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Computational
Geometry

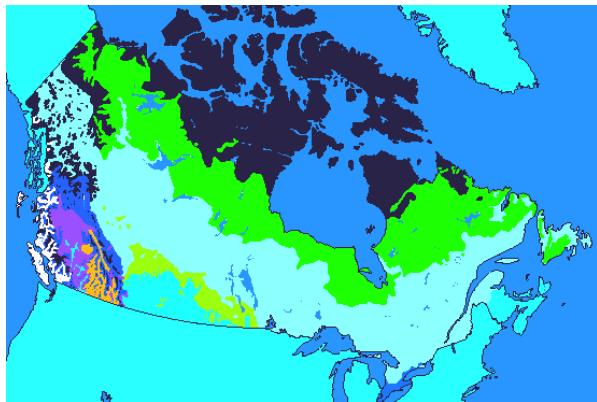
Doubly Connected
Edge List (DCEL)

Computing the
Overlay of Two
Subdivisions

Computing the Overlay of Two Subdivisions

1388-1389

- We have solved the easiest case of the map overlay problem, where the two maps are networks represented as collections of line segments.
- In general, maps have a more complicated structure: they are subdivisions of the plane into labeled regions.



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- Before we can give an algorithm for computing the overlay of two subdivisions, we must develop a suitable representation for a subdivision.
- Storing a subdivision as a collection of line segments is not such a good idea.
- Operations like reporting the boundary of a region would be rather complicated.
- Add topological information: which segments bound a given region, which regions are adjacent, and so on.

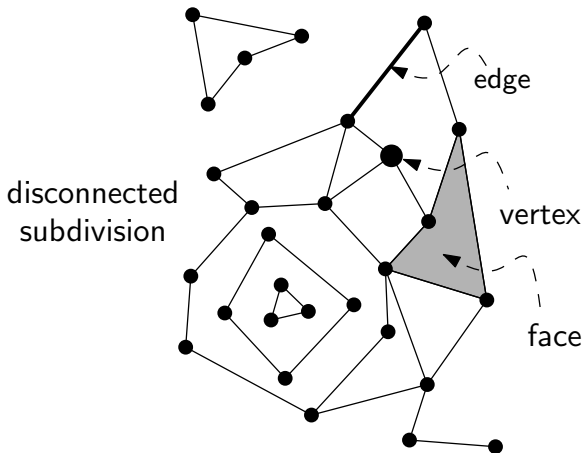


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Complexity of a subdivision

$\#faces + \#edges + \#vertices.$

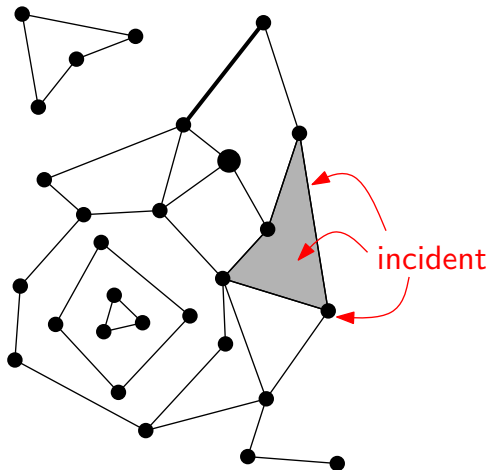


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Complexity of a subdivision

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What kind of queries?

- What is the face containing a given point? (TOO MUCH!)
- Walking around the boundary of a given face,
- Find the face from an adjacent one if we are given a common edge,
- Visit all the edges around a given vertex.

The representation that we shall discuss supports these operations. It is called the doubly-connected edge list (DCEL).



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DCEL contains:

- a record for each edge,
- a record for each vertex,
- a record for each face,
- plus attribute information.

