

# Computational Geometry (Master Course)

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Computational Geometry

#### Textbooks:

1) Mark de Berg, Otfried Cheong, Marc van Kreveld, Mark Overmars, **Computational Geometry Algorithms and Applications**, 3rd Edition, Springer-Verlag Berlin Heidelberg, 2008.





2) Giri Narasimhan, Michiel Smid, **Geometric Spanner Networks**, CAM-BRIDGE UNIVERSITY PRESS. 2007.



Computational Geometry

# Grading and webpage:



# Grading:

Midterm exam: 7

Final exam: 8

Presentation: 3

Homework: 2

Computational Geometry

Introduction

### Course Webpage:

http://pweb.yazduni.ac.ir/science/farshi/Teaching/CG/CG.html



Computational Geometry

Introduction

# **Computational Geometry**

Computational geometry is a branch of computer science devoted to the study of algorithms which can be stated in terms of geometry.



Computational Geometry

Introduction

#### **Applications**

- Computer graphics
- Computer-aided design and manufacturing (CAD/CAM),
- Robotics (motion planning and visibility problems),
- Geographic Information Systems (GIS) (geometrical location and search, route planning),
- Integrated Circuit design (IC geometry design and verification),
- and so on.

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# The main branches of computational geometry are:

- Combinatorial computational geometry, also called algorithmic geometry, which deals with geometric objects as discrete entities. A groundlaying book in the subject by Preparata and Shamos dates the first use of the term "computational geometry" in this sense by 1975.
- Numerical computational geometry, also called machine geometry, computer-aided geometric design (CAGD), or geometric modeling, which deals primarily with representing real-world objects in forms suitable for computer computations in CAD/CAM systems. This branch may be seen as a further development of descriptive geometry and is often considered a branch of computer graphics or CAD.



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Computational Geometry

### Combinatorial computational geometry

- The primary goal is to develop efficient algorithms and data structures for solving problems stated in terms of basic geometrical objects: points, line segments, polygons, polyhedra, etc.
- Example: The closest pair problem: Given n points in the plane, find the two with the smallest distance from each other. The brute-force algorithm takes  $\mathcal{O}(n^2)$  time. A classic result: an algorithm that takes  $\mathcal{O}(n\log n)$  time. Also randomized algorithms that take  $\mathcal{O}(n)$  expected time, as well as a deterministic algorithm that takes  $\mathcal{O}(n\log\log n)$  time.
- Computational geometry focuses heavily on computational complexity since the algorithms are meant to be used on very large data sets containing tens or hundreds of millions of points.



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Computational Geometry

#### Problem classes

- Static problems
  - Onvex hull: Given a set of points, find the smallest convex polyhedron/polygon containing all the points.
  - 2 Line segment intersection: Find the intersections between a given set of line segments.
  - Oelaunay triangulation
  - Voronoi diagram: Given a set of points, partition the space according to which point is closest.
  - Linear programming
  - Olosest pair of points: Given a set of points, find the two with the smallest distance from each other.
  - Euclidean shortest path: Connect two points in a Euclidean space (with polyhedral obstacles) by a shortest path.
  - Polygon triangulation: Given a polygon, partition its interior into triangles



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#### Problem classes

- Geometric query problems
  - Range searching: Preprocess a set of points, in order to efficiently count the number of points inside a query region.
  - Point location: Given a partitioning of the space into cells, produce a data structure that efficiently tells in which cell a query point is located.
  - Nearest neighbor: Preprocess a set of points, in order to efficiently find which point is closest to a query point.
  - Ray tracing: Given a set of objects in space, produce a data structure that efficiently tells which object a query ray intersects first.



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#### Problem classes

- Dynamic problems
- Variations
  - Point in polygon: Decide whether a point is inside or outside a given polygon.



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#### Journals:



#### Computational Geometry

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#### **Journals**

- Computational Geometry: Theory and Applications (CGTA)
- Discrete & Computational Geometry (DCG)
- International Journal of Computational Geometry and Applications (IJCGA)
- Journal of Computational Geometry (NEW)
- Other algorithmic journals

# Conferences:



Computational Geometry

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#### Conferences

- ACM Symposium on Computational Geometry (SOCG)
- Canadian Conference on Computational Geometry (CCCG)
- European Workshop on Computational Geometry (EWCG)
- International Conference on Computational Geometry and Computer Vision
- Others, like SODA, STOC, ESA.