{2})}{\epsilon_0} \quad v_2 = v_1 - \frac{1}{\epsilon_0} \left( (\rho_1 + \rho a) x + \frac{\rho x^2}{\epsilon_0} \right)$

$x' s a \rightarrow v_2 s v_1 - \frac{1}{\epsilon_0} (\rho_1 a + \rho a^2 + \rho a^2) \rightarrow v_2 s - \frac{1}{\epsilon_0} \left( \rho_1 a + \frac{\rho a^2}{2} + \rho_1 a + 2\rho a^2 \right)$

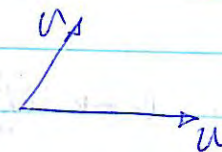
$\rightarrow v_2 s - \frac{\rho}{\epsilon_0} \left( 2\rho_1 + \frac{5\rho a}{\epsilon_0} \right) s v_0 \rightarrow 2\rho_1 + \frac{5\rho a}{2} - \epsilon_0 \frac{v_0}{a}$

$\rho_1 s - \frac{1}{2} \left( \frac{\epsilon_0 v_0}{a} + \frac{5\rho a}{2} \right) \rightarrow \left| \rho_1 s - \frac{(2\epsilon_0 v_0 + 5\rho a^2)}{4a} \right|$



$L = m \sqrt{G M a (1 - e^2)}$   $E = -\frac{G M m}{2a}$

- $\mathcal{E}(u, u) =$  مساحت بیضی
- $\mathcal{E}(u, u) = 0$
- $\mathcal{E}(u, u) = -\mathcal{E}(u, u)$
- $\mathcal{E}(\alpha u, u) = \alpha \mathcal{E}(u, u)$



رواکی

مثال: یک فواره می تواند ذرات آب را در هر جهات با سرعت اولیه  $v_0$  در تمام جهات پرتاب کند معادله بر روی  $y$  وجود داشته باشد که بر حسب  $\alpha$  آورده

$$y = \frac{v_0^2 \sin^2 \alpha}{2g}$$

مثال: تعداد سوراخ ها در راه سطح برابر یک آبپاش می تواند است. این تابع  $y$  بر حسب  $\alpha$  و بصورت تناسبی به گوندر  $r$  مشخص کنید که در فاصله دور از فواره آبپاشی

بصورت  $N = n(\alpha) \times 2\pi R^2 \sin \alpha d\alpha \sim 2\pi r dr$  انجام نموده

$$r = \frac{v_0^2 \sin^2 \left(\frac{\pi}{2} - \alpha\right)}{g} \rightarrow \frac{v_0^2 \sin(2\alpha)}{g} \rightarrow dr = \frac{v_0^2}{g} (2 \cos(2\alpha) d\alpha)$$

$$n(\alpha) \sim \frac{r dr}{\sin 2\alpha d\alpha} \rightarrow n(\alpha) \sim \frac{\sin 4\alpha}{\sin^3(\alpha)}$$

مثال:

$$x_1 \left(t - \sqrt{\frac{2h}{g}}\right) = a \sin \omega \left(t - \sqrt{\frac{2h}{g}}\right) \rightarrow x_2 = a \cos \omega \left(t - \sqrt{\frac{2h}{g}}\right)$$

$$\Delta x = x_2 - x_1 = a \left[ \cos \omega \left(t - \sqrt{\frac{2h}{g}}\right) - \sin \omega \left(t - \sqrt{\frac{2h}{g}}\right) \right]$$