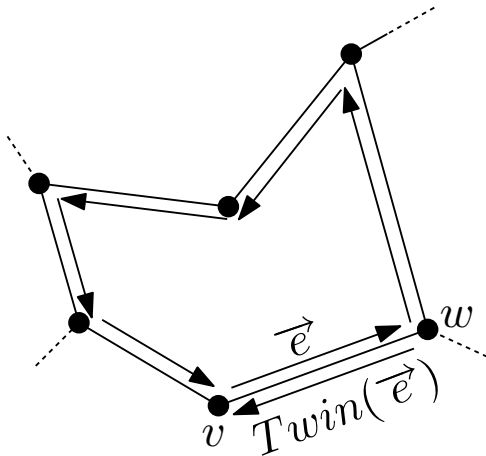


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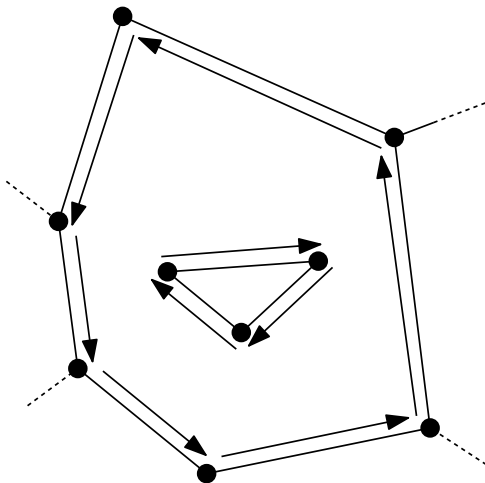
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To be able to traverse the boundary of a face, we need to keep a pointer to a half-edge of any boundary component and isolated points.



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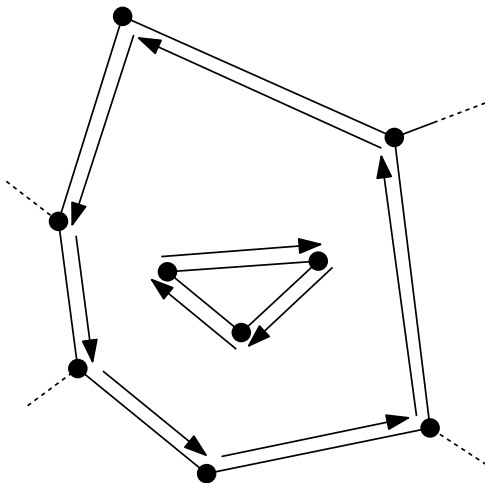


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DCEL contains:

- a record for each vertex,
 - 1 $Coordinates(v)$: the coordinates of v ,
 - 2 $IncidentEdge(v)$: a pointer to an arbitrary half-edge that has v as its origin.
- a record for each face,
 - 1 $OuterComponent(f)$: to some half-edge on its outer boundary (nil if unbounded),
 - 2 $InnerComponents(f)$: a pointer to some half-edge on the boundary of the hole, for each hole.
- a record for each half-edge $\vec{e}$,
 - 1 $Origin(\vec{e})$: a pointer to its origin,
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 - 3 $IncidentFace(\vec{e})$: a pointer to the face that it bounds.
 - 4 $Next(\vec{e})$ and $Prev(\vec{e})$: a pointer to the next and previous edge on the boundary of $IncidentFace(\vec{e})$.



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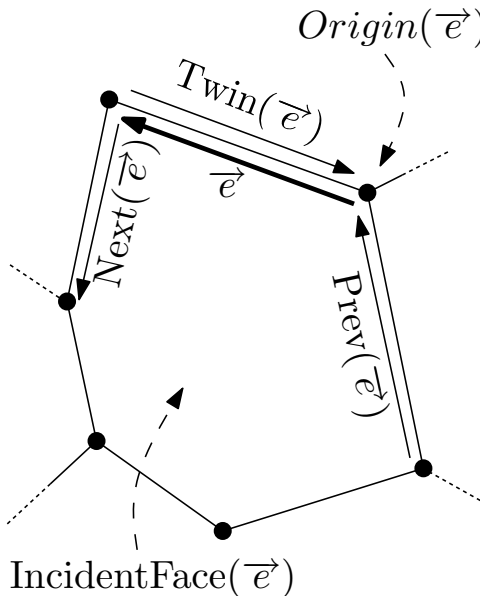


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DCEL: Example

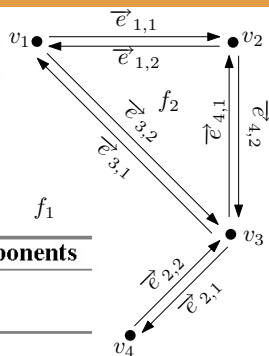


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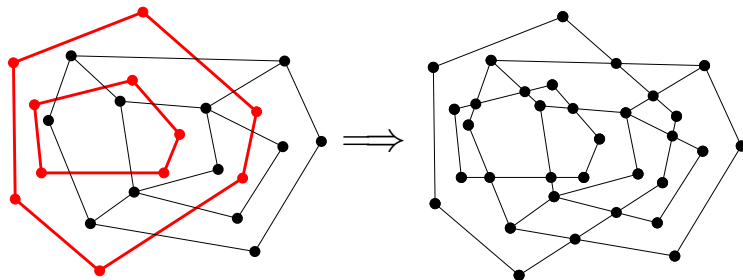


Vertex	Coordinates	IncidentEdge
v_1	(0,4)	$\vec{e}_{1,1}$
v_2	(2,4)	$\vec{e}_{4,2}$
v_3	(2,2)	$\vec{e}_{2,1}$
v_4	(1,1)	$\vec{e}_{2,2}$

Face	OuterComponent	InnerComponents
f_1	nil	$\vec{e}_{1,1}$
f_2	$\vec{e}_{4,1}$	nil

Half-edge	Origin	Twin	IncidentFace	Next	Prev
$\vec{e}_{1,1}$	v_1	$\vec{e}_{1,2}$	f_1	$\vec{e}_{4,2}$	$\vec{e}_{3,1}$
$\vec{e}_{1,2}$	v_2	$\vec{e}_{1,1}$	f_2	$\vec{e}_{3,2}$	$\vec{e}_{4,1}$
$\vec{e}_{2,1}$	v_3	$\vec{e}_{2,2}$	f_1	$\vec{e}_{2,2}$	$\vec{e}_{4,2}$
$\vec{e}_{2,2}$	v_4	$\vec{e}_{2,1}$	f_1	$\vec{e}_{3,1}$	$\vec{e}_{2,1}$
$\vec{e}_{3,1}$	v_3	$\vec{e}_{3,2}$	f_1	$\vec{e}_{1,1}$	$\vec{e}_{2,2}$
$\vec{e}_{3,2}$	v_1	$\vec{e}_{3,1}$	f_2	$\vec{e}_{4,1}$	$\vec{e}_{1,2}$
$\vec{e}_{4,1}$	v_3	$\vec{e}_{4,2}$	f_2	$\vec{e}_{1,2}$	$\vec{e}_{3,2}$
$\vec{e}_{4,2}$	v_2	$\vec{e}_{4,1}$	f_1	$\vec{e}_{2,1}$	$\vec{e}_{1,1}$

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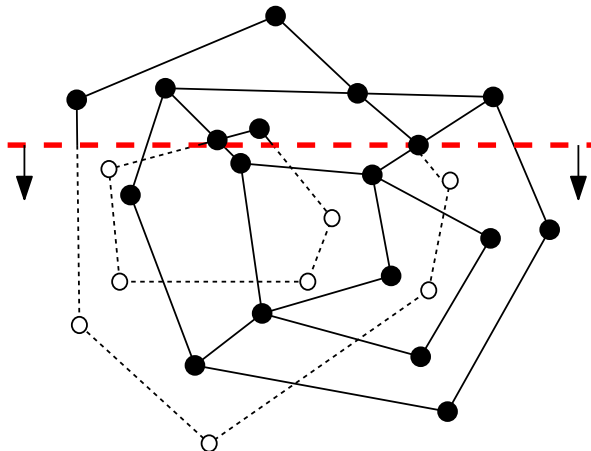


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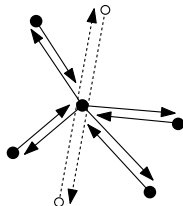
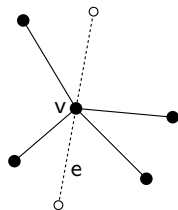
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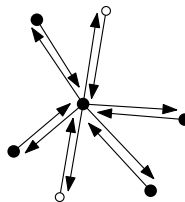
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Updating half-edges

the geometric situation and
the two doubly-connected
edge lists before handling the
intersection



the doubly-connected edge
list after handling the inter-
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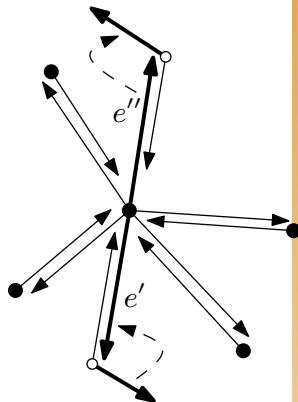
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Updating half-edges

- $Next()$ pointers of the two new half-edges each copy the $Next()$ pointer of the old half-edge that is not its twin.
- The half-edges to which these pointers point must also update their $Prev()$ pointer and set it to the new half-edges.



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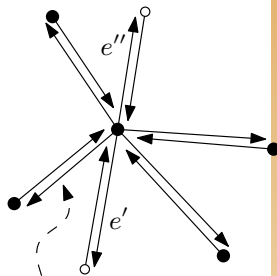
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Updating half-edges

- The half-edge for e' that has v as its destination must be linked to the first half-edge, seen clockwise from e' , with v as its origin.
- The half-edge for e' with v as its origin must be linked to the first counterclockwise half-edge with v as its destination.
- The same for e'' .
- Time complexity: $\mathcal{O}(m)$ (m : degree of v).



first clockwise half-edge from e' with v as its origin



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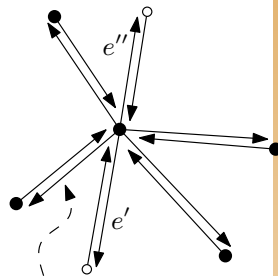
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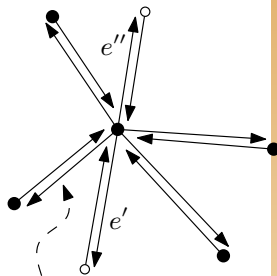
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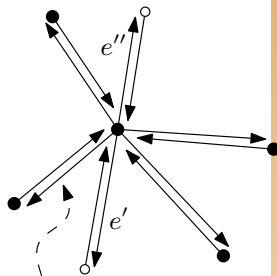
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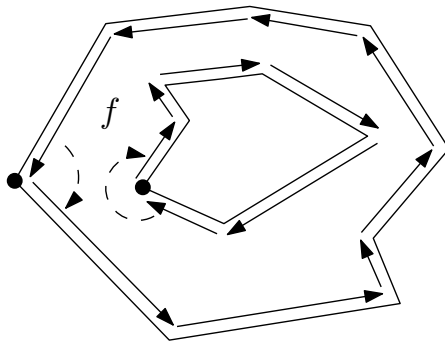
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Updating faces

- $\# \text{ faces} = \# \text{ outer boundaries} + 1$ (unbounded face).
- From half-edges we can construct the boundaries.
- To determine whether the boundary is outer boundary or boundary of a hole:



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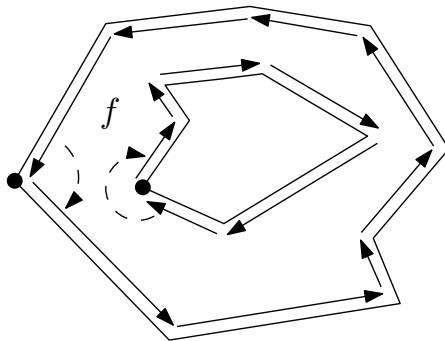
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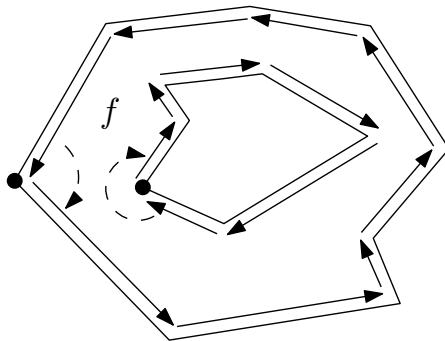
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Which boundary cycles bound the same face?

- Construct a graph $\mathcal{G}$.
 - Every boundary cycle is a node in $\mathcal{G}$.
 - One node for the imaginary outer boundary of the unbounded face.
- Add an arc between two cycles if and only if one of the cycles is the boundary of a hole and the other cycle has a half-edge immediately to the left of the leftmost vertex of that hole cycle.
- If there is no half-edge to the left of the leftmost vertex of a cycle, then the node representing the cycle is linked to the node of the unbounded face.

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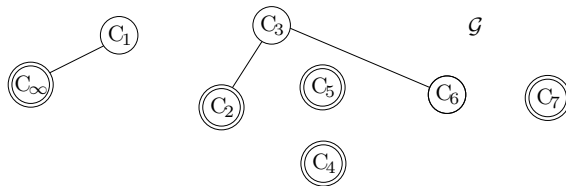
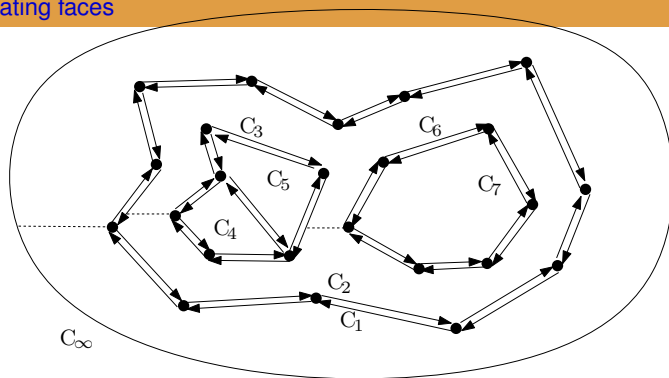
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Lemma 2.5

Each connected component of the graph $\mathcal{G}$ corresponds exactly to the set of cycles incident to one face.



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Computing $\mathcal{G}$

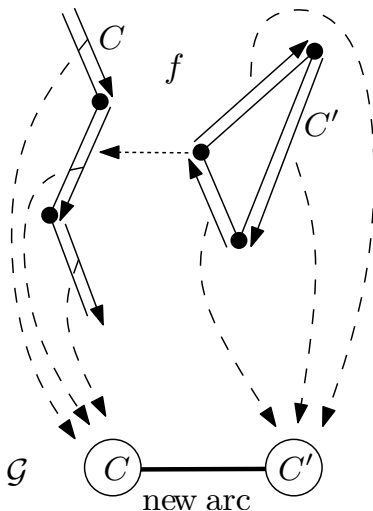


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Computing the Overlay of Two Subdivisions

Theorem 2.6

Let S_1 be a planar subdivision of complexity n_1 , let S_2 be a subdivision of complexity n_2 , and let $n := n_1 + n_2$. The overlay of S_1 and S_2 can be constructed in $\mathcal{O}(n \log n + k \log n)$ time, where k is the complexity of the overlay.



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Application: Boolean Operations

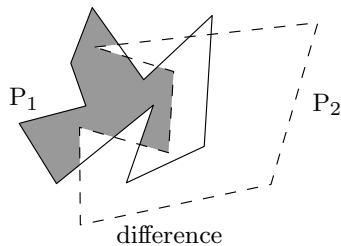
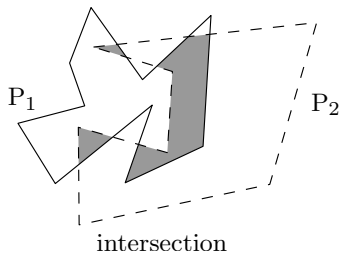
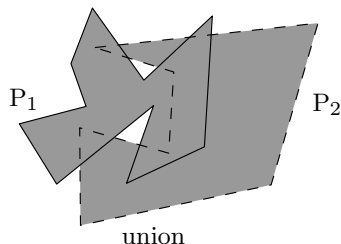


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END.